

SAND

Smooth Imputation of Sparse And Noisy Functional Data With Transformer Networks

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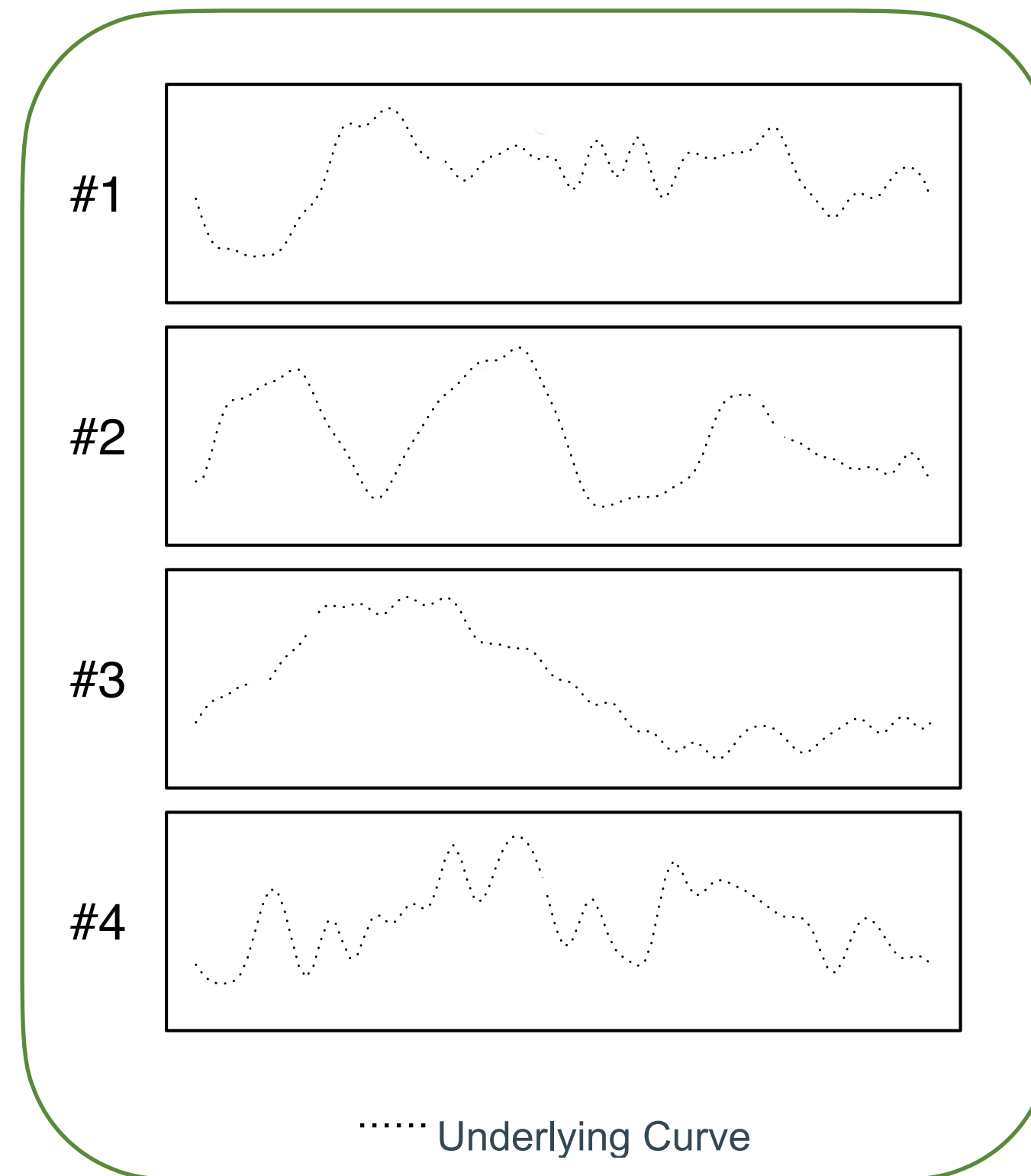
²Cleanlab

Sparse and Noisy Functional Data

- Functional data are random functions $X_i(t), t \in [0,1]$.

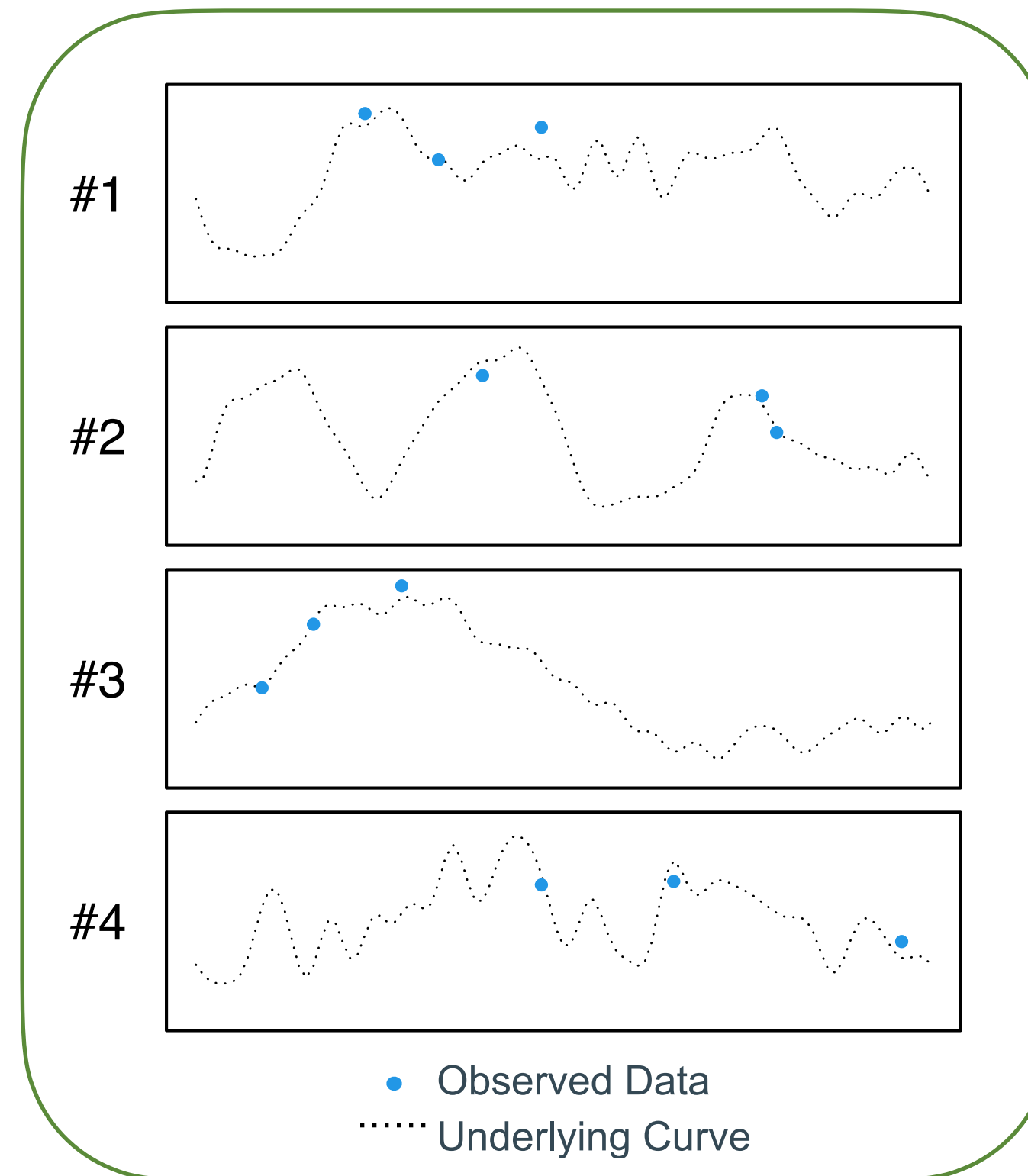
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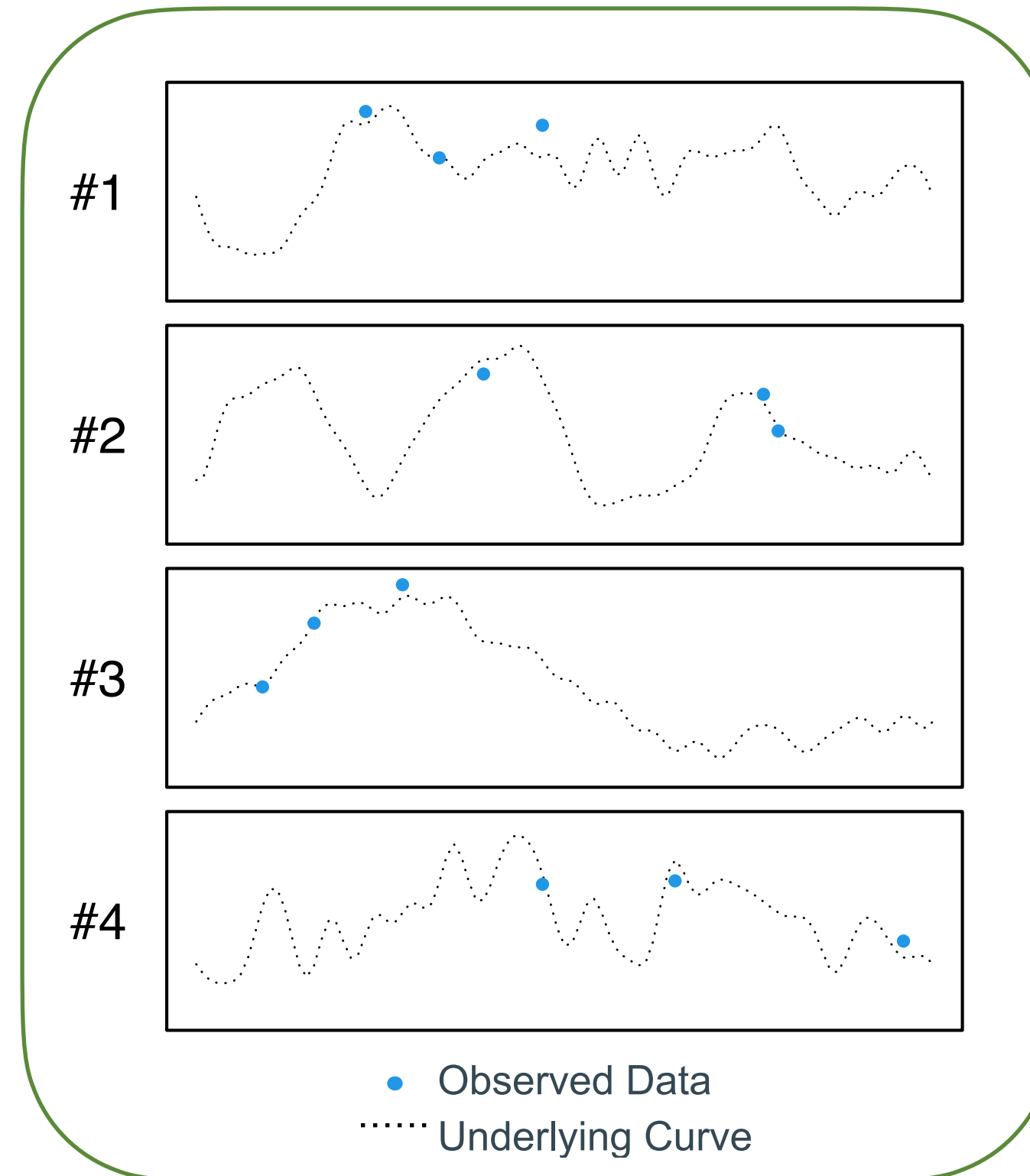
Sparse and Noisy Functional Data

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- $X_i(\cdot)$ is observed at time t_{i1}, \dots, t_{in_i}



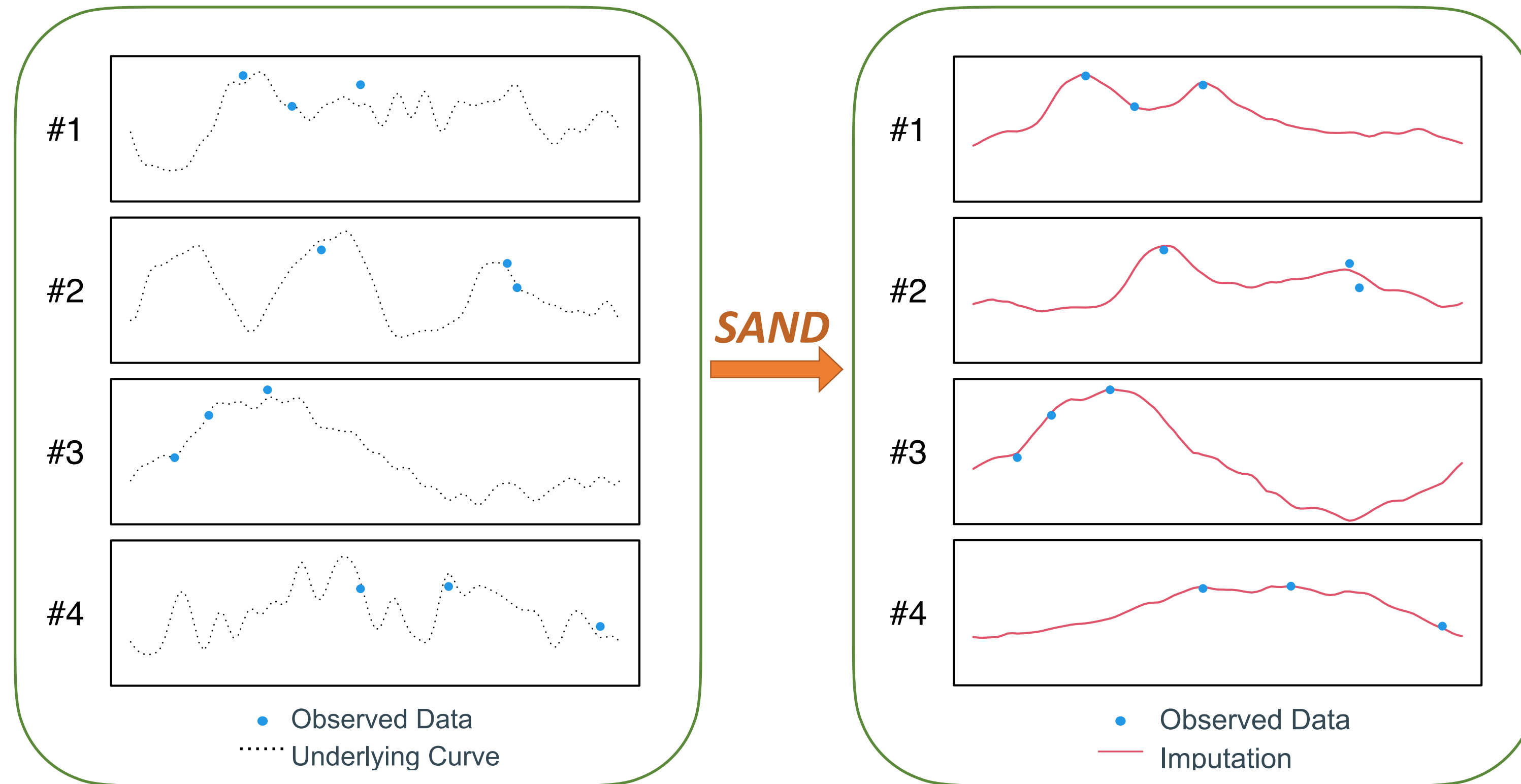
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- Observations: $Y_{ij} = X(t_{ij}) + \varepsilon_{ij}$.

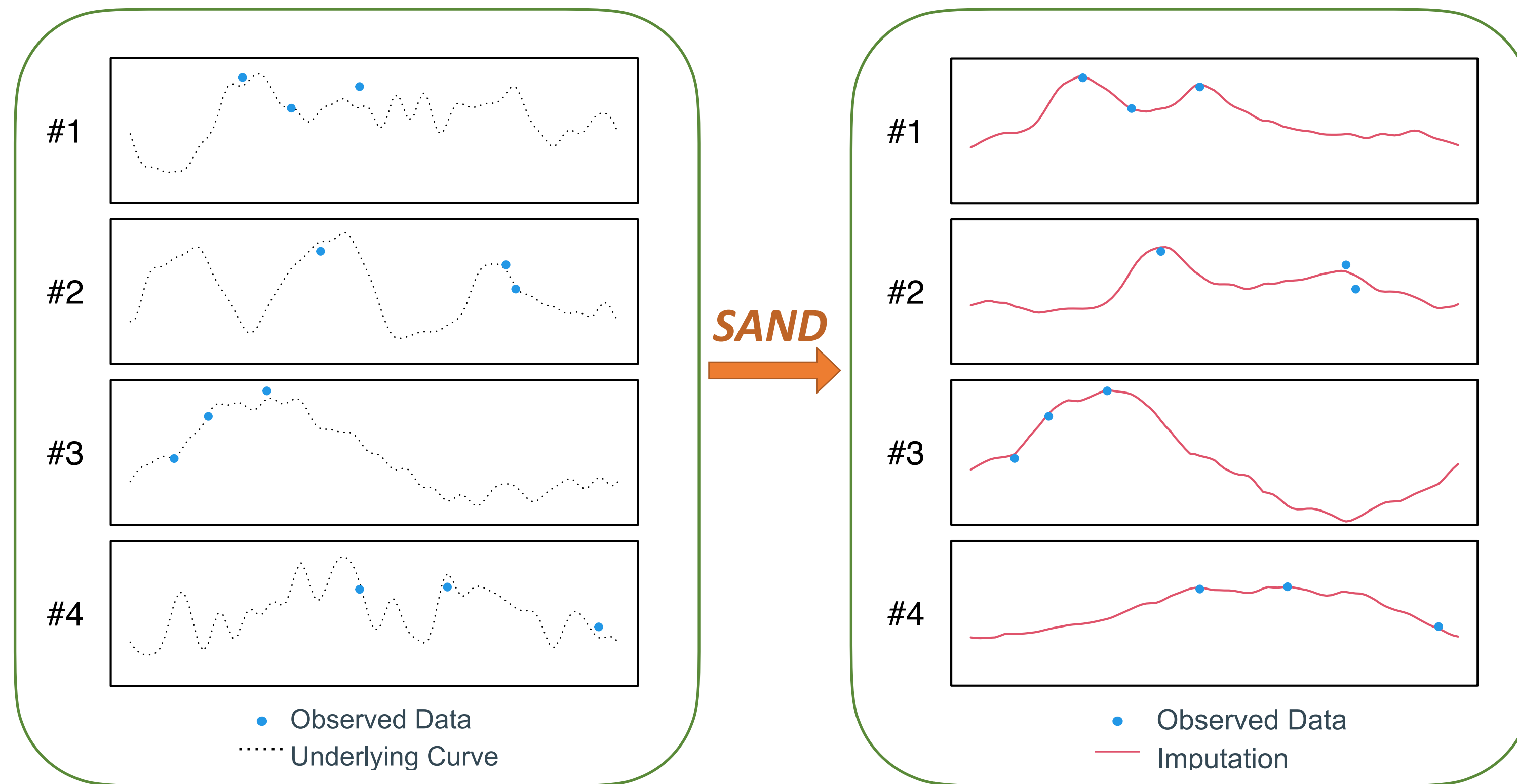


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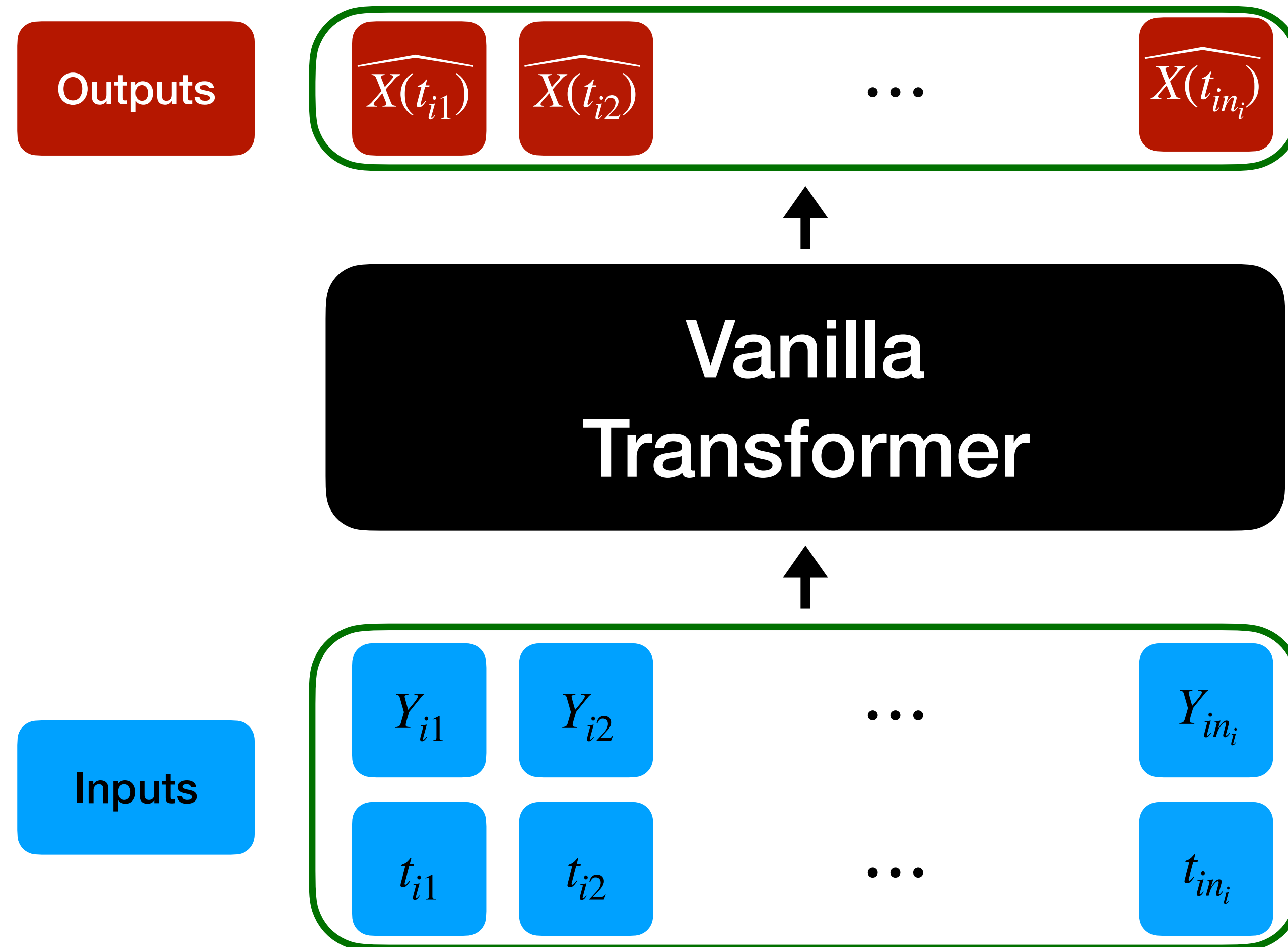
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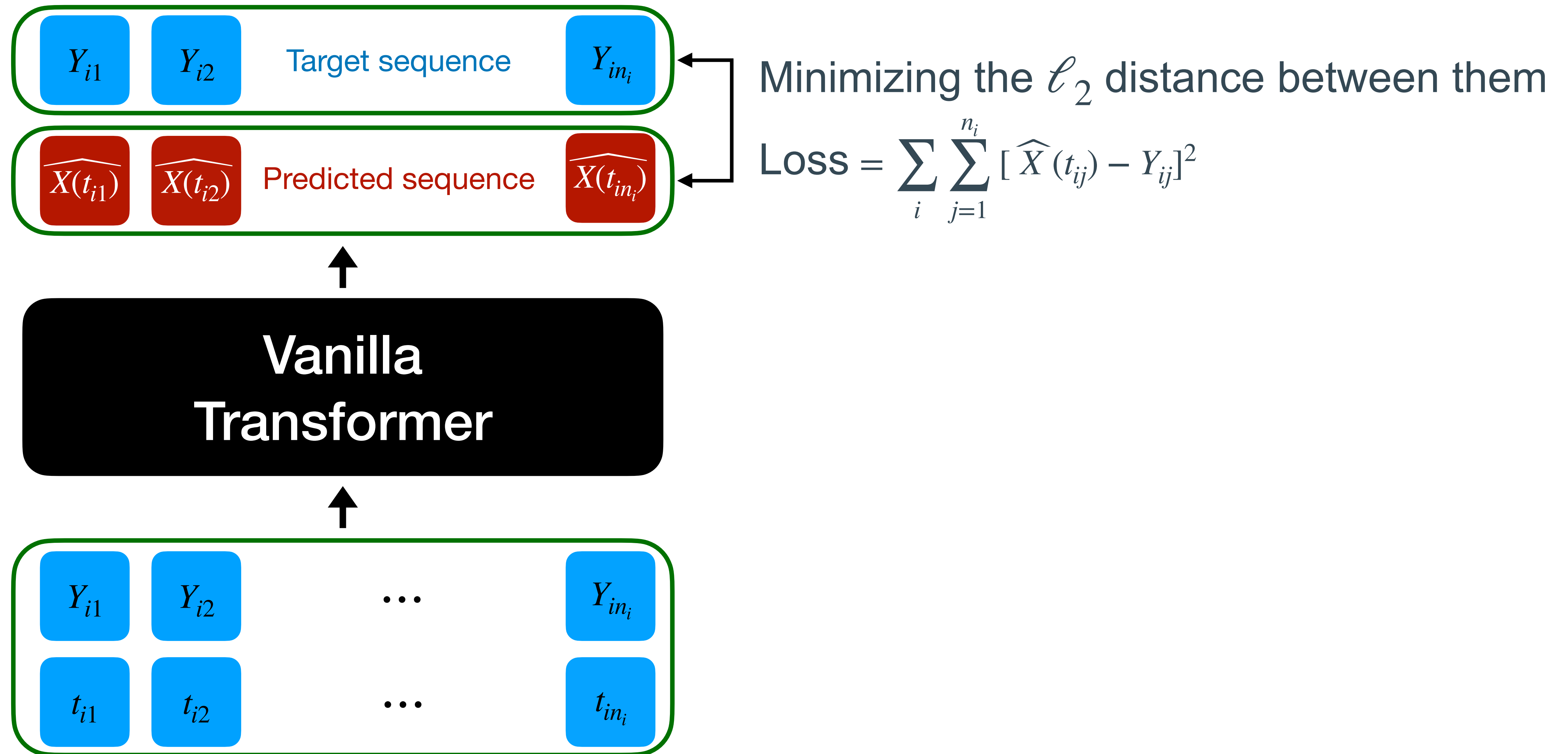
Goal: Recovering Underlying Curves



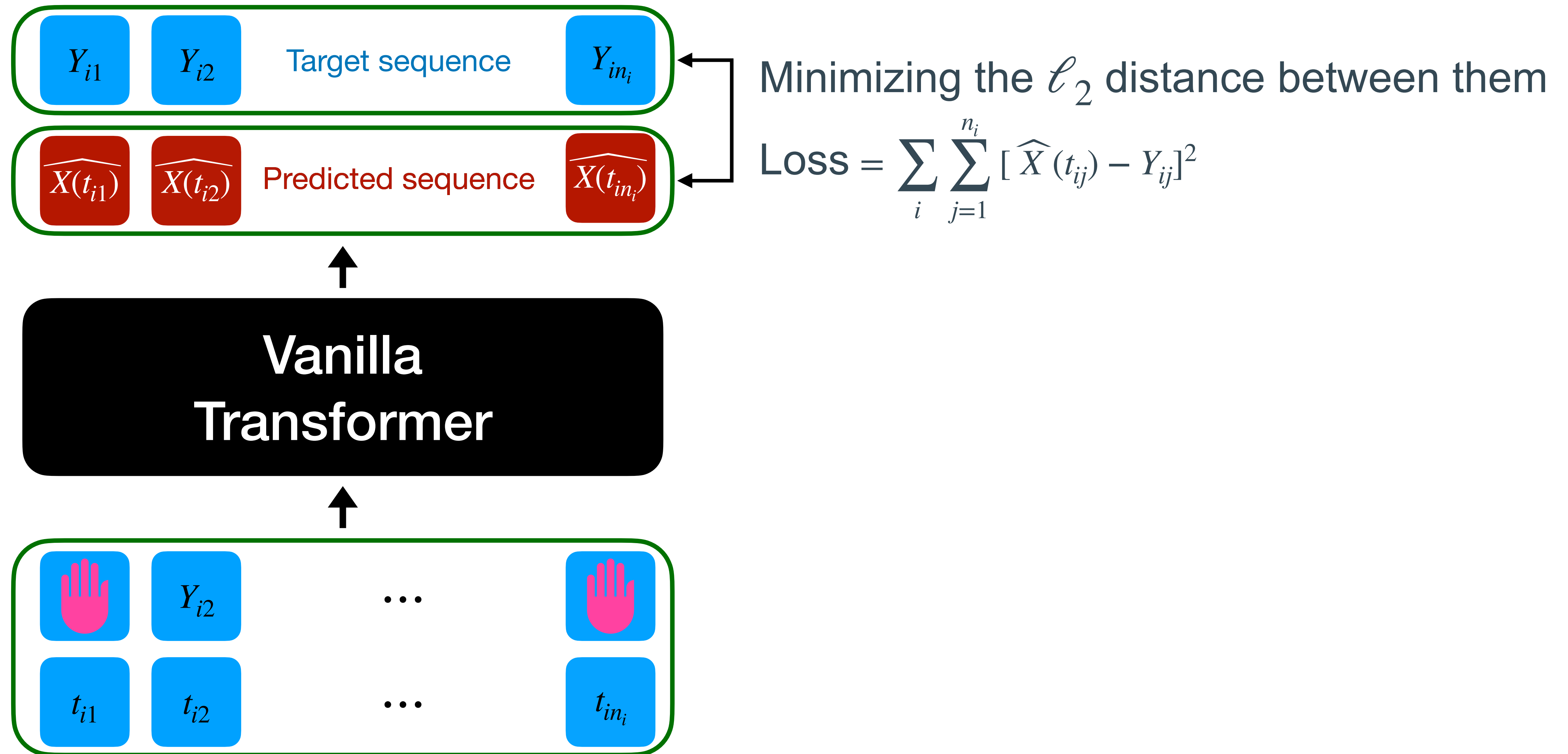
Limitations of Vanilla Transformers for Imputation



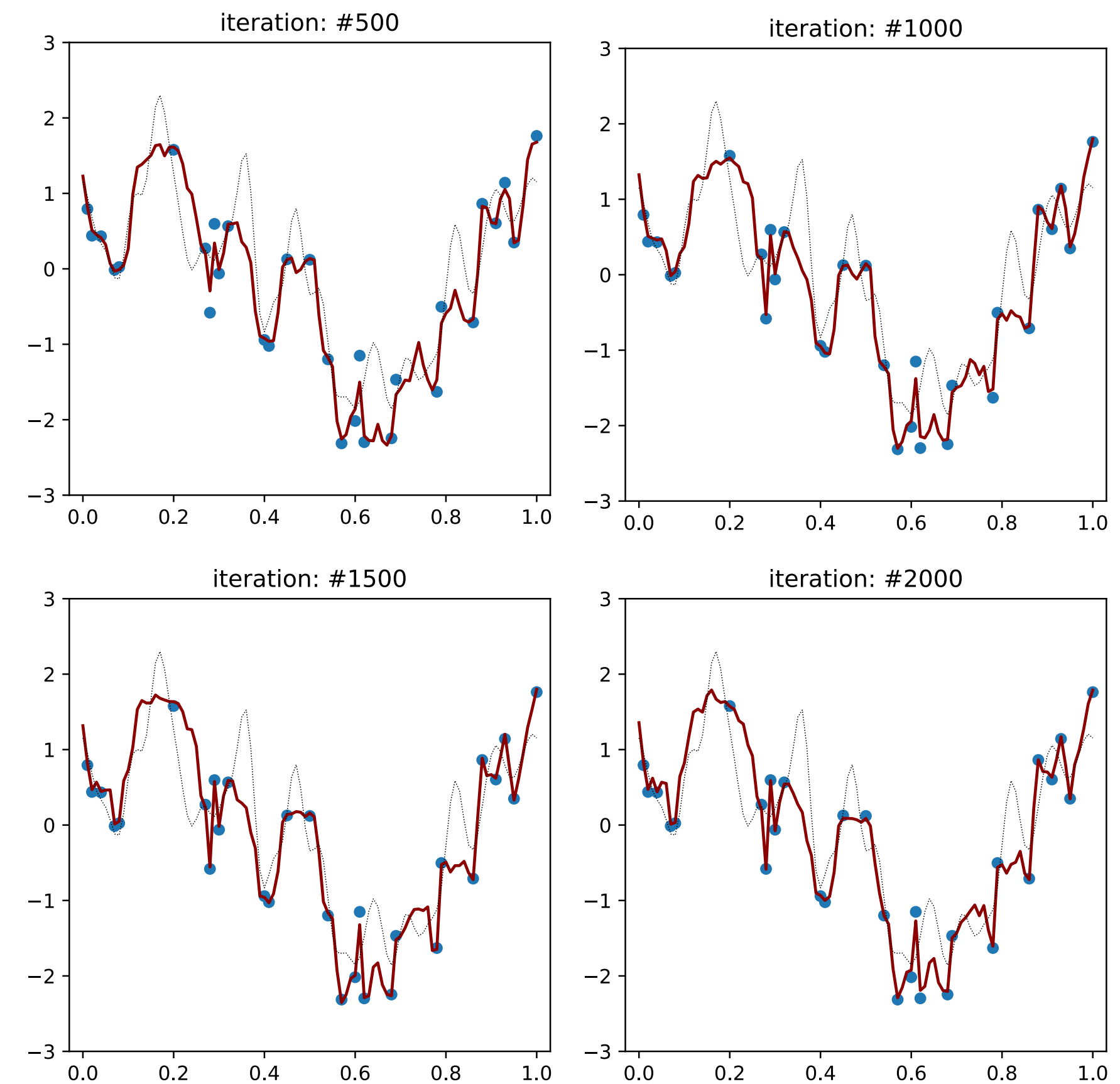
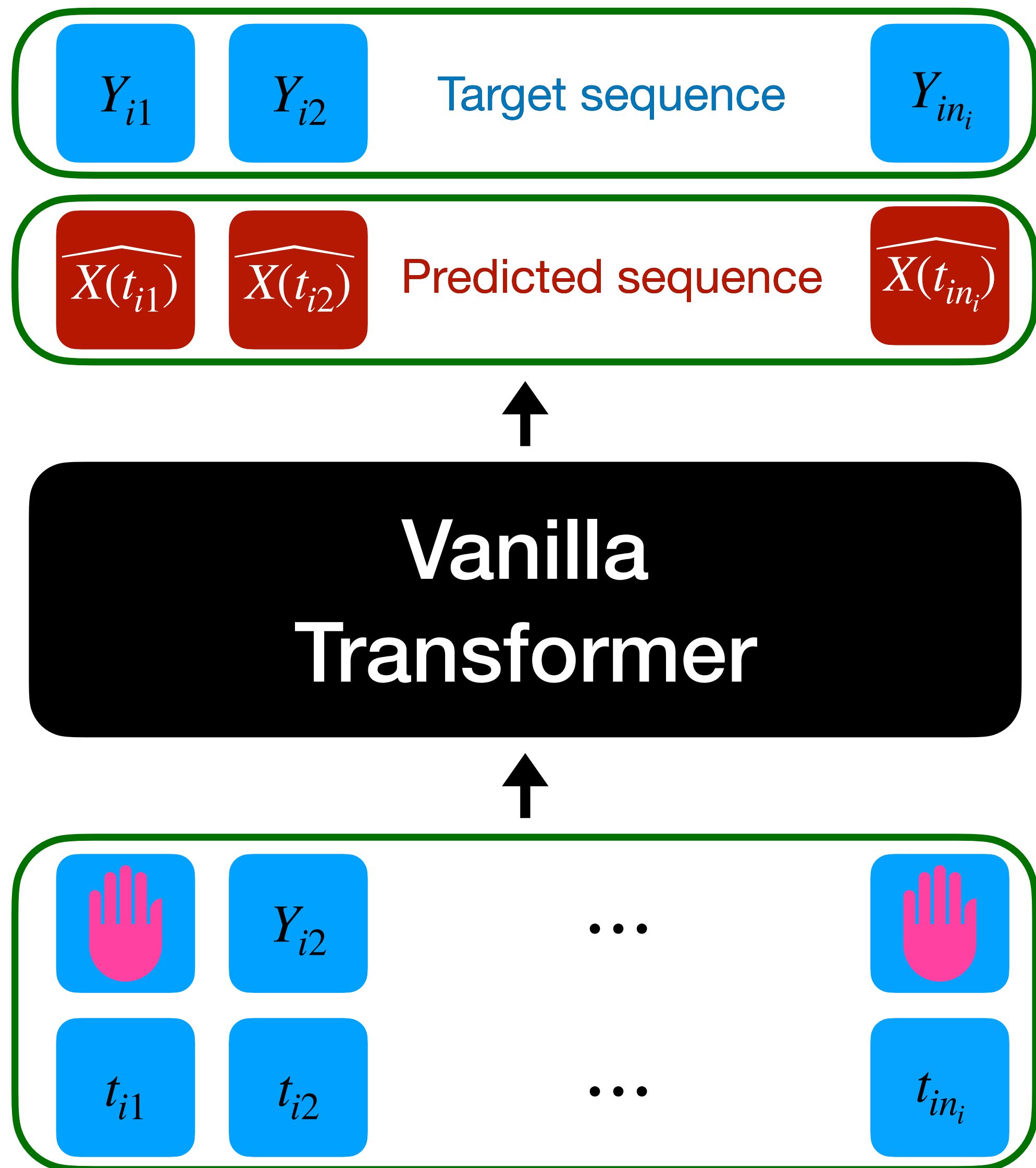
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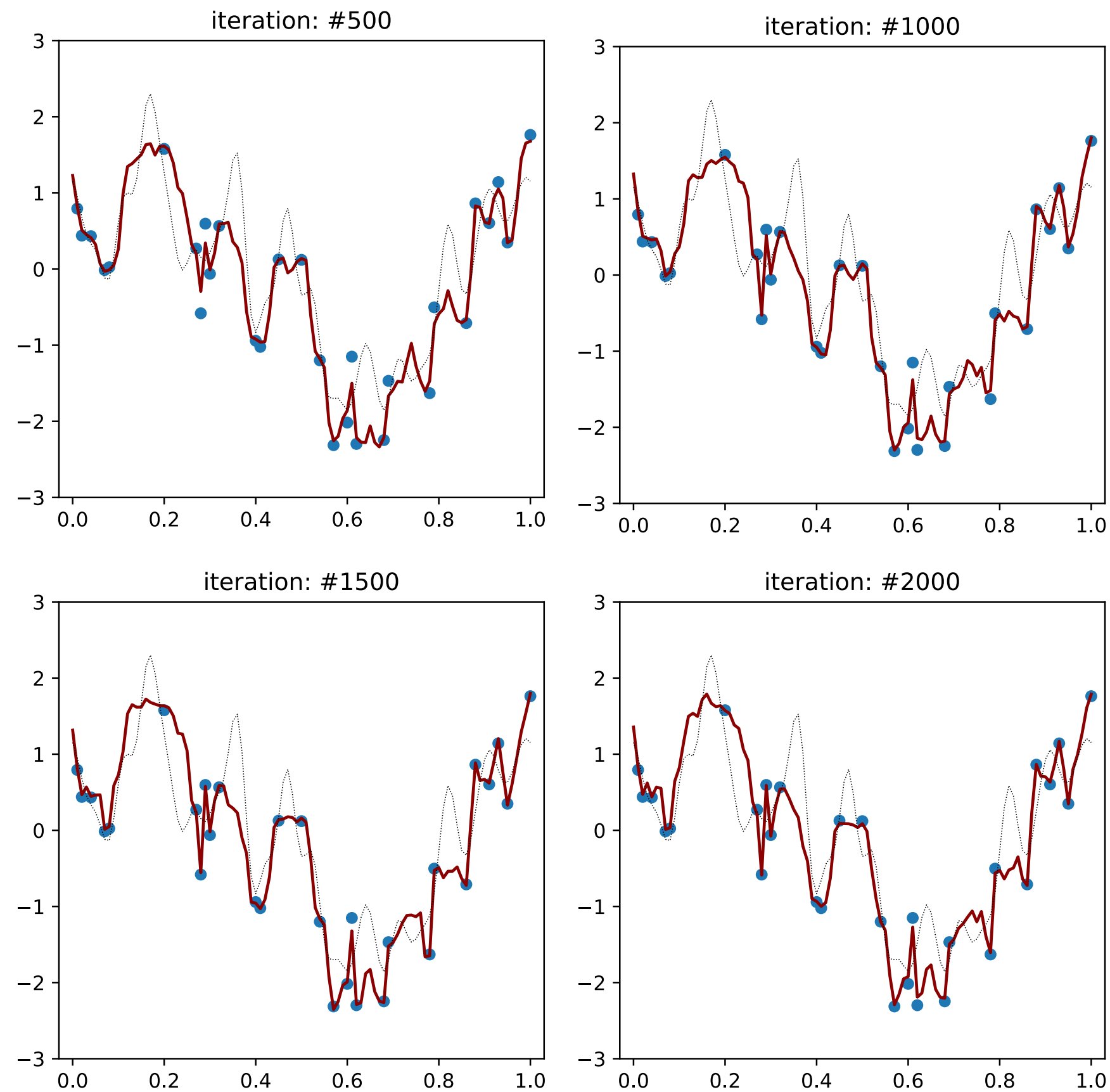


Limitations of Vanilla Transformers for Imputation



Vanilla Transformer:
Imputation Progress On **Testing Data** Over Iterations

Why vanilla transformers struggle with noisy data?



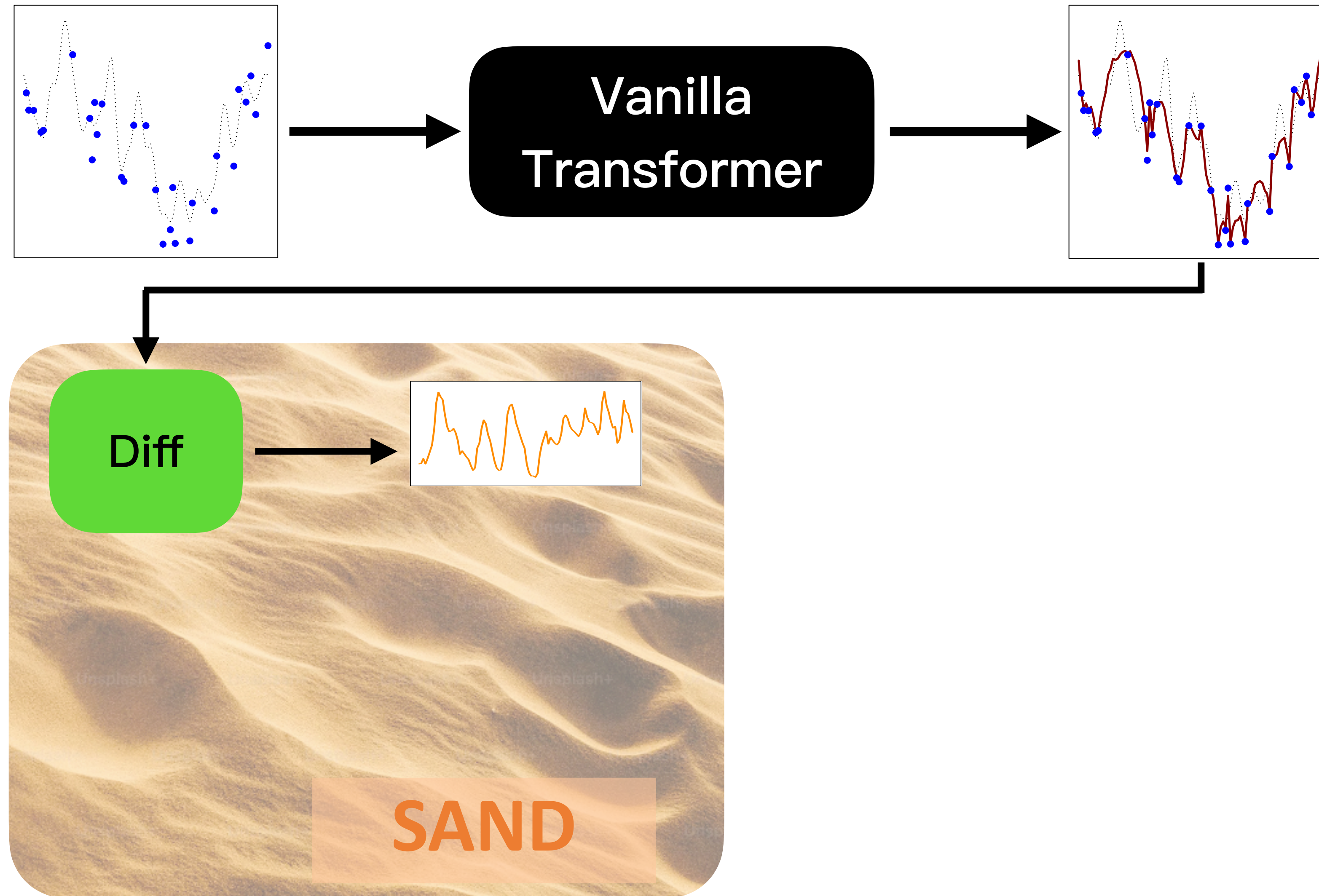
Vanilla Transformer:
Imputation Progress On **Testing Data** Over Iterations

- Transformers are universal approximators [4].
- Training data Y_{ij} are noisy.
- Imputed data mimics noise patterns

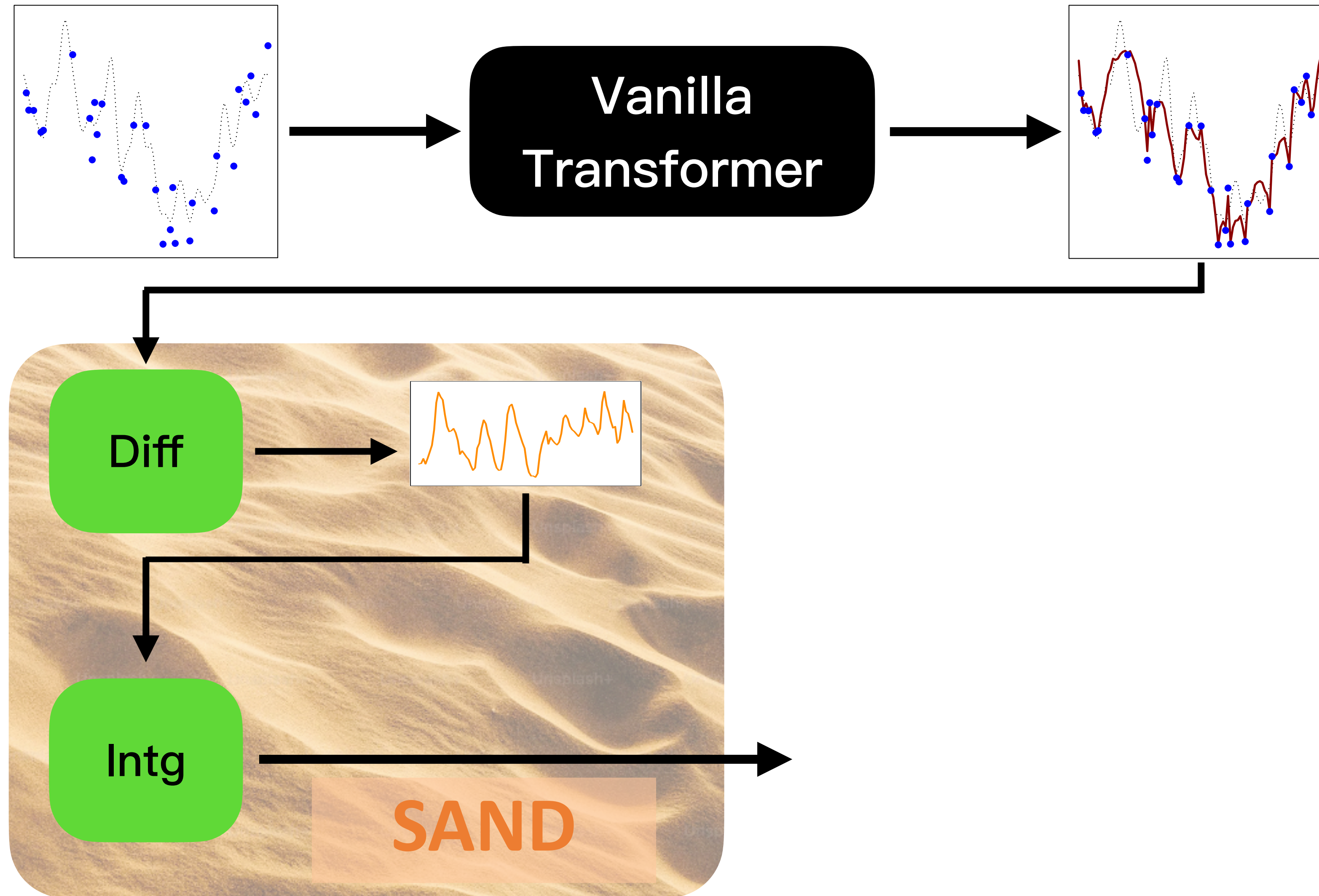
SAND — Self AtteNtion on Derivative



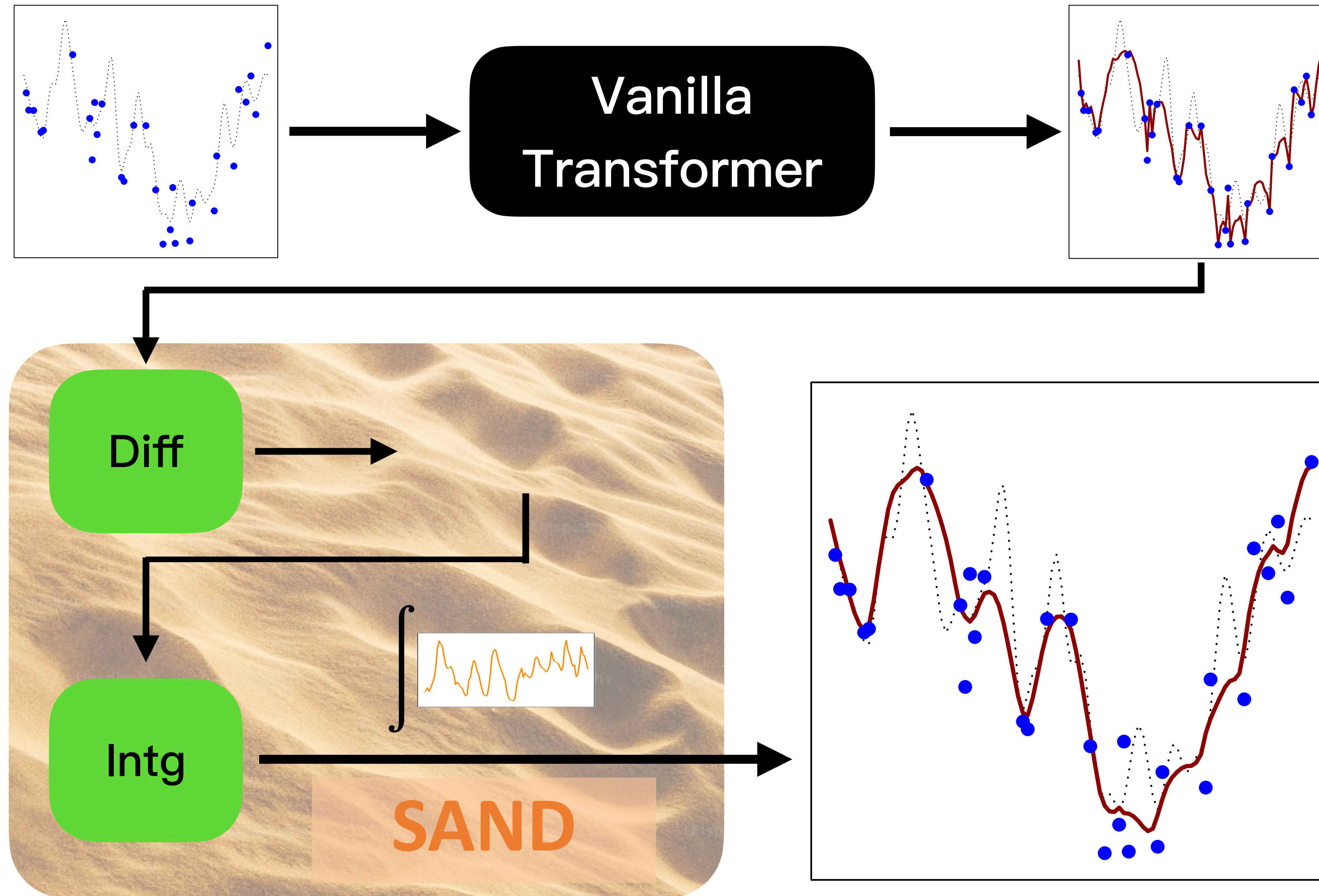
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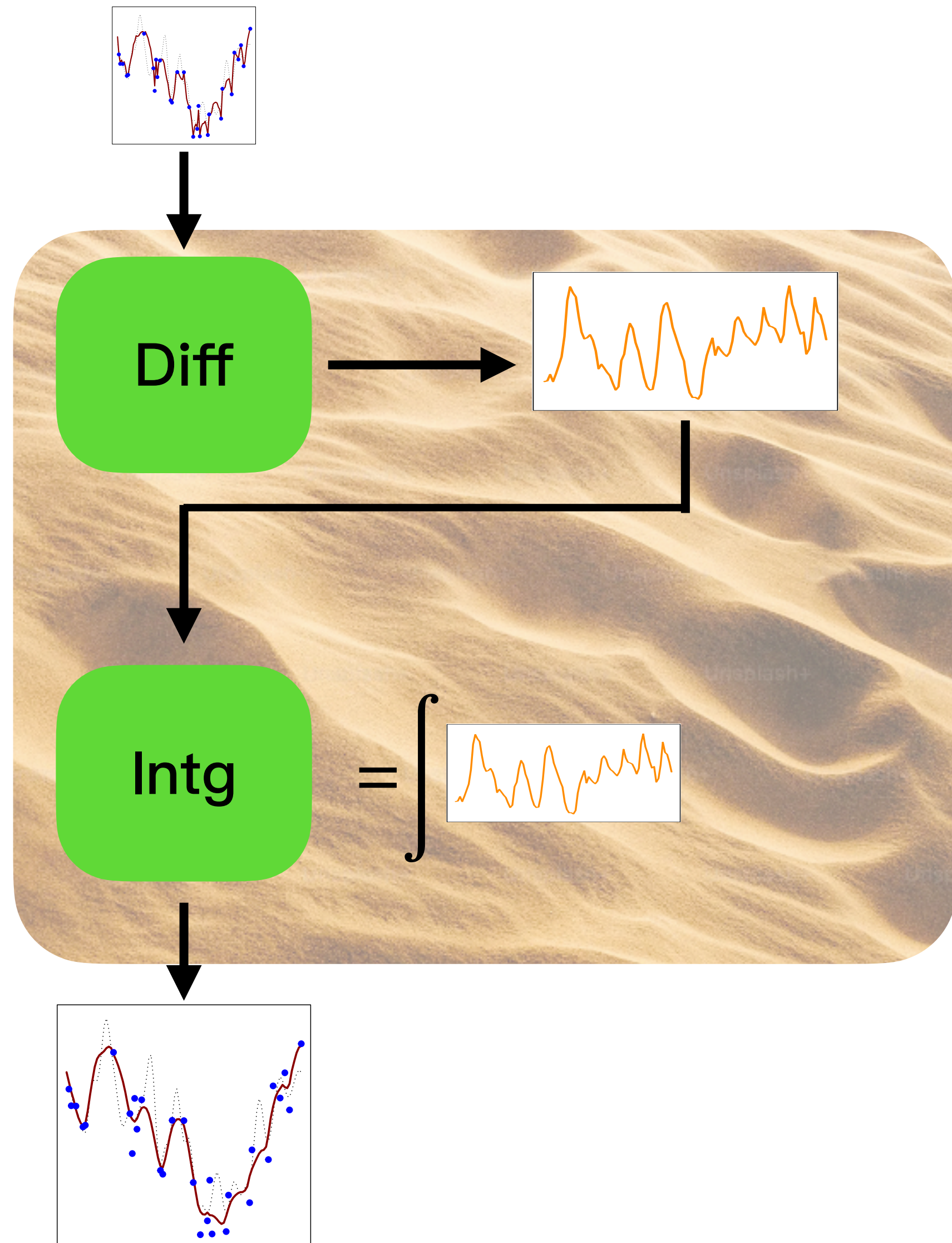


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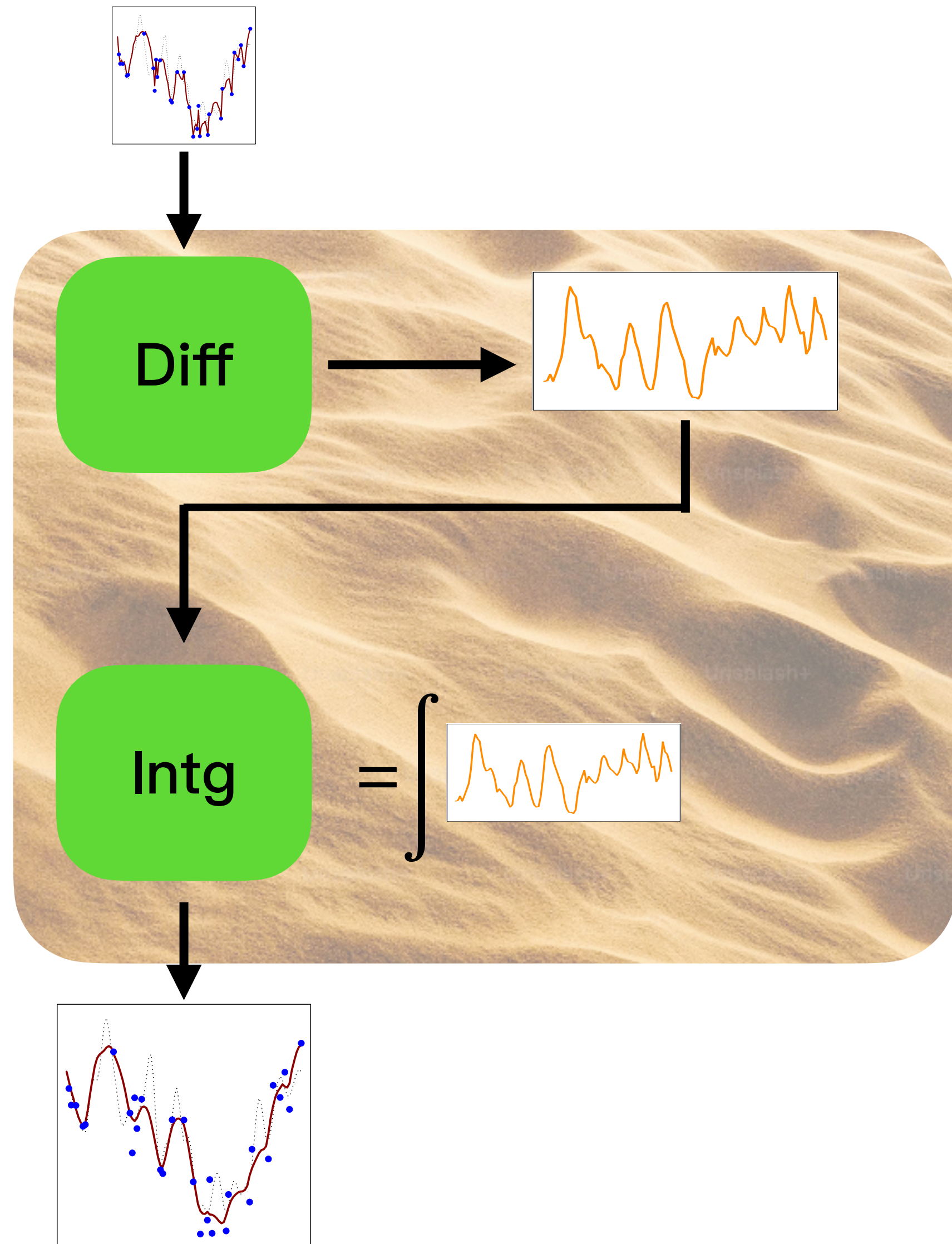


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Input: \tilde{T} , an coarse imputation from a vanilla transformer



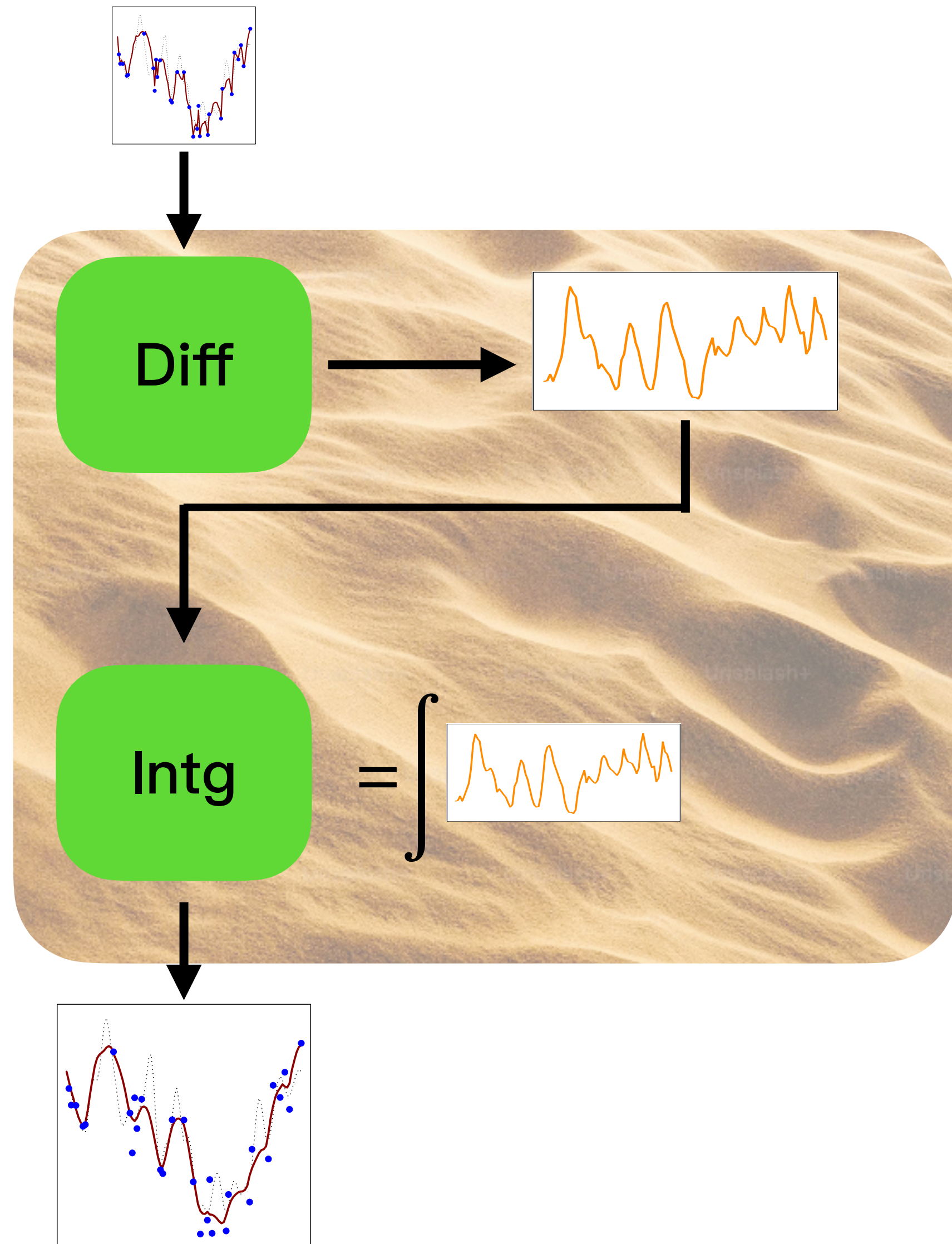
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Input: \tilde{T} , an coarse imputation from a vanilla transformer

$$\text{Diff}(\tilde{T}) = \sum_{h=1}^H W_O^{(h)} \left(W_V^{(h)} \tilde{T} \right) \left[\left(W_K^{(h)} \tilde{T} \right)^\top \left(W_Q^{(h)} \tilde{T} \right) / \sqrt{h_d} \right]$$

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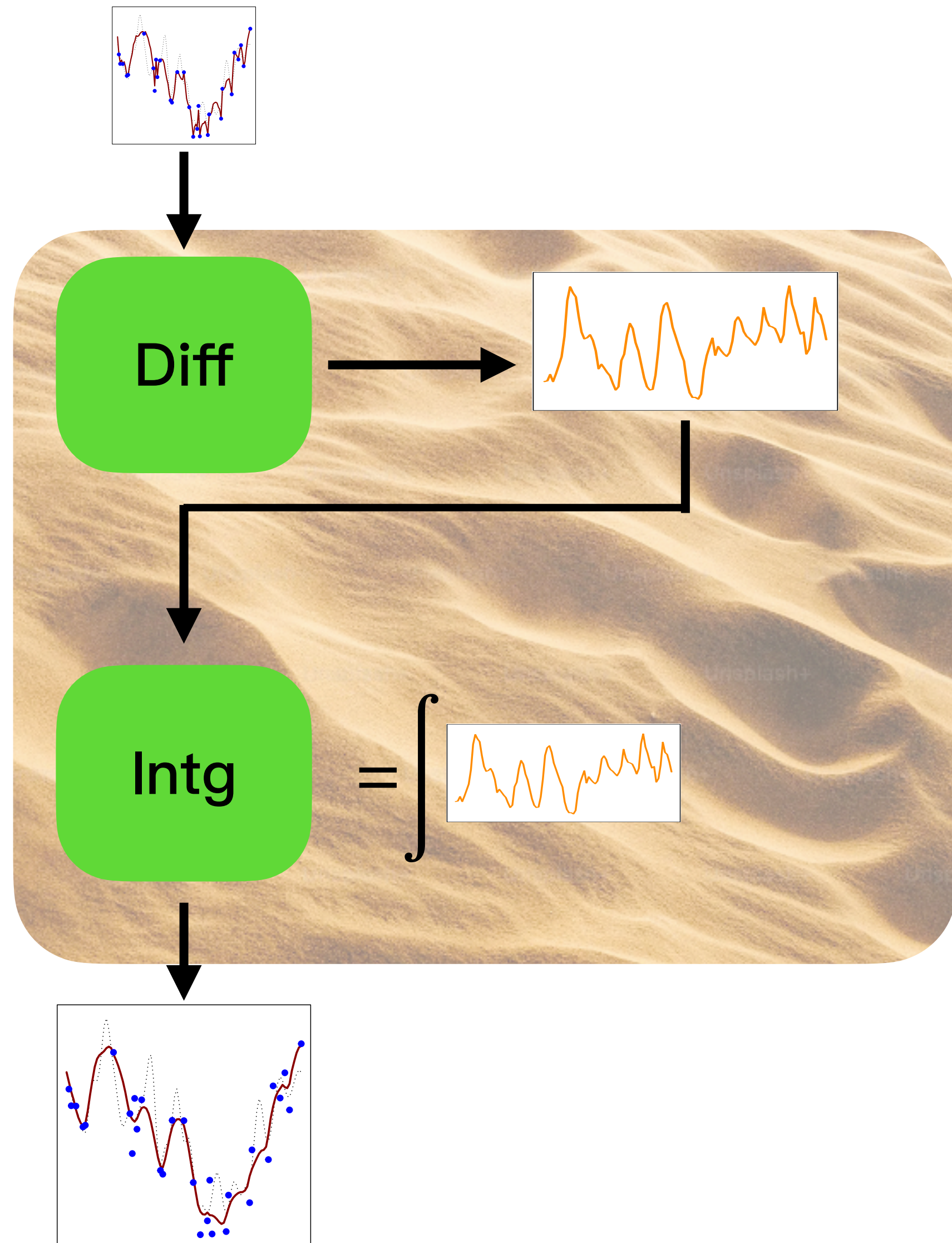


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$$\text{Diff}(\tilde{T}) = \sum_{h=1}^H W_O^{(h)} \left(W_V^{(h)} \tilde{T} \right) \left[\left(W_K^{(h)} \tilde{T} \right)^T \left(W_Q^{(h)} \tilde{T} \right) / \sqrt{h_d} \right]$$

Intg is the cumulative summation operator.

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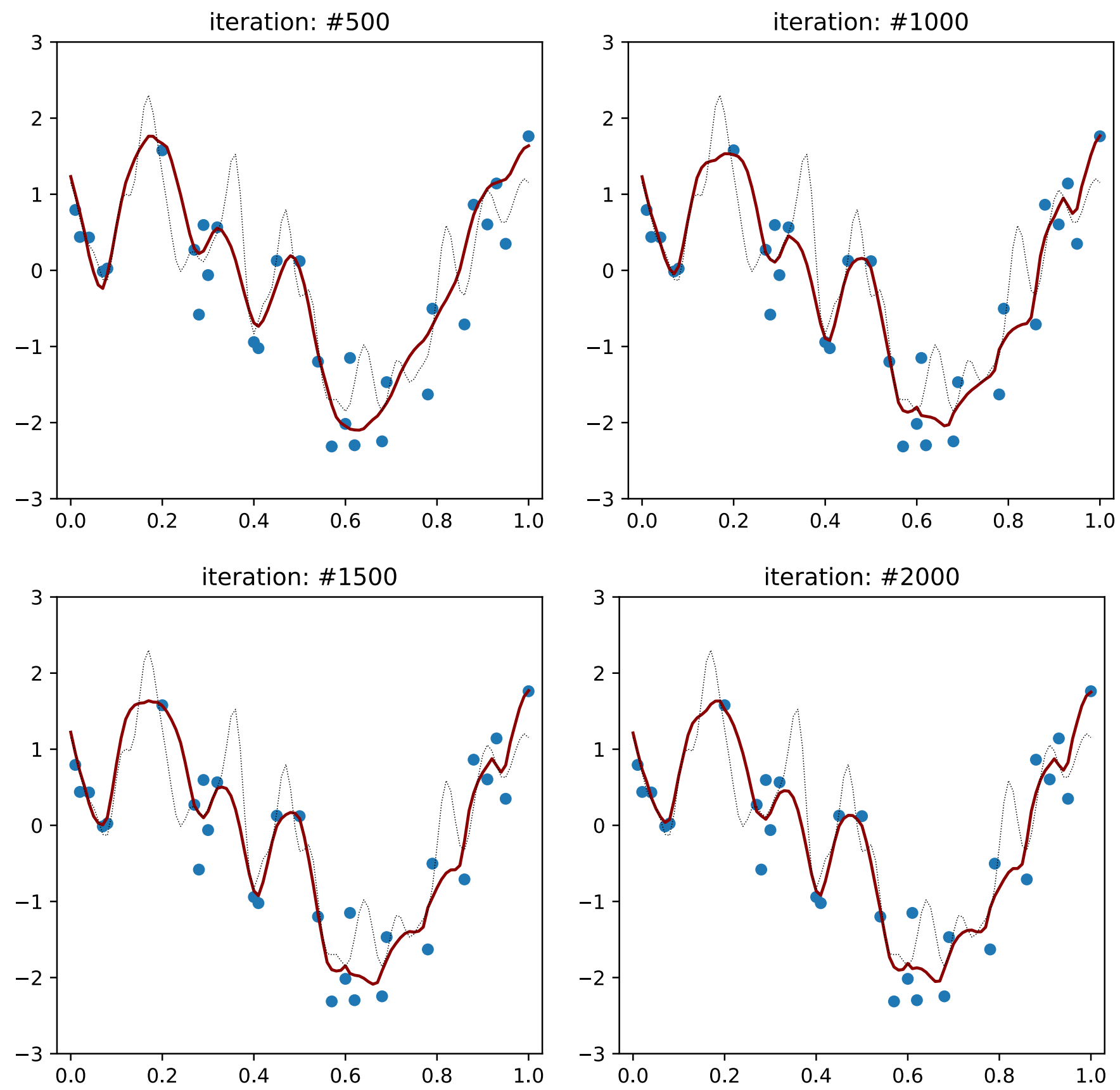
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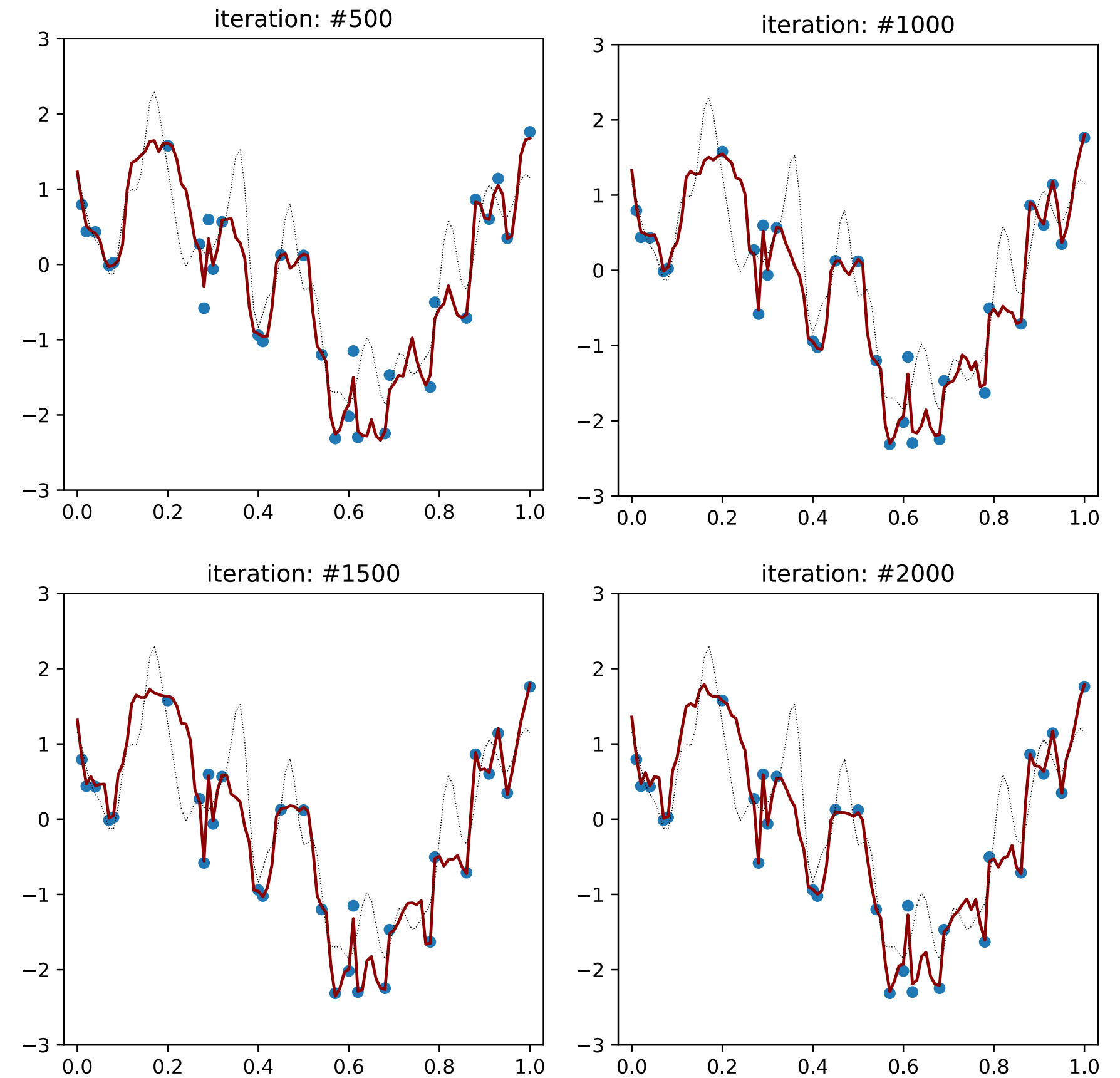
Intg is the cumulative summation operator.

Output: a smooth version of an input
 $\text{SAND}(\tilde{T}) = (\tilde{T})_1 + \text{Intg}[\text{Diff}(\tilde{T})]$

SAND — Compared to Vanilla Transformers



Imputation from SAND Over Iterations



Imputation from Vanilla Transformer Over Iterations

Simulation Studies

- Sample size $n = 10,000$. Signal-to-noise ratio = 4

	$n_i = 30$		$n_i = 8 \text{ to } 12$		$n_i = 3, 4, 5$	
	MSE(SD)	TV(SD)	MSE(SD)	TV(SD)	MSE(SD)	TV(SD)
PACE[1]	189.9(4.3)	187.1(2.0)	450.0(15)	201.9(2.1)	795.5(33)	209.5(2.2)
FACE[5]	284.6(8.8)	198.9(2.1)	488.2(16)	204.5(2.2)	807.1(32)	209.5(2.2)
mFPCA[6]	224.7(5.8)	192.0(2.1)	480.3(16)	204.0(2.2)	787.1(31)	209.3 (2.2)
MICE[7]	176.7(3.7)	233.1(1.7)	721.6(27)	318.4(3.0)	1416(57)	332.7(2.8)
CNP[2]	290.4(11)	198.9(2.0)	551.3(21)	207.6(2.1)	920.3(52)	211.9(2.2)
GAIN[8]	261.9(6.8)	350.0(3.4)	1767(52)	743.3(5.1)	2065(51)	759.2(4.3)
1DS	262.9(6.0)	273.8(2.4)	735.3(22)	305.7(3.7)	1157(43)	263.3(3.1)
Transformers and our method						
VT[3]	169.8(3.2)	218.2(1.7)	436.7(15)	227.0(2.2)	798.6(35)	230.6(2.6)
VTP	169.0(3.5)	179.9(2.0)	425.3(14)	199.4 (2.1)	777.4 (36)	210.2(2.2)
SAND	146.5 (2.7)	164.6 (1.8)	410.9 (13)	196.8 (2.0)	758.1 (43)	206.8 (2.2)

*MSE, TV: the smaller the better

Read Data

- Impute $n = 5500$ household's energy usage in London from Nov 13 — 14, 2013

	UK electricity					
	$n_i = 30$		$n_i = 8 \text{ to } 12$		$n_i = 3, 4, 5$	
	MSE(SD)	TV(SD)	MSE(SD)	TV(SD)	MSE(SD)	TV(SD)
PACE	12.8(1.8)	19.0 (1.1)	30.1 (4.5)	21.1 (1.2)	39.6 (5.2)	21.9 (1.2)
FACE	15.8(2.1)	21.3(1.2)	32.5(5.4)	22.6(1.2)	39.6 (5.2)	23.0(1.2)
mFPCA	16.4(2.0)	22.2(1.2)	34.8(4.9)	23.2(1.2)	41.7(5.4)	23.3(1.2)
MICE	20.4(2.2)	67.8(3.3)	40.0(4.5)	65.4(2.8)	75.4(8.6)	71.4(1.5)
CNP	23.0(3.5)	21.4(1.2)	31.5(4.3)	22.1(1.2)	47.9(7.1)	22.7 (1.2)
GAIN	31.9(3.7)	108(5.6)	75.4(8.2)	104(6.7)	99.6(15)	121(2.4)
1DS	17.3(2.2)	19.4(1.1)	50.0(7.0)	22.8(1.3)	105(18)	44.1(2.7)
VT	10.7 (1.8)	20.6(1.1)	31.2(3.3)	23.2(1.3)	42.6(5.6)	38.5(2.5)
SAND	10.0 (1.9)	15.7 (0.9)	26.7 (3.0)	20.1 (1.2)	38.3 (5.1)	25.5(1.6)

Reference

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