

# BICCOS: Scalable Neural Network Verification with Branch-and-bound Inferred Cutting Planes

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NEURAL INFORMATION  
PROCESSING SYSTEMS

# Motivation: Scalable Neural Network Verification

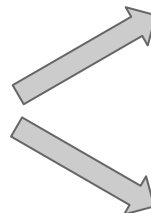
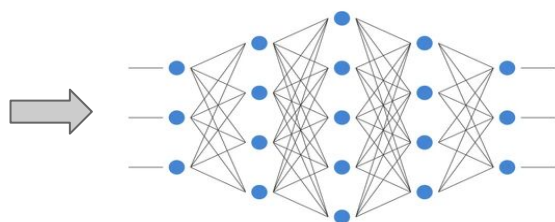
$\forall x \in \mathcal{S}$



Eykholt et al. 2018

(Real world attack to NN)

$f(x)$



STOP 😊

$f(x) > 0$

Speed Limit 😈

Otherwise

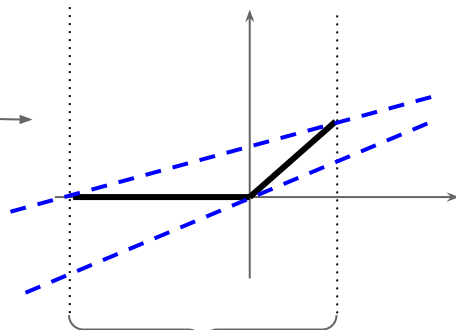
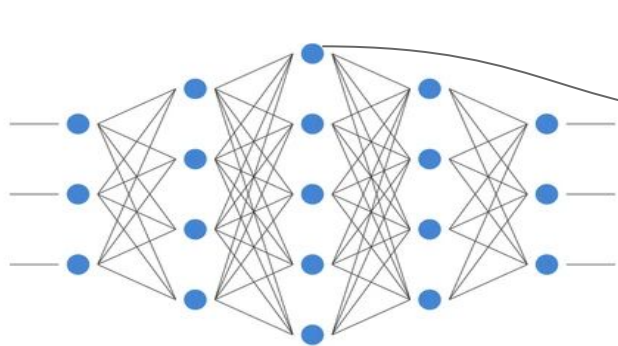
**Problem Statement.** Prove:  $\forall x \in \mathcal{S}, f(x) > 0 \Leftrightarrow \min_{x \in \mathcal{S}} f(x) > 0$

**SOTA:** GCP-CROWN<sup>1</sup>, Bound Propagation + *General* Cutting Planes.

**Challenges:** Cutting Planes are from external MIP solvers, which **can not scale**

**Our Goal:** *specialized* and efficient cutting planes for NN verification

# Preliminary: Math Programming & Bound Propagation



Pre-activation bounds

(can be pre-computed using CROWN)

$$\hat{x}_j^{(i)} \geq 0;$$

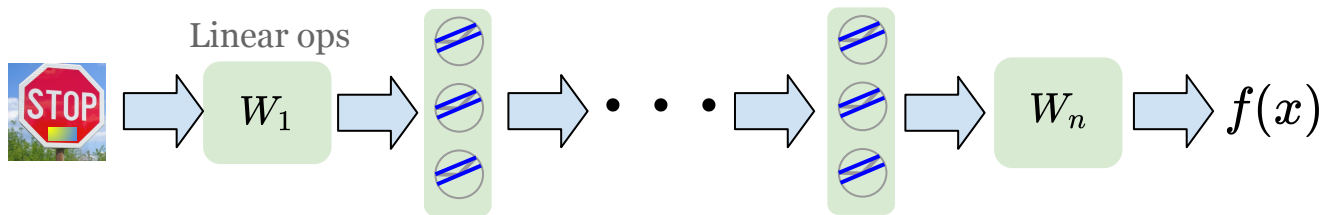
$$\hat{x}_j^{(i)} \geq x_j^{(i)};$$

$$\hat{x}_j^{(i)} \leq u_j^{(i)} z_j^{(i)};$$

$$\hat{x}_j^{(i)} \leq x_j^{(i)} - l_j^{(i)} (1 - z_j^{(i)});$$

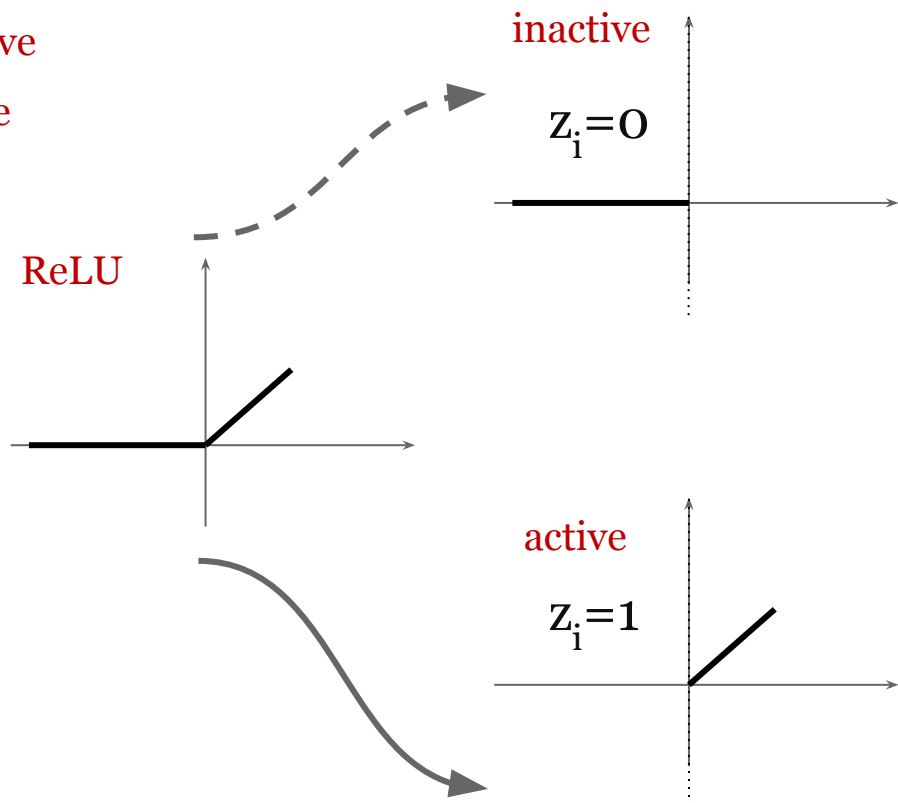
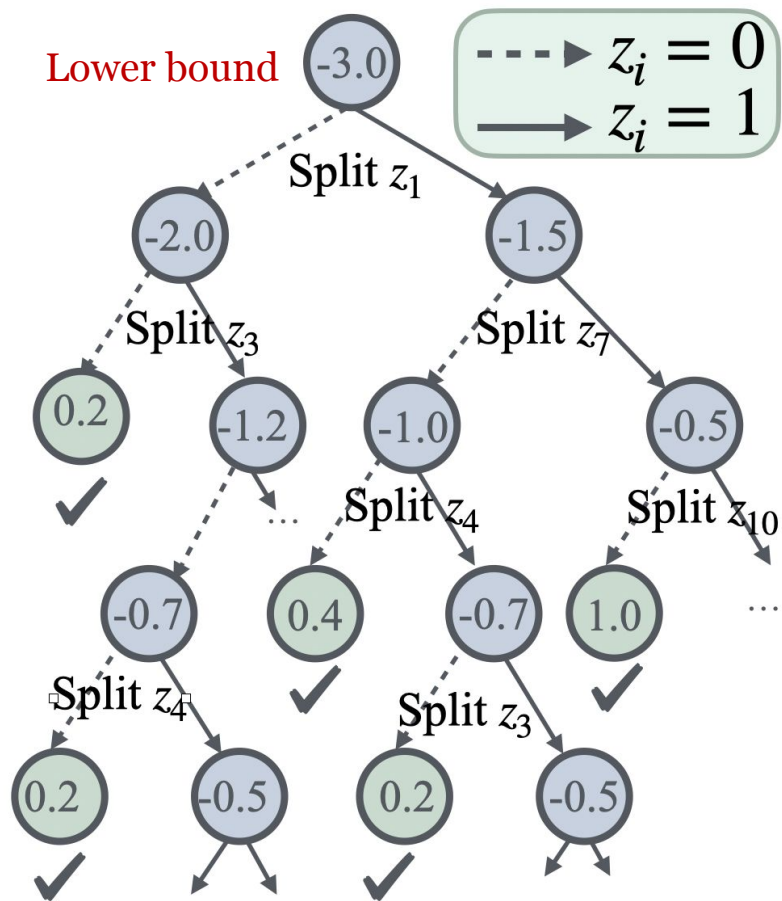
$$z_j^{(i)} \in \{0, 1\} \xrightarrow{\text{Relax}} [0, 1];$$

$x_0 := x$  : Input;  $x_j^{(i)}$  : Pre-ReLU( $i, j$ );  $\hat{x}_j^{(i)}$  : Post-ReLU( $i, j$ );  $z_j^{(i)}$  : ReLU Indicator( $i, j$ )



Backward propagate lower bounds

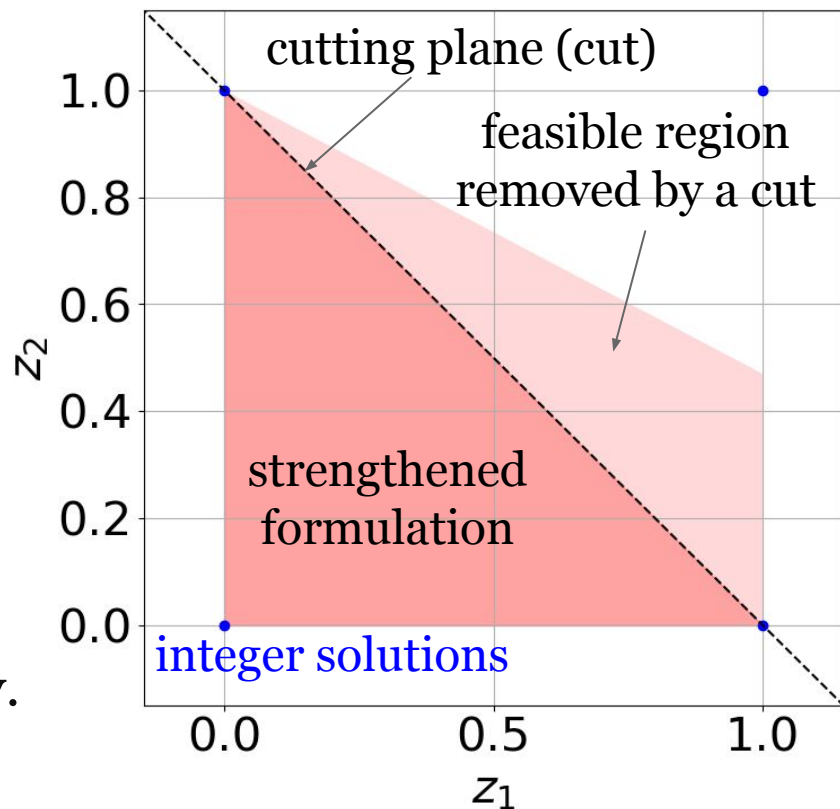
# Preliminary: Branch-and-bound (BaB)



# Goal of Our Paper: Find Cutting Planes

A cutting plane reduces the solution space by excluding infeasible regions without impacting feasible integer solutions.

Our objective: develop **specialized** cutting planes **from NN verification** procedure that strengthen the formulation while ensuring **scalability**.

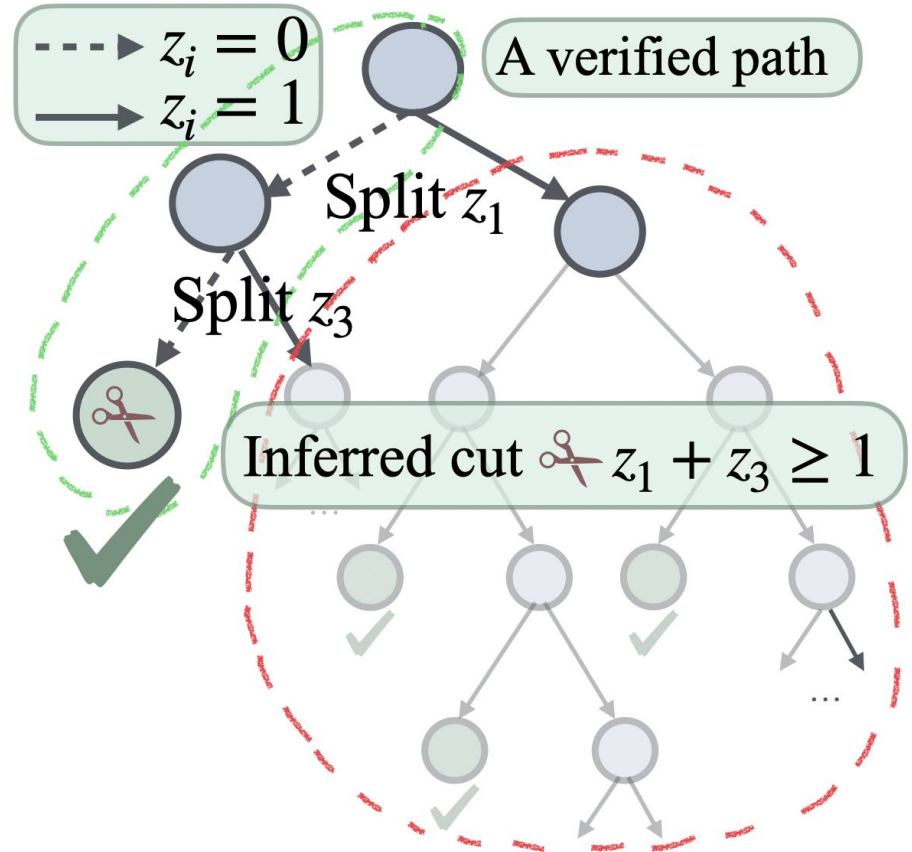


# Main idea: BaB inferred cuts from verified subproblems

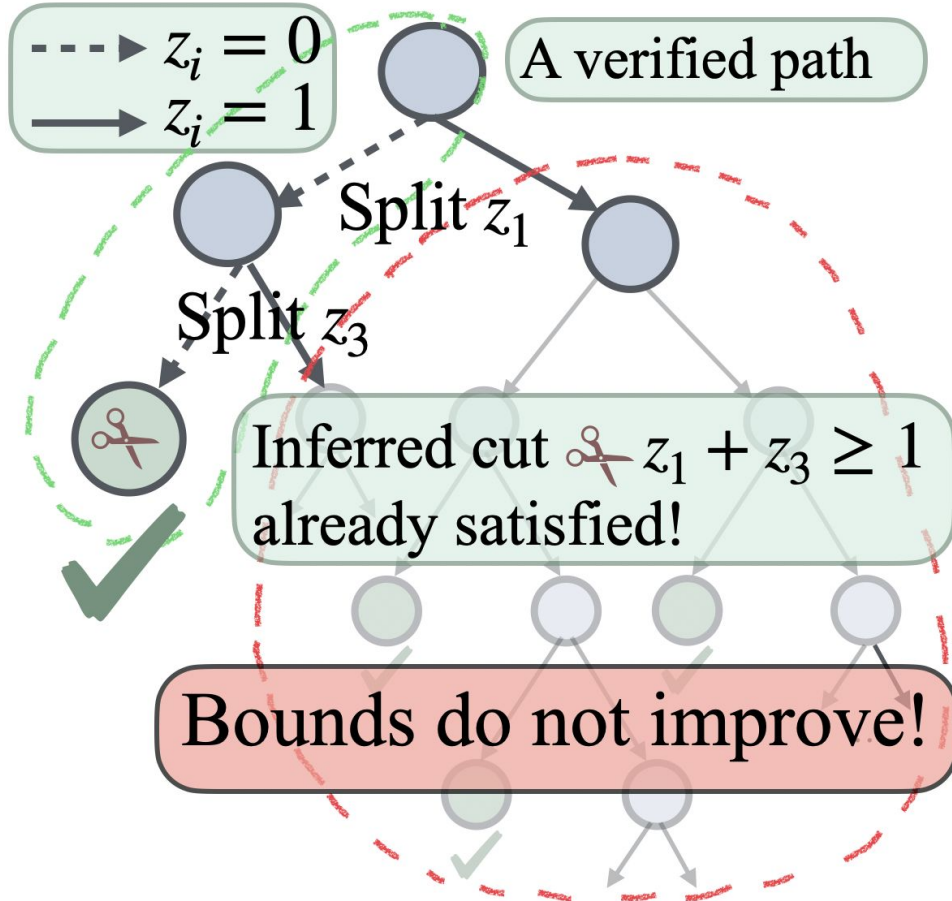
- After splitting  $z_1$  and  $z_3$  both to inactive cases, subproblem verified
- Neuron  $z_1$  and  $z_3$  cannot simultaneously be inactive. To exclude this situation, we create a new constraint (cut) on the relaxed  $z$ :

$$z_1 + z_3 \geq 1$$

- See the general form in our paper



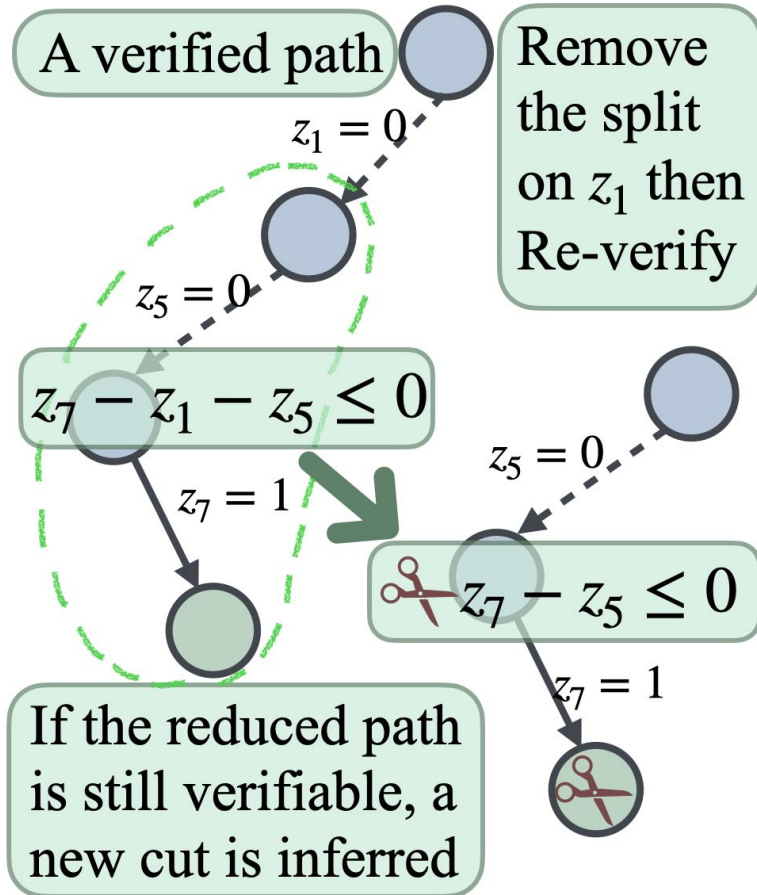
# However, just adding this cut does not improve verification!



The rest of subproblems all have  $z_1=1$  or  $z_3=1$

None of the other subproblems on the search tree violate the cut  $z_1 + z_3 \geq 1$ , so their bounds do not improve.

# Solution: Constraint Strengthening - shorter cuts are stronger!



Starting from the verified path left,

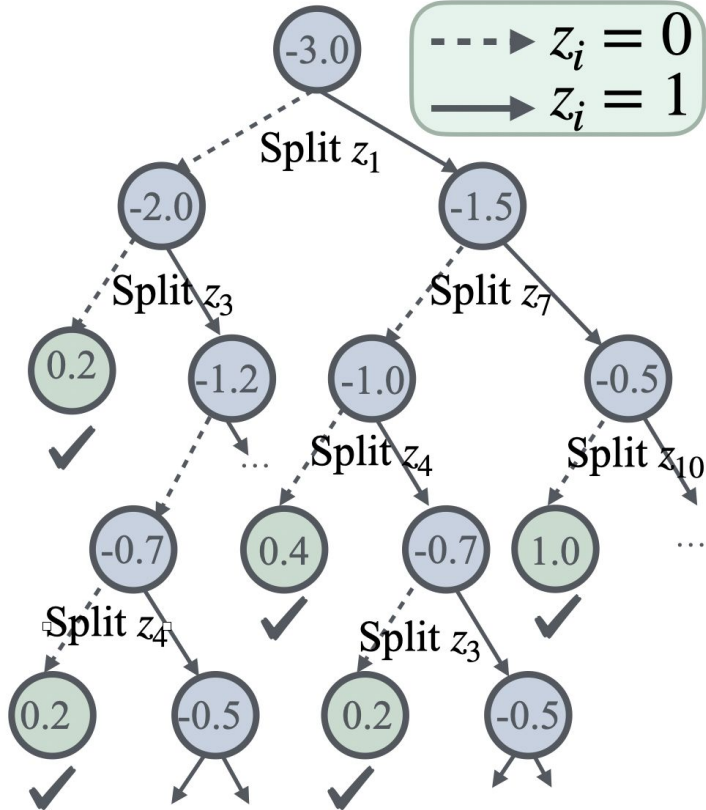
If  $z_1 = 0$  is not needed to make the path verifiable, we can get a strengthened cut.

Simplifying the cut by involving fewer  $z$  variables reduces the dimensionality of the hyperplane

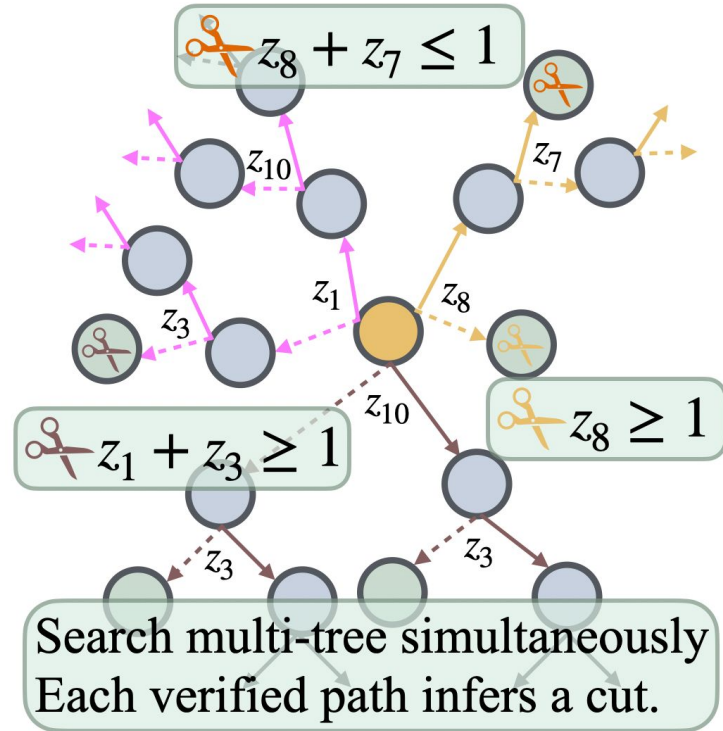


# Even more short cuts via Multi-Tree Searching (MTS)

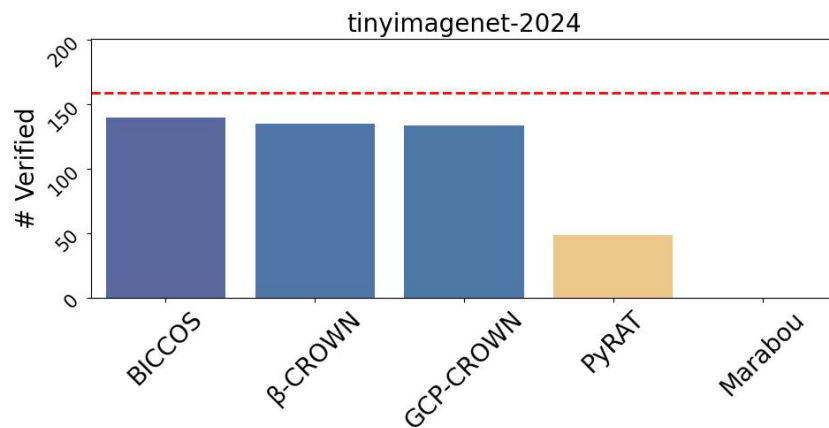
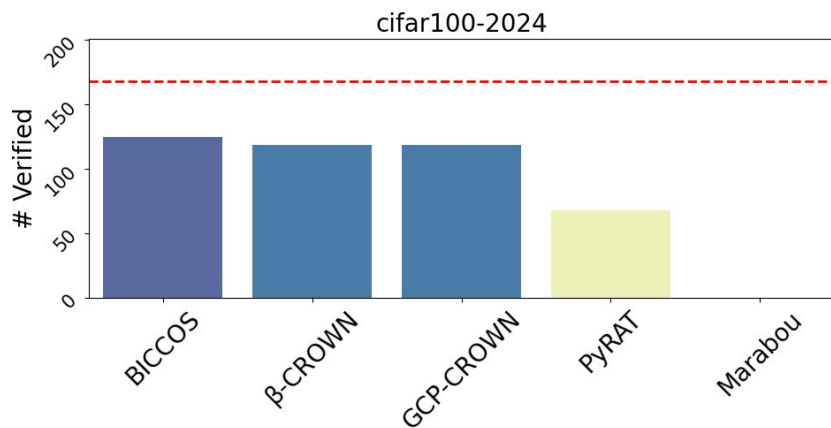
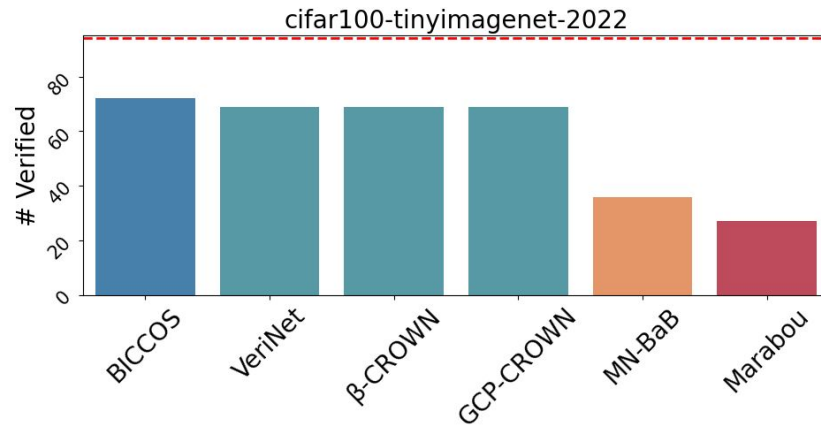
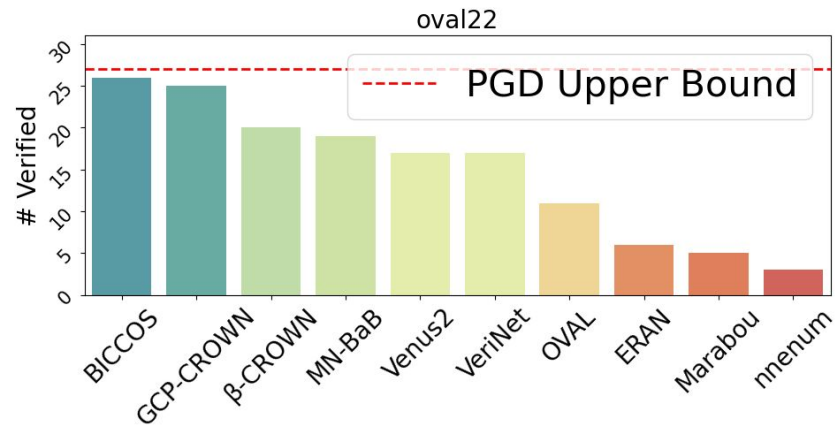
Regular BaB Search Tree



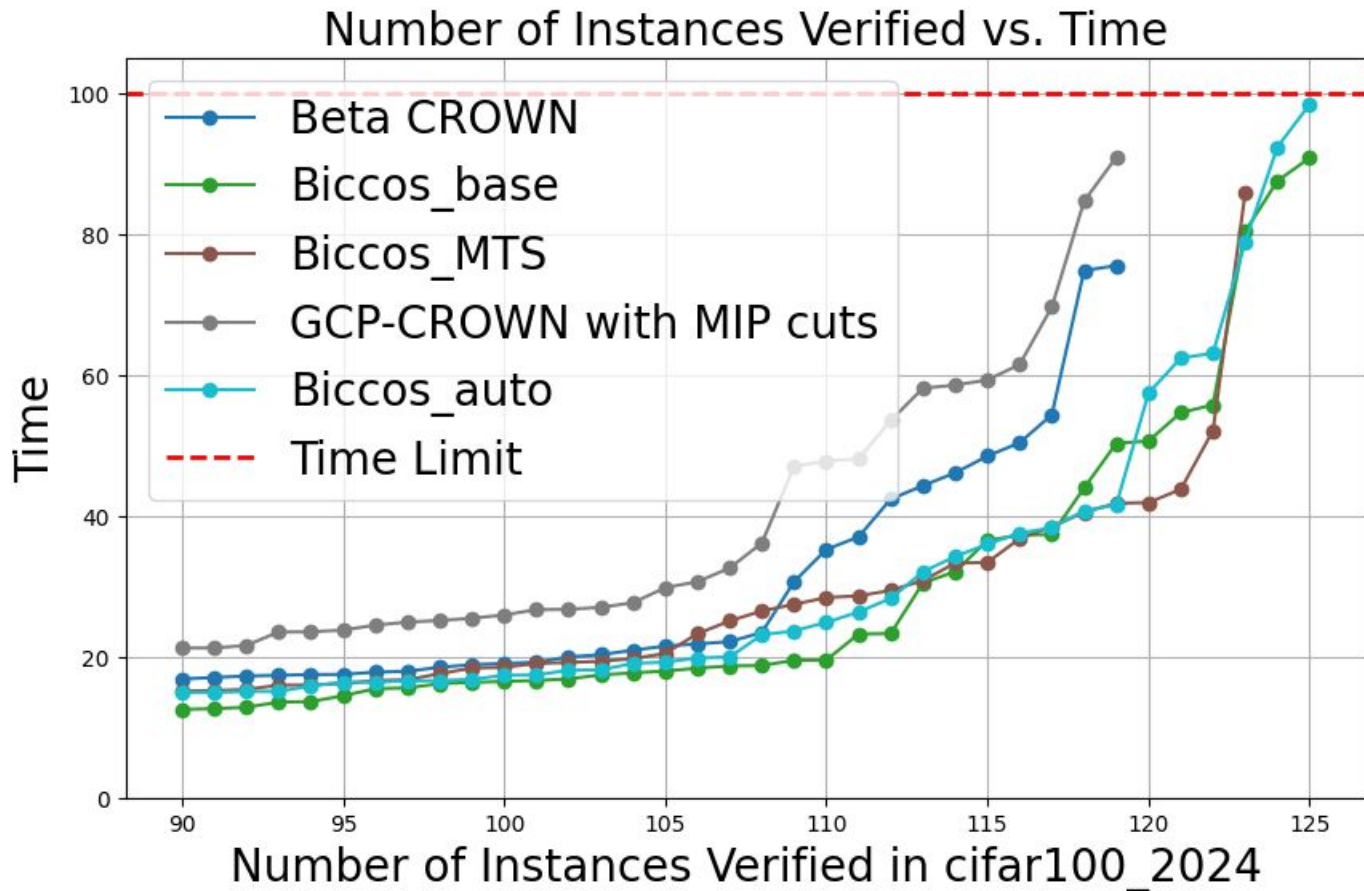
Multiple trees are searched in parallel, with cuts from one tree applied across others



# Results on VNN-COMP benchmarks



# Ablation study on components of BICCOS



# Conclusion

- Specialized and scalable cutting plane generation for NN verification
- Cut improvements with constraint strengthening and multi-tree search
- SOTA performance on multiple NN verification benchmarks
- Integrated to the SOTA verifier  $\alpha, \beta$ -CROWN: <https://abcrown.org>.



Winner of International Verification  
of Neural Networks Competitions  
VNN-COMP 2021-2024