

Are Multiple Instance Learning Algorithms Learnable for Instances?

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I. Introduction

- **Multiple Instance Learning (MIL)**
 - **Learns from labels assigned to bags and performs predictions at both the bag and instance levels.**
 - **Ex) Video-Snippets, Review-Words, Image-Patch, Sliding window-Time point**
 - **Most research primarily focuses on enhancing prediction performance at the bag level, rather than the instance level.**

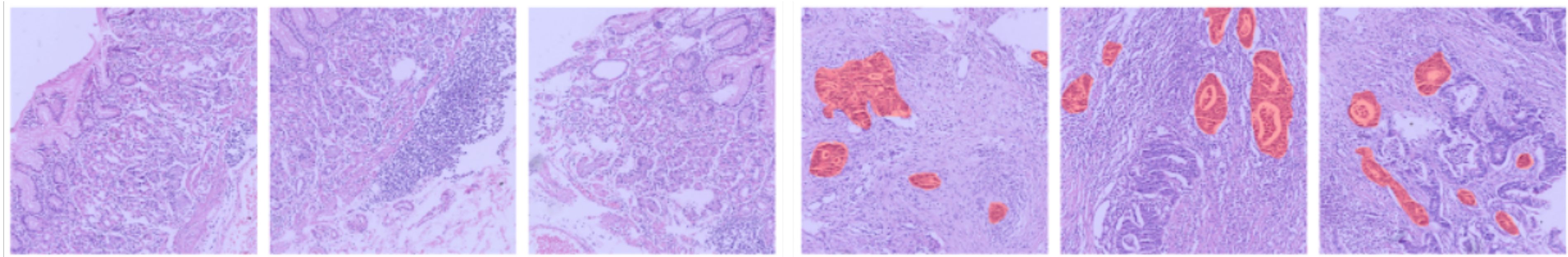


Figure 1. The data structure consisting of multi-instances (Blue: Negative, Red: Positive)

II. Problem Setting

- **Definition 4. PAC Learnability of Bag**

$$\mathbb{P}_{S \sim D_{XY}^m} [|R_{bag}(A(S)) - \inf_{h \in \mathcal{H}_{bag}} R_{bag}(h)| \leq \epsilon] \geq 1 - \delta$$

- **Definition 5. PAC Learnability of Instance**

$$\mathbb{P}_{S_{inst_i} \sim D_{X_{inst_i} Y}^m} [|R_{inst_i}(A(S_{inst_i})) - \inf_{h \in \mathcal{H}_{inst_i}} R_{inst_i}(h)| \leq \epsilon] \geq 1 - \delta$$

- **Definition 6.** *If the MIL algorithm satisfies Condition 2, it is learnable for instances.*

Condition 2. *The Deep MIL algorithm A must exhibit equivalent PAC learnability for bags and instances:*

$$\mathbb{P} \left[|R_{bag}(A(S)) - \inf_{h \in \mathcal{H}_{bag}} R_{bag}(h)| \leq \epsilon \wedge \bigcap_{i=1}^n |R_{inst_i}(A(S_{inst_i})) - \inf_{h \in \mathcal{H}_{inst_i}} R_{inst_i}(h)| \leq \epsilon \right] \geq 1 - \delta$$

II. Problem Setting

- **Theorem 1.** *If MIL algorithm A satisfies Condition 1, then this algorithm is not PAC learnable for any instance domain space $\mathcal{D}_{X_{inst_i}Y}$ and instance hypothesis space $\mathcal{H}_{inst_i} \subset \{h_{inst_i} : X \rightarrow Y\}$.*

$$\mathbb{P} \left[\bigcup_{i=1}^n |R_{inst_i}(A(S_{inst_i})) - \inf_{h \in \mathcal{H}_{inst_i}} R_{inst_i}(h)| > \epsilon \right] > \delta$$

- **Condition 1.** *The MIL algorithm A is not PAC learnable for the given domain space \mathcal{D}_{XY} and bag hypothesis space $\mathcal{H}_{bag} \subset \{h_{bag} : X \rightarrow Y\}$:*

$$\mathbb{P} \left[|R_{bag}(A(S)) - \inf_{h \in \mathcal{H}_{bag}} R_{bag}(h)| > \epsilon \right] > \delta$$

- **Assumption 1.** *The MIL algorithm is PAC learnable for bags.*

III. Proposed Theoretical Framework

III.I. Summary of Framework

Priori Learnability Theorems for Instances

Theorem 1: Relationship between learnability for Bags and learnability for Instances

Consequence: If an MIL algorithm is not PAC learnable for bags, it cannot be PAC learnable for instances.

Assumption 1: The MIL algorithm is PAC learnable for bags

Theorem 4: PAC Learnability for Bags in D_{XY}^{Ind}

Consequence: All MIL pooling techniques are PAC trainable on D_{XY}^{Ind} to Bag.

(Instance, Embedding, Attention, Additive, Conjunctive-Pooling)

Example: In drug activity prediction, MIL analyzes various independent chemical structures of a drug candidate to predict whether the candidate is active against a disease.

Theorem 5: PAC Learnability for Bags in D_{XY}^{Gen}

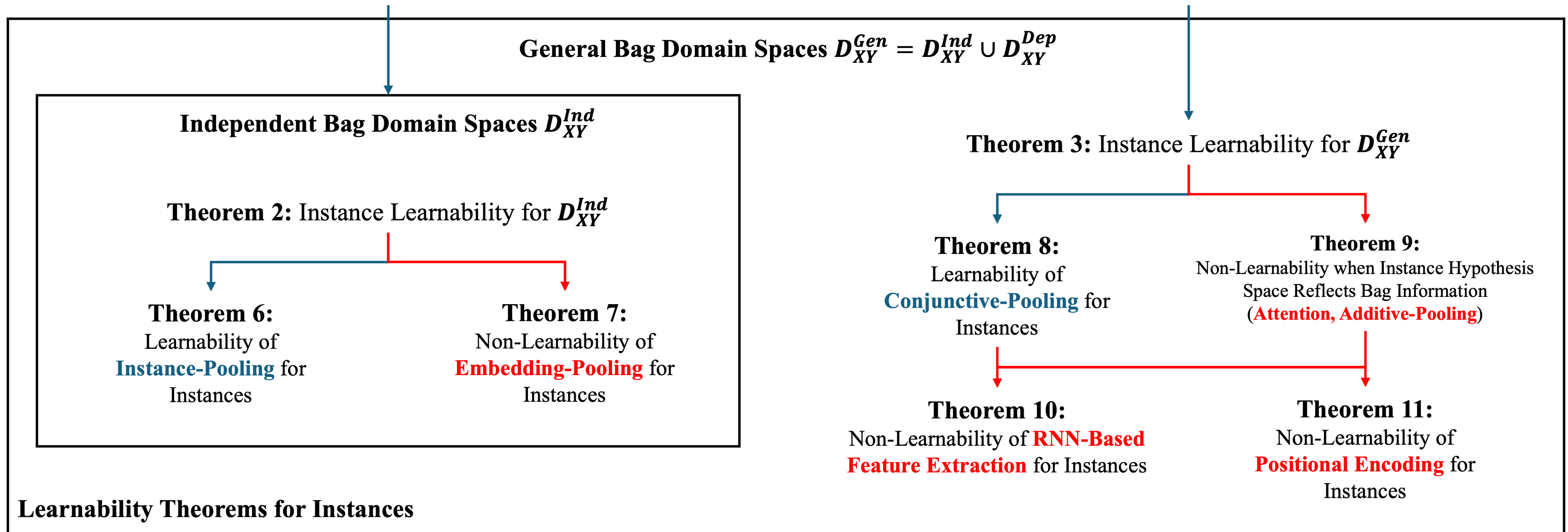
Consequence: For MIL algorithms to be PAC learnable in D_{XY}^{Gen} , the use of an attention mechanism is necessary.

(Attention, Additive, Conjunctive-Pooling)

Example: In review-sentence analysis, MIL considers the relationships between sentences within a review to predict the overall sentiment of the review.

III. Proposed Theoretical Framework

III.I. Summary of Framework



III. Proposed Theoretical Framework

III.II. PAC Learnability for Independent Bag Domain Spaces

- **Definition 7. Independent Bag Domain Space (\mathcal{D}_{XY}^{Ind})**

$$D_{XY}^{Ind} := \bigcup_{i=1}^N D_{X_{inst_i} Y} \in \mathcal{D}_{XY}^{Ind}$$

- **Theorem 2.** *If a MIL algorithm satisfies Condition 4 in \mathcal{D}_{XY}^{Ind} , it is learnable for instances.*

Condition 4. *The risk of the optimal hypothesis for D_{XY}^{Ind} must ensure that it equals the sum of the individual risks of the optimal hypotheses within D_{XY}^{Ind} :*

$$\inf_{h \in \mathcal{H}} R_{\mathcal{D}_{XY}^{Ind}} = \sum_{i=1}^N \inf R_{inst_i}$$

III. Proposed Theoretical Framework

III.III. PAC Learnability for General Bag Domain Spaces

- **Definition 8. General Bag Domain Space** ($\mathcal{D}_{XY}^{Ind} \cup \mathcal{D}_{XY}^{Dep} = \mathcal{D}_{XY}^{Gen}$)

$$D_{XY}^{Gen} = \sum_{i=1}^N \alpha_i D_{X_{inst_i} Y} \in \mathcal{D}_{XY}^{Gen} \quad \text{such that} \quad \sum_{i=1}^N \alpha_i = 1, \quad 0 \leq \alpha_i \leq 1$$

- **Theorem 3.** *If a MIL algorithm satisfies Condition 7 in \mathcal{D}_{XY}^{Gen} , it is learnable for instances.*

Condition 7. *The risk of the optimal hypothesis for D_{XY}^{Gen} must ensure that it equals the weighted sum of the individual risks of the optimal hypotheses within D_{XY}^{Gen} :*

$$\inf_{h \in \mathcal{H}} R_{\mathcal{D}_{XY}^{Gen}} = \sum_{i=1}^N \alpha_i \inf R_{inst_i} \quad \text{such that} \quad \sum_{i=1}^N \alpha_i = 1, \quad 0 \leq \alpha_i \leq 1$$

IV. Theoretical Verification of Existing Deep MILs

IV.I. Classifications of Existing Deep MIL Methodologies

- **Aggregation-level**
 - **At which stage are the values of individual instances aggregated?**
- **Attention-Target**
 - **At which stage are attention weights applied to the instances?**

Table 4: Classification of existing Deep MIL methodologies

	Instance -Pooling	Embedding -Pooling	Attention -Pooling	Additive -Pooling	Conjunctive -Pooling
Aggregation-level	Instance	Embedding	Embedding	Instance	Instance
Attention-target	None	None	Embedding	Embedding	Instance

IV. Theoretical Verification of Existing Deep MILs

IV.II. Verification Learnability for Instances by MIL Pooling Method

- **Lemma 1.** *Condition 9 serves as a necessary condition for the learnability of instances, when the hypothesis space for the i^{th} instance of a MIL algorithm is $\mathcal{H}_{inst_i} \cup \mathcal{H}_{add_i}$:*

- **Condition 9.** \mathcal{H}_{add_i} must be a subset of \mathcal{H}_{inst_i} :

$$\mathcal{H}_{inst_i} \supset \mathcal{H}_{add_i} := \{h_{add_i} : \mathcal{X}_{add_i} \rightarrow \mathcal{Y}\}$$

- **Theorem 6.** *In $\mathcal{D}_{\mathbf{XY}}^{\text{Ind}}$, MIL algorithms that perform instance-pooling are PAC learnable for instances.*
- **Theorem 7.** *MIL algorithms that perform Embedding-Pooling are not learnable for instances.*

IV. Theoretical Verification of Existing Deep MILs

IV.II. Verification Learnability for Instances by MIL Pooling Method

- **Theorem 8.** *If the MIL algorithm does not adhere to Condition 10, it is not learnable for instances.*

- **Condition 10.** *The risk R_{inst_i} for the i^{th} instance should be as follows:*

$$R_{inst_i} = \mathbb{E}_{(x_{inst_i}, y) \sim D_{X_{inst_i} Y}} \ell_{inst_i}(h, y) \quad , \text{ where } h \in \mathcal{H}_{inst_i} \cup \mathcal{H}_{bag-level_i}$$

- Attention-Pooling and Additive-Pooling is not learnable for Instances
- **Theorem 9.** *When MIL algorithms use Conjunctive-Pooling for aggregation in \mathcal{D}_{XY}^{Gen} , they are learnable for instances.*

IV. Theoretical Verification of Existing Deep MILs

IV.II. Verification Learnability for Instances by MIL Pooling Method

Table 2: Prediction performance of Deep MIL on Bags in D_{XY}^{Gen} .

		Macro-F1 Score	Micro-F1 Score	Weighted-F1 Score
Instance-Pooling	mi-Net	0.3286	0.5548	0.4550
	Causal MIL	0.2341	0.3577	0.2645
	MIREL	0.3623	0.5318	0.4372
Attention-Pooling	Attention MIL	0.7652	0.7683	0.7583
	Loss-Attention	0.7935	0.7832	0.7753
	SA-AbMILP	0.7540	0.7619	0.7562
	TransMIL	0.7834	0.7711	0.7738
Additive-Pooling	Additive MIL	0.5314	0.6341	0.5732
Conjunctive-Pooling	Conjunctive MIL	0.7544	0.7701	0.7683
None-Pooling	Fully Connected Layer	0.7704	0.7724	0.7714

IV. Theoretical Verification of Existing Deep MILs

IV.II. Verification Learnability for Instances by MIL Pooling Method

Table 3: Prediction performance comparison of MIL algorithms on bags and instances.

	Performance of Bags (PB)		Performance of Instances (PI)		PI - PB	
	Macro-F1	AUROC	Macro-F1	AUROC	Macro-F1	AUROC
Attention MIL	0.8434	0.9516	0.3215	0.7317	-0.5219	-0.2199
Loss-Attention	0.8228	0.9574	0.4797	0.7951	-0.3431	-0.1623
SA-AbMILP	0.7692	0.9552	0.3340	0.5464	-0.4352	-0.4088
TransMIL	0.8515	0.9622	0.2192	0.5369	-0.6323	-0.4253
Additive MIL	0.4776	0.9181	0.2320	0.8092	-0.2456	-0.1089
Conjunctive MIL	0.7916	0.9463	0.6430	0.9516	-0.1486	+0.0053

IV. Theoretical Verification of Existing Deep MILs

IV.III.I. Rethinking Position Dependencies of Instances on Deep MILs

- **Theorem 10.** *If the MIL algorithm extracts features of instances through RNN-based neural networks for aggregation, it is unable to learn from instances.*
- **Theorem 11.** *If the hypothesis space $\mathcal{H}_{Pos-Encode_i}$ generated through positional encoding values for the i -th position of the MIL algorithm is not a subset of \mathcal{H}_{inst_i} , then the algorithm is not PAC learnable for instances.*

Table 4: Test positional dependencies for WebTraffic datasets

	Default	PE (All)	<u>PE (Att)</u>	PE (Predict)	RNN (All)	<u>RNN (Att)</u>	RNN (Predict)
AOPCR	13.041	12.372	<u>14.555</u>	12.256	9.011	17.502	12.210
NDCG@n	0.676	0.665	0.727	0.642	0.620	<u>0.714</u>	0.523

IV. Theoretical Verification of Existing Deep MILs

IV.III.II. Instance Learnability for Multi-dimensional Deep MILs

- **Multi-Dimensional(MD) MIL predicts multi-dimensional instances using a top-level bag label.**
- **MD-instances should consider relationships with other dimensions.**
- **Conjunctive-Pooling, reflecting MD relationships through attention, showed the best performance.**

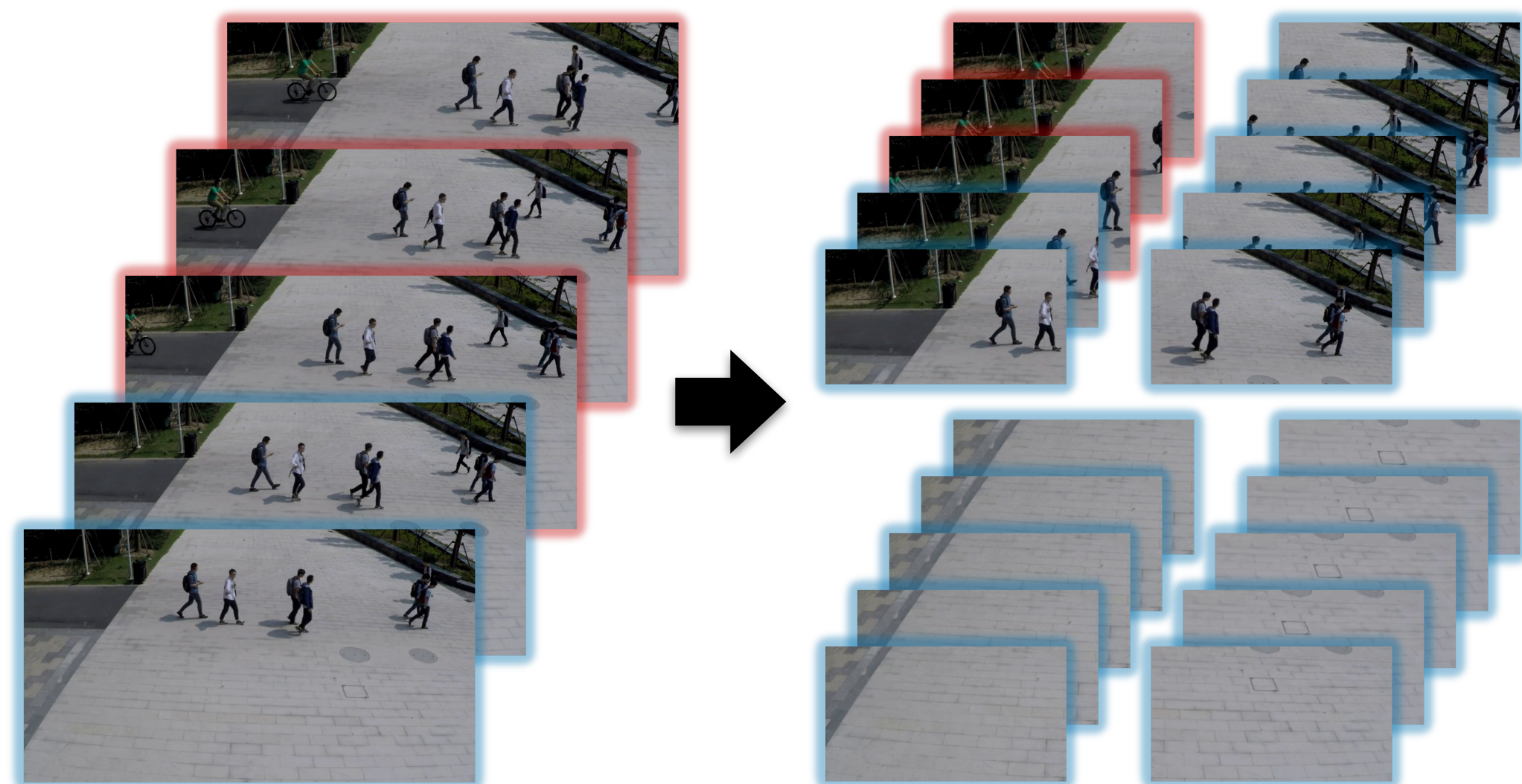


Table 4: Predicted performance for Snippets (i.e., bags) and patches (i.e., instances) of MD-MIL.

	None-Attention	Attention	Cross-Attention
Snippet (Bag)	0.87	0.88	0.91
Patch (Instance)	0.85	0.85	0.91

V. Conclusions

- **This study proposes a theoretical framework that defines the necessary conditions for an MIL algorithm to achieve learnability at the instance level, assuming Assumption 1 is satisfied.**
- **The framework is expected to benefit various domains where instance-level learnability is critical.**
 - **Although MIL is actively utilized in domains with limited labeling, such as medical applications, most research has focused on bag-level performance, primarily relying on Attention-Pooling methods.**
- **Future theoretical and experimental validations regarding positional dependencies and MD-MIL are anticipated to support further advancements in MIL research.**

Thank You

