

Distributional Reinforcement Learning with Regularized Wasserstein Loss

Ke Sun, Yingnan Zhao, Wulong Liu, Bei Jiang, Linglong Kong

University of Alberta
Alberta Machine Intelligence Institute (Amii)

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Ke Sun

Introduction

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Motivation

Our Contribution

Distributional RL with Sinkhorn Divergence

Sinkhorn Divergence

Contraction Properties under Sinkhorn Divergence

Extension to Multi-dimensional Return

Algorithm

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Return: Cumulative Rewards

$$Z^\pi = \sum_{t=0}^{\infty} \gamma^t R_t$$

- ▶ Classical RL learns **value function**, the expectation of returns:

$$\begin{aligned} Q^\pi(s, a) &= \mathbb{E}[Z^\pi(s, a)] \\ &= \mathbb{E}\left[\sum_{t=0}^{\infty} \gamma^t R(s_t, a_t) \mid s_0 = s, a_0 = a\right] \end{aligned}$$

- ▶ Classical RL learns **value function**, the expectation of returns:

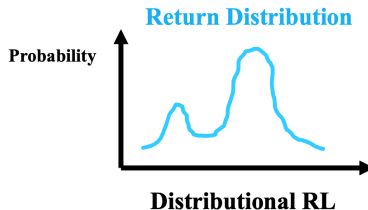
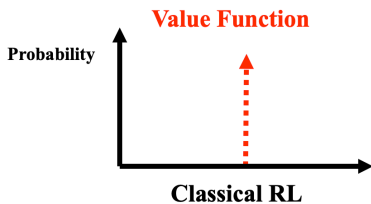
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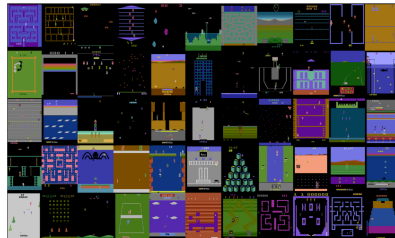
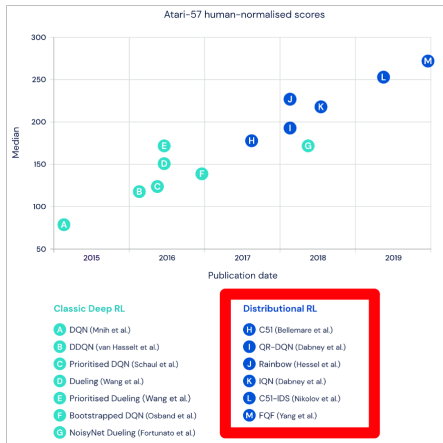
- ▶ Distributional RL learns the whole distribution of returns:

$$\mathcal{D}(Z^\pi(s, a))$$

where \mathcal{D} extracts the distribution of a random variable.

Distributional Learning: Beyond Expectation





Atari Games

Classical RL vs Distributional RL

- ▶ **Classical RL:** Classical Bellman operator \mathcal{T}^π is defined as

$$\mathcal{T}^\pi Q(s, a) = \mathbb{E}[R(s, a)] + \gamma \mathbb{E}_{s' \sim p, \pi} [Q(s', a)], \quad (1)$$

where \mathcal{T}^π is a γ -contractive operator.

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- ▶ **Distributional RL:** Distributional Bellman operator \mathfrak{T}^π is defined as

$$\mathfrak{T}^\pi Z(s, a) \stackrel{D}{=} R(s, a) + \gamma Z(s', a), \quad (2)$$

where \mathfrak{T}^π is a contractive operator under **some proper distribution divergence / statistical distances**, e.g., Wasserstein distance.

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where \mathfrak{T}^π is a contractive operator under **some proper distribution divergence / statistical distances**, e.g., Wasserstein distance.

- ▶ **Two key factors** in Distributional RL:
 - ① How to parameterize Z^π ?
 - ② How to choose the statistical distance?

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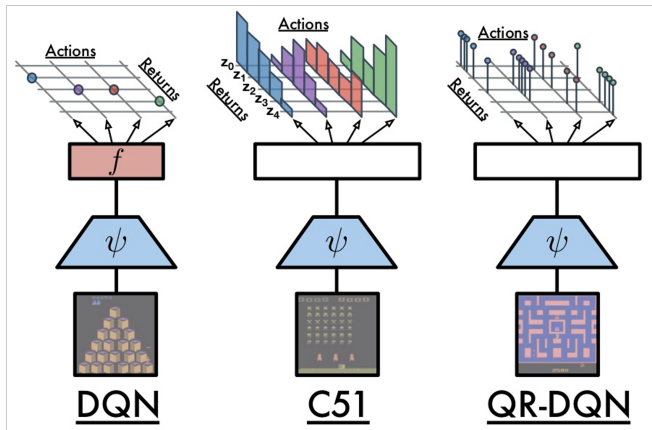
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① Inaccuracy in Capturing Return Distribution Characteristics

- ▶ Non-crossing issue of learned quantile curves
- ▶ Restricted expressiveness of pre-specified statistics

② Difficulties in Extension to Multi-dimensional Rewards

- ▶ Many RL tasks learn a multi-dimensional return distribution
 - ▶ multi-source rewards
 - ▶ hybrid reward architecture
 - ▶ sub-reward architecture
- ▶ Difficult to extend existing algorithms to multi-dimensional setting
 - ▶ multi-dimensional categorical representation?
 - ▶ multi-dimensional quantile regression?

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- ▶ **Algorithm.** We introduce a new distributional RL algorithm based on **Sinkhorn divergence**, a regularized Wasserstein loss.
- ▶ **Theory.** We prove the contraction properties of Bellman operators under Sinkhorn divergence, revealing an **interpolation** relationship between Wasserstein distance and MMD.
- ▶ **Experiments.** We conduct extensive experiments over 55 Atari games, investigating
 - ▶ superiority in **multi-dimensional reward setting**
 - ▶ Comprehensive comparison with existing algorithms
 - ▶ Sensitivity analysis and computational cost

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► Optimal Transport

$$W_c = \inf_{\Pi \in \Pi(\mu, \nu)} \int c(x, y) d\Pi(x, y), \quad (3)$$

where the minimizer Π^* is called the *optimal transport plan* or *optimal coupling*.

► p -Wasserstein Distance

$$W_p = \left(\inf_{\Pi \in \Pi(\mu, \nu)} \int \|x - y\|^p d\Pi(x, y) \right)^{1/p}. \quad (4)$$

► Maximum Mean Discrepancy (MMD)

$$\text{MMD}_k^2 = \mathbb{E} [k(X, X')] + \mathbb{E} [k(Y, Y')] - 2\mathbb{E} [k(X, Y)], \quad (5)$$

where $k(\cdot, \cdot)$ is a continuous kernel and X' (resp. Y') is a random variable independent of X (resp. Y).

- ▶ Sinkhorn divergence is an **entropic regularized** Wasserstein distance. We first define $\mathcal{W}_{c,\varepsilon}(\mu, \nu)$ as

$$\mathcal{W}_{c,\varepsilon}(\mu, \nu) = \min_{\Pi \in \Pi(\mu, \nu)} \int c(x, y) d\Pi(x, y) + \varepsilon \text{KL}(\Pi | \mu \otimes \nu), \quad (6)$$

where the regularization $\text{KL}(\Pi | \mu \otimes \nu) = \int \log \left(\frac{\Pi(x, y)}{d\mu(x) d\nu(y)} \right) d\Pi(x, y)$, is also known as **mutual information**.

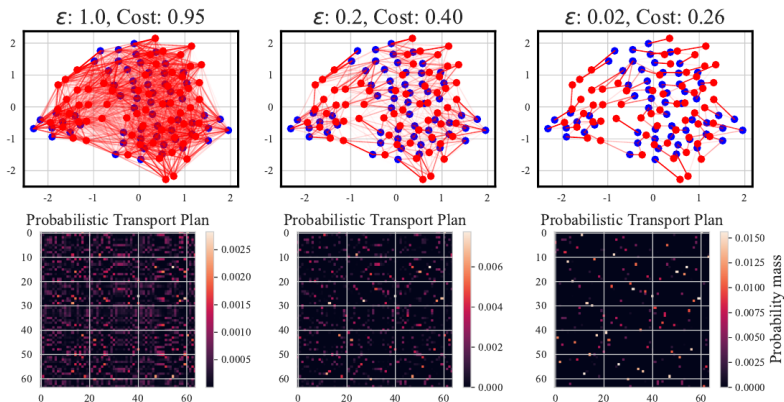
- ▶ Sinkhorn divergence $\overline{\mathcal{W}}_{c,\varepsilon}$ is defined as

$$\overline{\mathcal{W}}_{c,\varepsilon}(\mu, \nu) = 2\mathcal{W}_{c,\varepsilon}(\mu, \nu) - \mathcal{W}_{c,\varepsilon}(\mu, \mu) - \mathcal{W}_{c,\varepsilon}(\nu, \nu). \quad (7)$$

- ① **Addressing Limitation 1:** Efficient approximation of a **multi-dimensional** Wasserstein distance
- ② **Addressing Limitation 2:** Leveraging **samples**, un-restricted statistics, to represent return distributions
- ③ **Regularization Effects**
 - ▶ “Smoother” transport plan
 - ▶ Maximum entropy principle
 - ▶ Stable optimization: strongly convexity and smoothness

- **Recap.** Regularized Wasserstein distance:

$$\mathcal{W}_{c,\varepsilon}(\mu, \nu) = \min_{\Pi \in \Pi(\mu, \nu)} \int c(x, y) d\Pi(x, y) + \varepsilon \text{KL}(\Pi | \mu \otimes \nu) \quad (8)$$



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The contraction analysis of \mathfrak{T}^π depends on two properties of the statistical distance d_p .

Contraction Properties of statistical distance d_p

① **Scale Sensitive (S):**

$$d_p(aX, aY) \leq |a|^\tau d_p(X, Y), \quad (9)$$

where $\tau > 0$.

② **Sum Invariant (I):**

$$d_p(A + X, A + Y) \leq d_p(X, Y), \quad (10)$$

where the random variable A is independent of X and Y .

- ▶ **Recap.** Regularized Wasserstein distance:

$$\mathcal{W}_{c,\varepsilon}(\mu, \nu) = \min_{\Pi \in \Pi(\mu, \nu)} \int c(x, y) d\Pi(x, y) + \varepsilon \text{KL}(\Pi | \mu \otimes \nu) \quad (11)$$

- ▶ Given a joint distribution Π , we define the supremal form of the regularization term:

$$\text{MI}_{\Pi}^{\infty}(\mu, \nu) = \sup_{(s, a) \in \mathcal{S} \times \mathcal{A}} \text{KL}(\Pi | \mu(s, a) \otimes \nu(s, a)) \quad (12)$$

Proposition 1. Contraction under $\text{MI}_{\Pi}^{\infty}(\mu, \nu)$.

The distributional Bellman operator \mathfrak{T}^{π} is **non-expansive** under MI_{Π}^{∞} for any non-trivial joint distribution Π .

Two Basic Contraction Properties of $\mathcal{W}_{c,\varepsilon}$

Considering $\mathcal{W}_{c,\varepsilon}$ with **the unrectified kernel** $k_\alpha := -\|x - y\|^\alpha$ as $-c$ ($\alpha > 0$) and a scaling factor $a \in (0, 1)$, we have:

- ▶ **(I)** $\mathcal{W}_{c,\varepsilon}$ is sum-invariant
- ▶ **(S)** $\mathcal{W}_{c,\varepsilon}(a\mu, a\nu) \leq \Delta_\varepsilon(a, \alpha)\mathcal{W}_{c,\varepsilon}(\mu, \nu)$,
with a scaling constant $\Delta_\varepsilon(a, \alpha) \in (|a|^\alpha, 1)$ for any μ and ν in a **finite** set of probability measures.

Remark. The scaling factor $\Delta_\varepsilon(a, \alpha)$ has no explicit form, but it is determined by the scale factor a , the order α , the hyperparameter ε , and the set of interested probability distributions.

- ▶ We consider the supremal form of statistical distance.

$$\overline{W}_{c,\varepsilon}^\infty(\mu, \nu) = \sup_{(s,a) \in \mathcal{S} \times \mathcal{A}} \overline{W}_{c,\varepsilon}(\mu(s,a), \nu(s,a)). \quad (13)$$

Thm 1. Contraction under $\overline{W}_{c,\varepsilon}$ and Interpolation Relationship.

Considering $\overline{W}_{c,\varepsilon}(\mu, \nu)$ with an **unrectified kernel** $k_\alpha := -\|x - y\|^\alpha$ as $-c$ ($\alpha > 0$), where $\mu, \nu \in$ the distribution set of $\{Z^\pi(s, a)\}$ for $s \in \mathcal{S}, a \in \mathcal{A}$ in a **finite** MDP. Then, we have:

- ① ($\varepsilon \rightarrow 0$) $\overline{W}_{c,\varepsilon}(\mu, \nu) \rightarrow 2W_\alpha^\alpha(\mu, \nu)$. When $\varepsilon = 0$, \mathfrak{T}^π is γ^α -contractive under $\overline{W}_{c,\varepsilon}^\infty$.
- ② ($\varepsilon \rightarrow +\infty$) $\overline{W}_{c,\varepsilon}(\mu, \nu) \rightarrow \text{MMD}_{k_\alpha}^2(\mu, \nu)$. When $\varepsilon = +\infty$, \mathfrak{T}^π is γ^α -contractive under $\overline{W}_{c,\varepsilon}^\infty$.
- ③ ($\varepsilon \in (0, +\infty)$) \mathfrak{T}^π is at least $\overline{\Delta}_\varepsilon(\gamma, \alpha)$ -**contractive** under $\overline{W}_{c,\varepsilon}^\infty$, where $\overline{\Delta}_\varepsilon(\gamma, \alpha) \in (\gamma^\alpha, 1)$ is an **MDP-dependent constant**.

- ▶ **Interpolation Property.** Sinkhorn divergence **interpolates** between Wasserstein distance and MMD by varying ϵ .
⇒ Contraction of \mathfrak{T}^π in distributional RL !

- ▶ **Interpolation Property.** Sinkhorn divergence **interpolates** between Wasserstein distance and MMD by varying ϵ .
⇒ Contraction of \mathfrak{T}^π in distributional RL !
- ▶ **Consistency with Existing Contraction Conclusions.**
 - ▶ QR-DQN with contraction guarantee under Wasserstein distance
 - ▶ MMD-DQN with contraction guarantee under MMD if
 1. Unrectified kernel (energy distance or Cramer distance)
 2. Gaussian kernel: **no contraction guarantee...**

Algorithm	d_p	Distribution Divergence	Representation Z_θ	Convergence Rate of \mathcal{E}^π	Sample Complexity of d_p
C51		Cramér distance	Categorical Distribution	$\sqrt{\gamma}$	$\mathcal{O}(n^{-\frac{1}{2}})$
QR-DQN-1		Wasserstein distance	Quantiles	γ	$\mathcal{O}(n^{-\frac{1}{2}})$
MMD-DQN		MMD	Samples	$\gamma^{\alpha/2} (k_\alpha)$	$\mathcal{O}(n^{-1})$
SinkhornDRL (ours)		Sinkhorn divergence ($c = -k_\alpha$)	Samples	$\gamma (\varepsilon \rightarrow 0)$ $\gamma^{\alpha/2} (\varepsilon \rightarrow \infty)$	$\mathcal{O}(n^{\frac{\alpha}{2}} \sqrt{\varepsilon}) (\varepsilon \rightarrow 0)$ $\mathcal{O}(n^{-\frac{1}{2}}) (\varepsilon \rightarrow \infty)$

Table 1: Properties of different distribution divergences in typical distributional RL algorithms. d is the sample dimension and $\kappa = 2\beta d + \|c\|_\infty$, where the cost function c is β -Lipschitz [24]. Sample complexity is improved to $\mathcal{O}(1/n)$ using the kernel herding technique [10] in MMD.

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- ▶ We define a ***d*-dimensional** reward function $\mathbf{R} : \mathcal{S} \times \mathcal{A} \rightarrow P(\mathbb{R}^d)$.
- ▶ We have a ***d*-dimensional** return vector $\mathbf{Z}^\pi(s, a) = \sum_{t=0}^{\infty} \gamma^t \mathbf{R}(s_t, a_t)$, with $\mathbf{Z}^\pi(s, a) = (Z_1^\pi(s, a), \dots, Z_d^\pi(s, a))^\top$.
- ▶ The **joint** distributional Bellman operator \mathfrak{T}_d^π is defined as

$$\mathfrak{T}_d^\pi \mathbf{Z}(s, a) \stackrel{D}{=} \mathbf{R}(s, a) + \gamma \mathbf{Z}(s', a')$$

Corollary 1.

For two joint distributions \mathbf{Z}_1 and \mathbf{Z}_2 , \mathfrak{T}_d^π is $\overline{\Delta}_\varepsilon(\gamma, \alpha)$ -contractive under $\overline{W}_{c,\varepsilon}^\infty$, i.e.,

$$\overline{W}_{c,\varepsilon}^\infty(\mathfrak{T}^\pi \mathbf{Z}_1, \mathfrak{T}^\pi \mathbf{Z}_2) \leq \overline{\Delta}_\varepsilon(\gamma, \alpha) \overline{W}_{c,\varepsilon}^\infty(\mathbf{Z}_1, \mathbf{Z}_2). \quad (14)$$

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Two key factors in distributional RL:

- ▶ **Samples** to represent the return distribution
- ▶ **Sinkhorn divergence** as the statistical distance

Algorithm 1 Generic Sinkhorn distributional RL Update

Require: Number of generated samples N , the cost function c , hyperparameter ε and the target network Z_{θ^*} .

Input: Sample transition (s, a, r', s')

1: **Policy evaluation:** $a^* \sim \pi(\cdot|s')$ or **Control:** $a^* \leftarrow \arg \max_{a' \in \mathcal{A}} \frac{1}{N} \sum_{i=1}^N Z_{\theta}(s', a')_i$

2: $\mathfrak{T}Z_i \leftarrow r + \gamma Z_{\theta^*}(s', a^*)_i, \forall 1 \leq i \leq N$

Output: $\overline{W}_{c,\varepsilon} \left(\{Z_{\theta}(s, a)_i\}_{i=1}^N, \{\mathfrak{T}Z_j\}_{j=1}^N \right)$

$$\overline{W}_{c,\varepsilon}(Z_{\theta}(s, a), \mathfrak{T}^{\pi} Z_{\theta}(s, a))$$

Sinkhorn Iteration with L steps for approximation

- ▶ Differentiable and Efficient, e.g., matrix-vector multiplication
- ▶ Approximation guarantee with a linear rate
- ▶ Easy to implement: adding extra differential layers in existing network architecture

Algorithm 2 Sinkhorn Iterations to Approximate $\overline{W}_{c,\varepsilon} \left(\{Z_i\}_{i=1}^N, \{\mathfrak{T}Z_j\}_{j=1}^N \right)$

Input: Two samples sequences $\{Z_i\}_{i=1}^N, \{\mathfrak{T}Z_j\}_{j=1}^N$, number of iterations L and hyperparameter ε .

- 1: $\hat{c}_{i,j} = c(Z_i, \mathfrak{T}Z_j)$ for $\forall i = 1, \dots, N, j = 1, \dots, N$
- 2: $\mathcal{K}_{i,j} = \exp(-\hat{c}_{i,j}/\varepsilon)$
- 3: $b_0 \leftarrow \mathbf{1}_N$
- 4: **for** $l = 1, 2, \dots, L$ **do**
- 5: $a_l \leftarrow \frac{\mathbf{1}_N}{\mathcal{K}b_{l-1}}, b_l \leftarrow \frac{\mathbf{1}_N}{\mathcal{K}a_l}$
- 6: **end for**
- 7: $\widehat{W}_{c,\varepsilon} \left(\{Z_i\}_{i=1}^N, \{\mathfrak{T}Z_j\}_{j=1}^N \right) = \langle (K \odot \hat{c})b, a \rangle$

Return: $\widehat{W}_{c,\varepsilon} \left(\{Z_i\}_{i=1}^N, \{\mathfrak{T}Z_j\}_{j=1}^N \right)$

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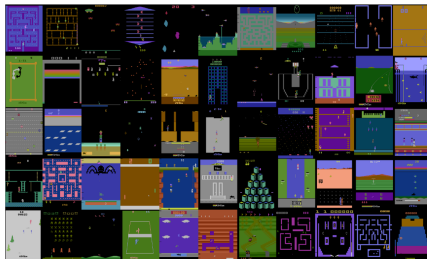
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- ▶ Environments:
55 Atari Games
- ▶ Algorithms:
 - ▶ DQN
 - ▶ C51
 - ▶ QR-DQN
 - ▶ MMD-DQN
 - ▶ SinkhornDRL (ours)
- ▶ The unrectified kernel $k_\alpha := -\|x - y\|^\alpha$ in SinkhornDRL (consistent with Theorem 1)



Atari Games

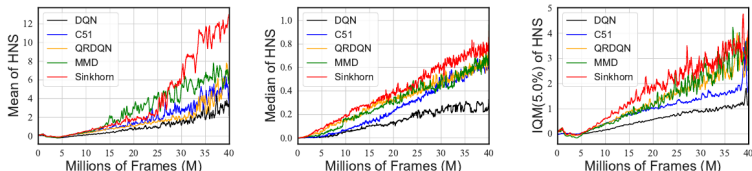


Figure 1: Mean (left), Median (middle), and IQM (5%) (right) of Human-Normalized Scores (HNS) summarized over 55 Atari games. We run 3 seeds for each algorithm.

Evaluation Metric: Human Normalized Score (HNS)

- ▶ Mean
- ▶ Median
- ▶ Interquartile Mean (%)

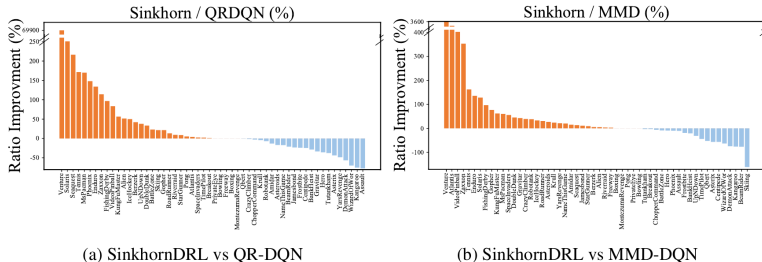


Figure 2: Ratio improvement of return for SinkhornDRL over QR-DQN (left) and MMD-DQN (right) averaged over 3 seeds. The ratio improvement is calculated by $(\text{SinkhornDRL} - \text{QR-DQN}) / \text{QR-DQN}$ in (a) and $(\text{SinkhornDRL} - \text{MMD-DQN}) / \text{MMD-DQN}$ in (b), respectively.

► Sensitivity Analysis

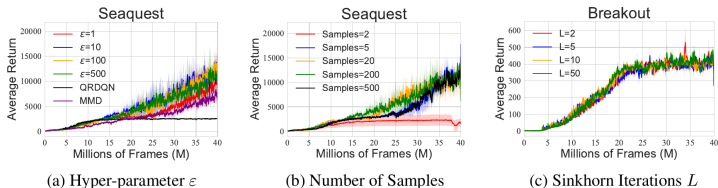


Figure 3: Sensitivity analysis of SinkhornDRL on Breakout and Seaquest in terms of ϵ , number of samples, and number of iteration L . Learning curves are reported over three seeds.

- **Computational Cost.** SinkhornDRL improves performance over baselines at the cost of **slightly** increasing computational burden.

- ▶ **Reward Decomposition.** We decompose the scalar-based rewards to multi-dimensional vectors based on the respective reward structures.
- ▶ **Algorithms.**
 - ① SinkhornDRL
 - ② MMD-DQN
 - ③ Multi-dimensional Quantile Regression DQN? (not clear)

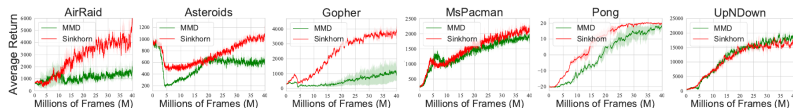


Figure 4: Performance of SinkhornDRL on six Atari games with multi-dimensional reward functions.

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Conclusion: Take-away Messages

- ① Sinkhorn divergence can efficiently approximate a multi-dimensional Wasserstein distance by introducing **an entropic regularization**, interpolation between Wasserstein distance and MMD.
- ② Distributional RL under Sinkhorn divergence can also guarantee a contraction with **an MDP-dependent contraction factor**.
- ③ Distributional RL with Sinkhorn divergence can
 - ▶ **Address two major limitations**: unrestricted distribution representation and extension to multi-dimensional reward setting
 - ▶ **Regularization effect**: “smoother” transport plan and stable optimization
 - ▶ **Competitive performance** in extensive experiments

- ① The **gap** exists between theoretical properties of statistical distances and performance in RL environments.
- ② It lacks a **quantitative criterion** to recommend in choosing an RL algorithm, given an environment.
- ③ Connection and discrepancy between **generative models** and distributional RL.

Thank You!
Questions?