

DeepUQ: Assessing the Aleatoric Uncertainties from two Deep Learning Methods



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DEEP SKIES

Bringing Artificial Intelligence to Astrophysics



arXiv

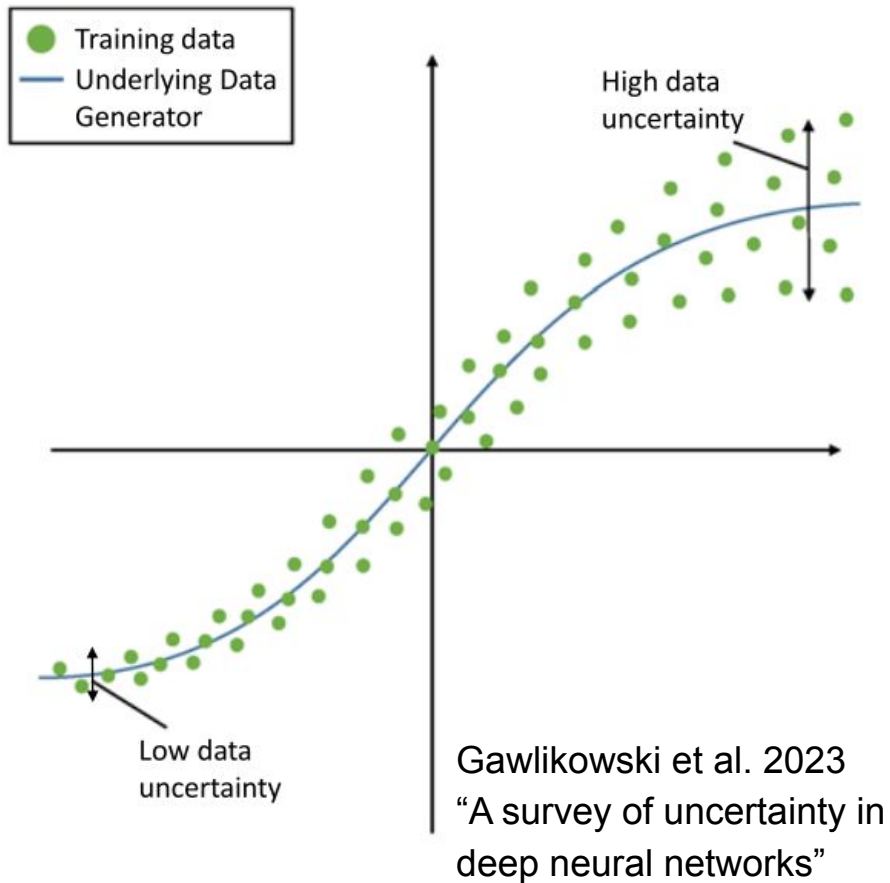


paper repo

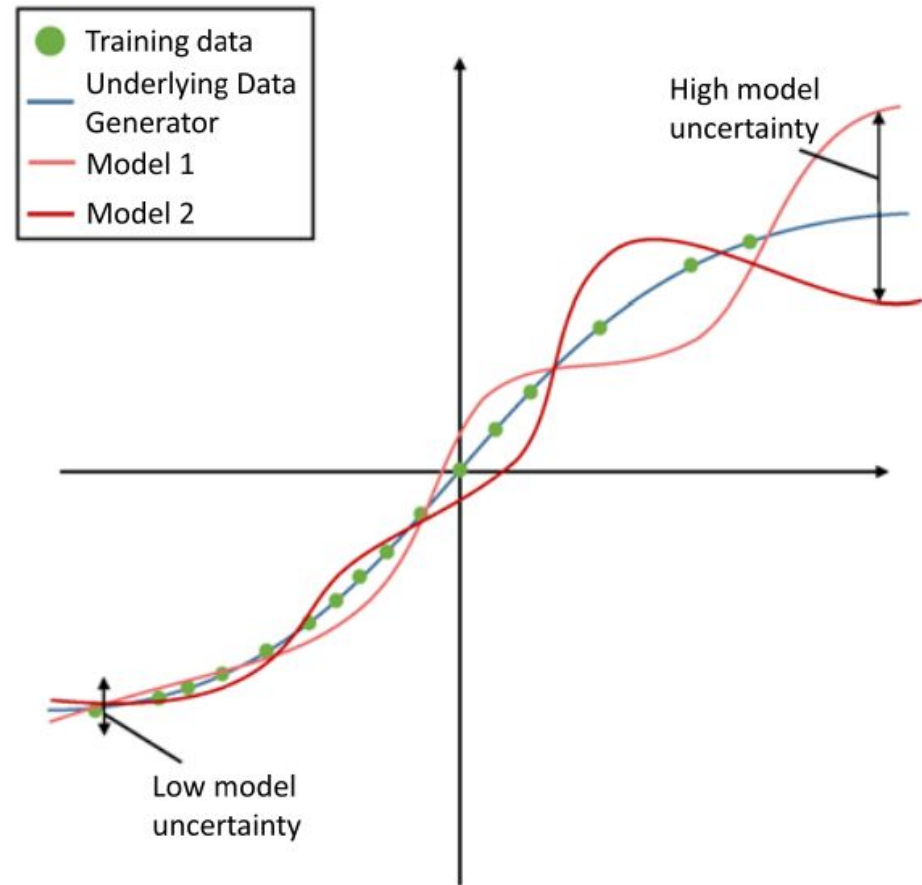


DeepUQ pypi

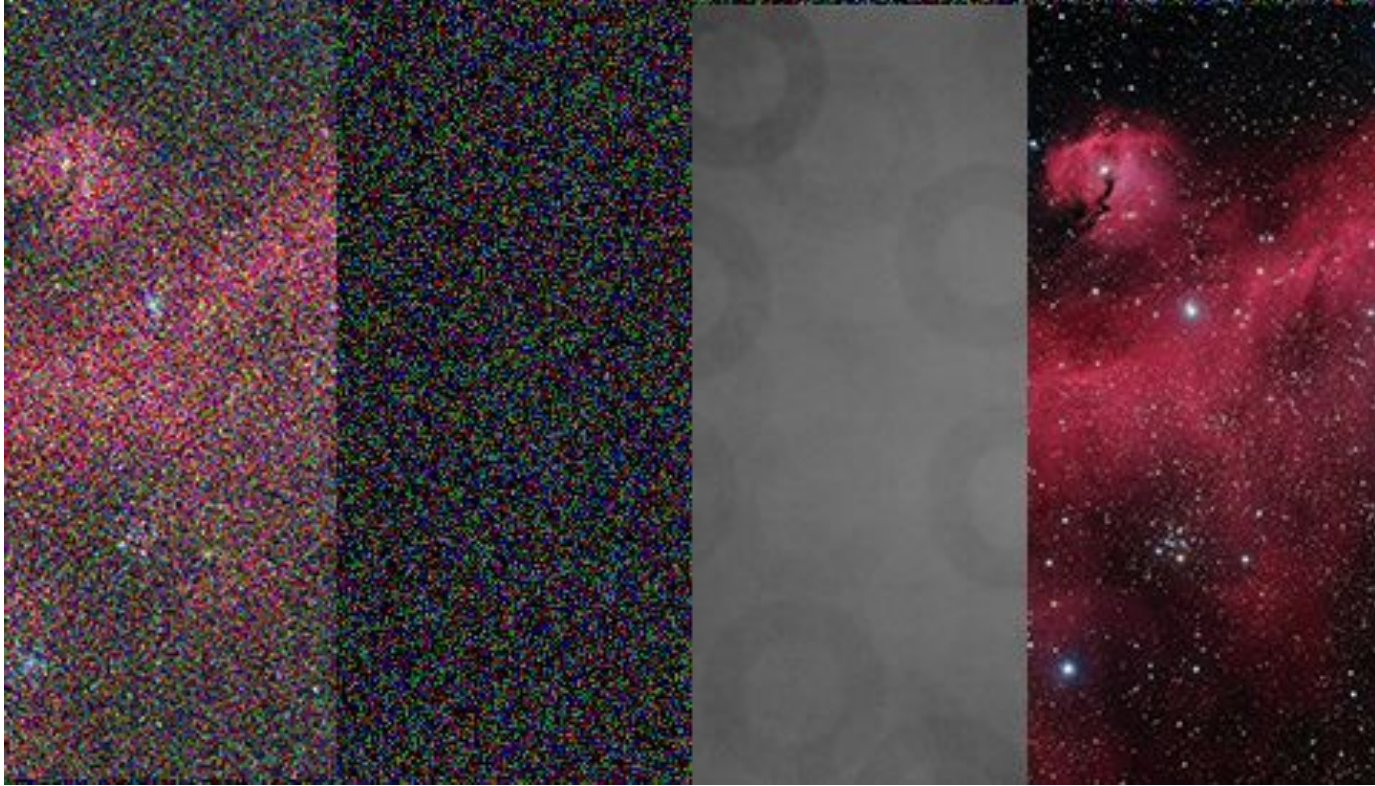
I focus on **aleatoric** (data) uncertainty



Other work focuses on **epistemic** (model) uncertainty

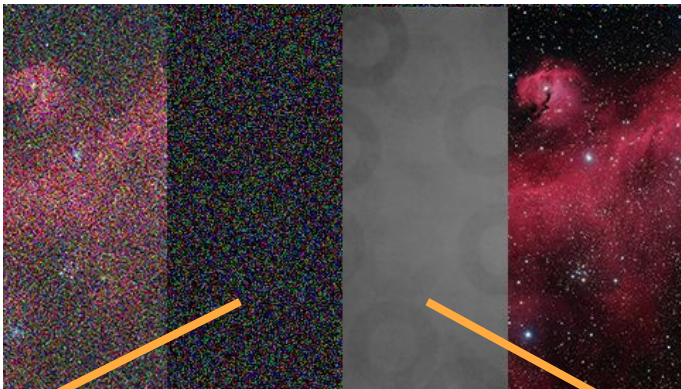


Aleatoric uncertainty is important in many physics and astrophysics applications, i.e., Poisson or Gaussian noise in astrophysics

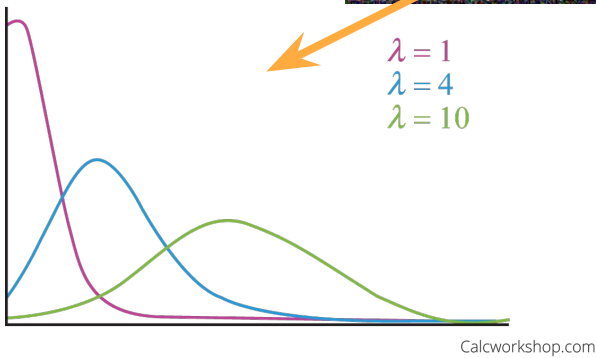


Sky and Telescope: Richard Wright

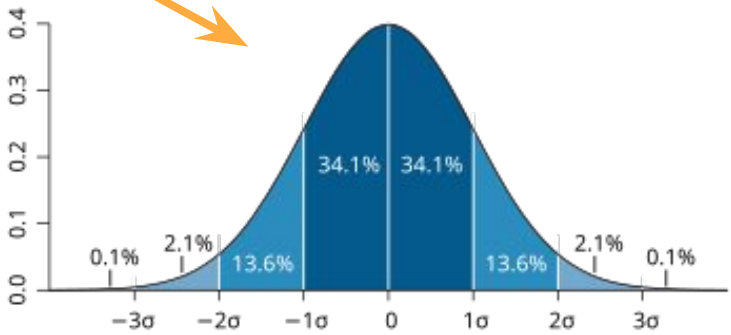
Deep learning or non deep learning methods *should* predict uncertainties that match these known distributions



Poisson

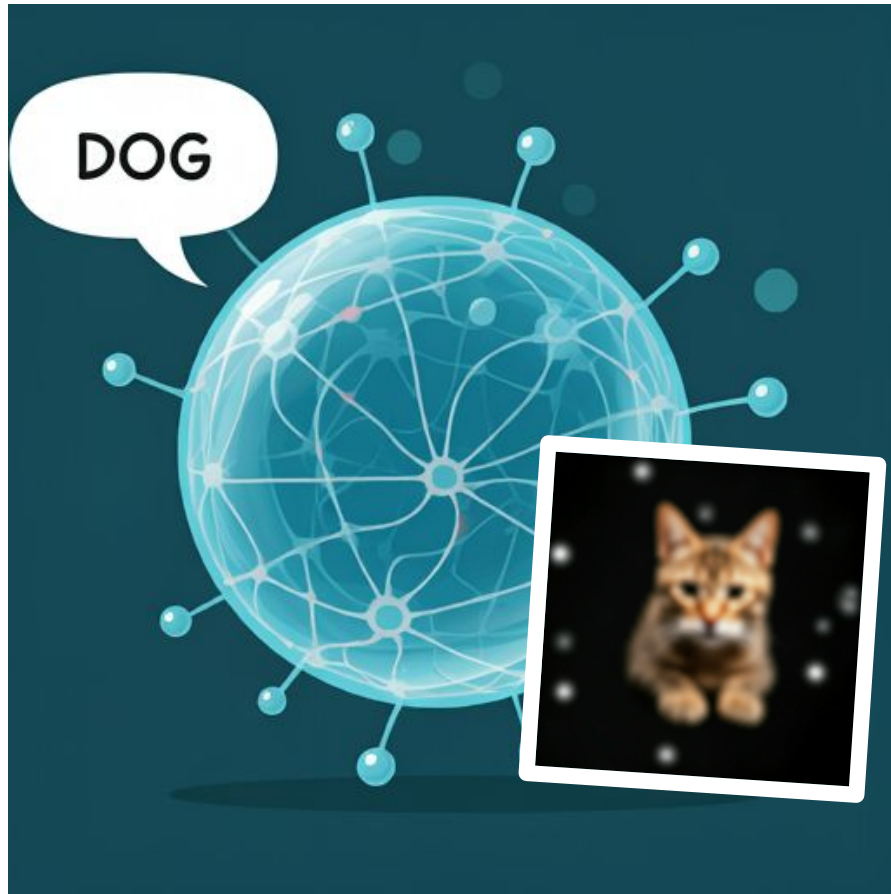


Gaussian / Normal

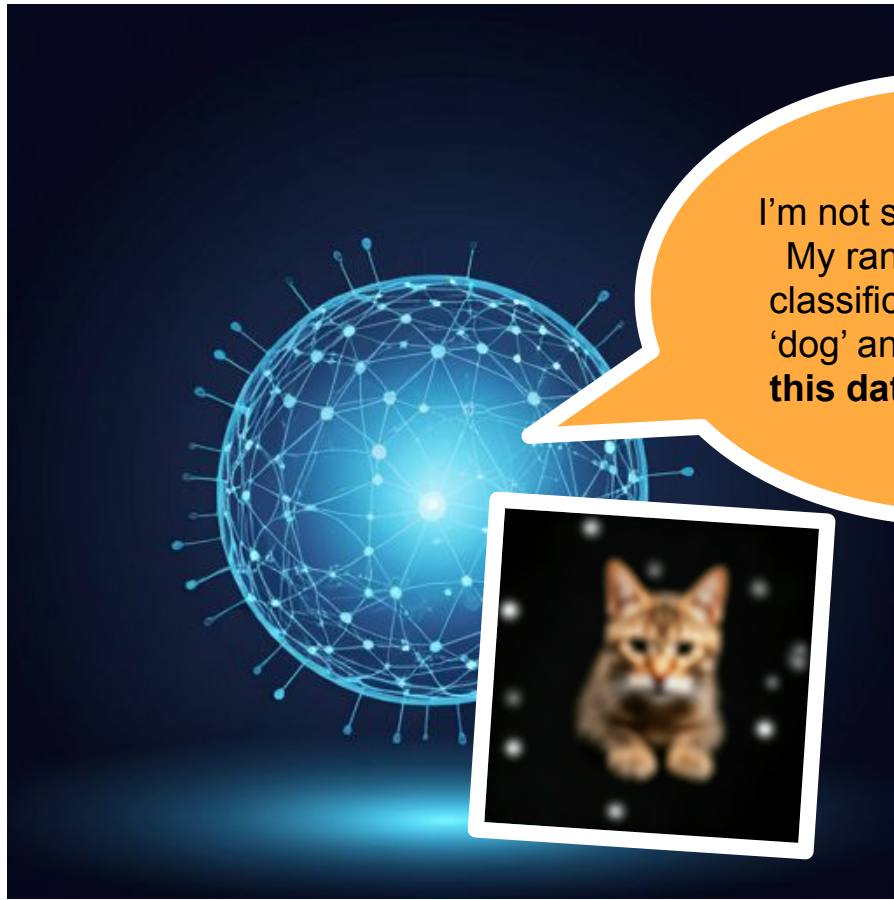


Gen AI image



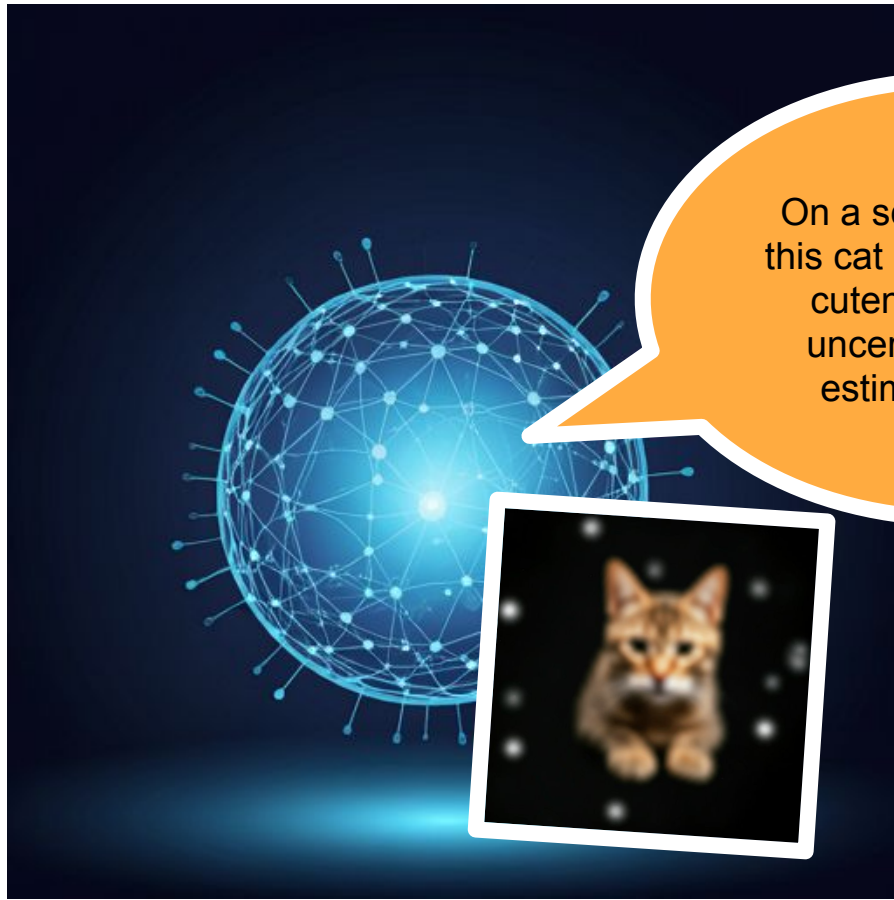


Gen AI image



I'm not sure what this is.
My range of possible
classifications includes
'dog' and 'cat' because
this data is very noisy.

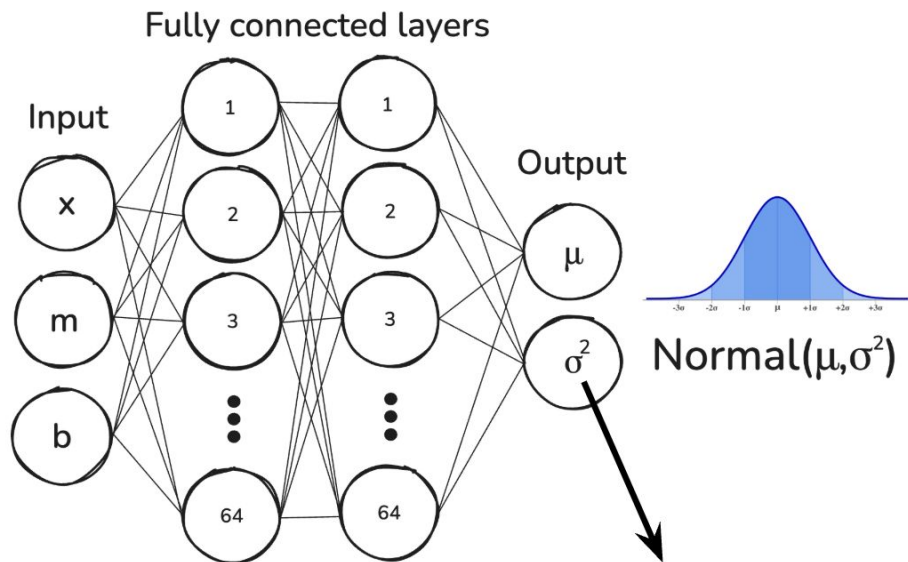
Gen AI image



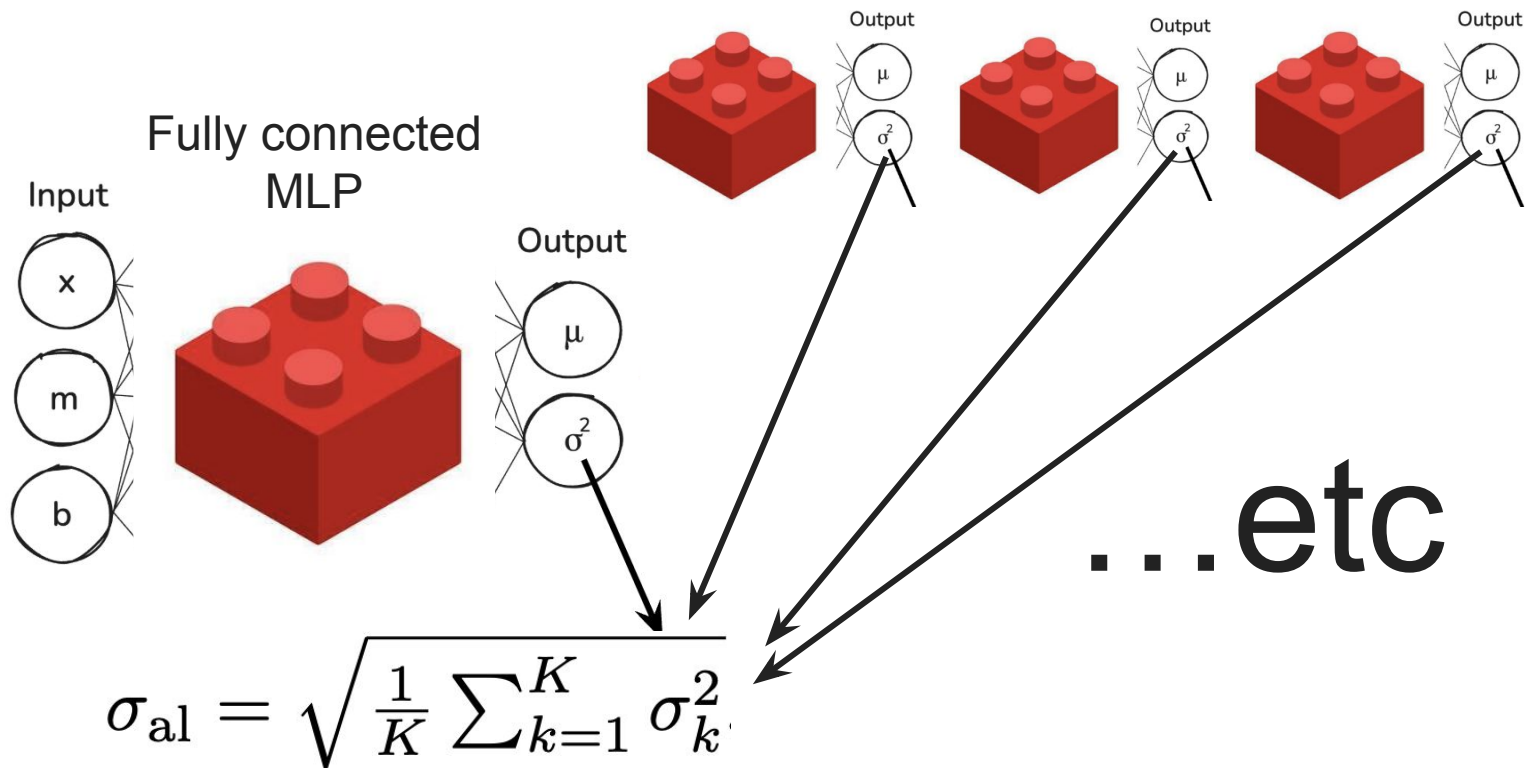
On a scale of 1 to 10, this cat has an average cuteness of 8; the uncertainty on this estimate is ± 2 .

Gen AI image

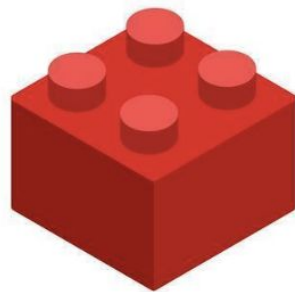
Mean variance estimation networks (MVEs) predict **aleatoric uncertainty** via their two output nodes (mean and variance)



The aleatoric uncertainty for a Deep Ensemble (of many MVEs) is the average of the predicted standard deviations



Deep Evidential Regression predicts aleatoric uncertainty using a normal-inverse-gamma loss



Output

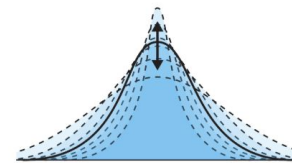
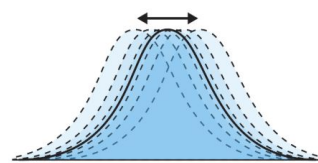
γ

ν

α

β

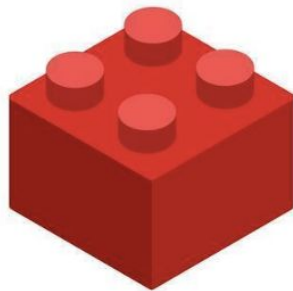
$(\mu, \sigma^2) \sim$ Evidential Prior



Amini+2020 "Deep Evidential Regression"

$$\sigma_{\text{al}} \equiv w_{\text{St}} = \sqrt{\frac{\beta(1+\nu)}{\alpha\nu}}$$

Deep Evidential Regression predicts aleatoric uncertainty using a normal-inverse-gamma loss



Output

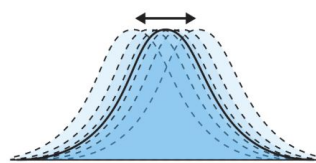
γ

ν

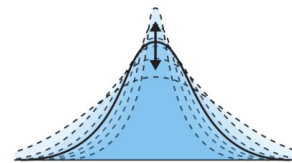
α

β

$(\mu, \sigma^2) \sim$ Evidential Prior



$$\mu \sim \mathcal{N}(\gamma, \sigma^2/\nu)$$



$$\sigma^2 \sim \Gamma^{-1}(\alpha, \beta)$$

Amini+2020 "Deep Evidential Regression"

$$\sigma_{\text{al}} \equiv w_{\text{St}} = \sqrt{\frac{\beta(1+\nu)}{\alpha\nu}}$$

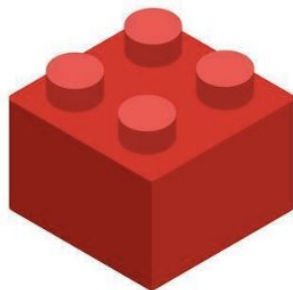
Deep Evidential Regression predicts aleatoric uncertainty using a normal-inverse-gamma loss

distribution

distribution



Deep Evidential
Regression



Output

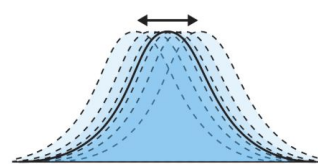
γ

ν

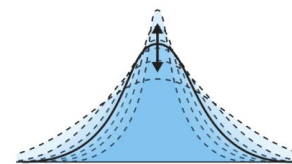
α

β

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$$\mu \sim \mathcal{N}(\gamma, \sigma^2/\nu)$$

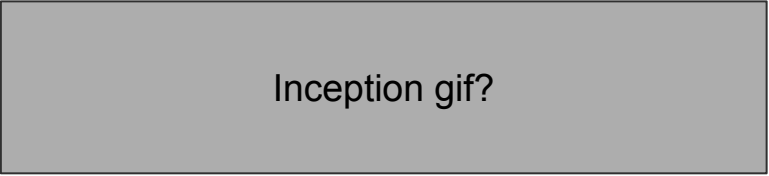


$$\sigma^2 \sim \Gamma^{-1}(\alpha, \beta)$$

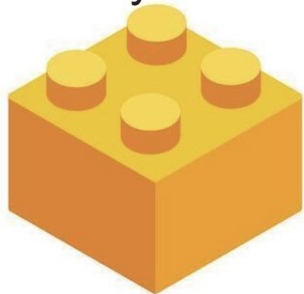
Amini+2020 "Deep Evidential Regression"

$$\sigma_{\text{al}} \equiv w_{\text{St}} = \sqrt{\frac{\beta(1+\nu)}{\alpha\nu}}$$

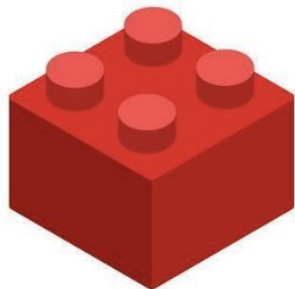
Deep Evidential Regression predicts aleatoric uncertainty using a normal-inverse-gamma loss



Convolutional
Layers



Fully connected
MLP



Output

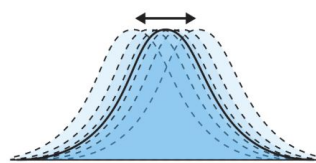
γ

ν

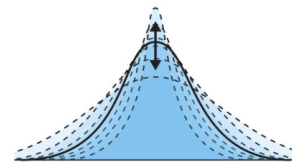
α

β

$(\mu, \sigma^2) \sim$ Evidential Prior



$$\mu \sim \mathcal{N}(\gamma, \sigma^2/\nu)$$



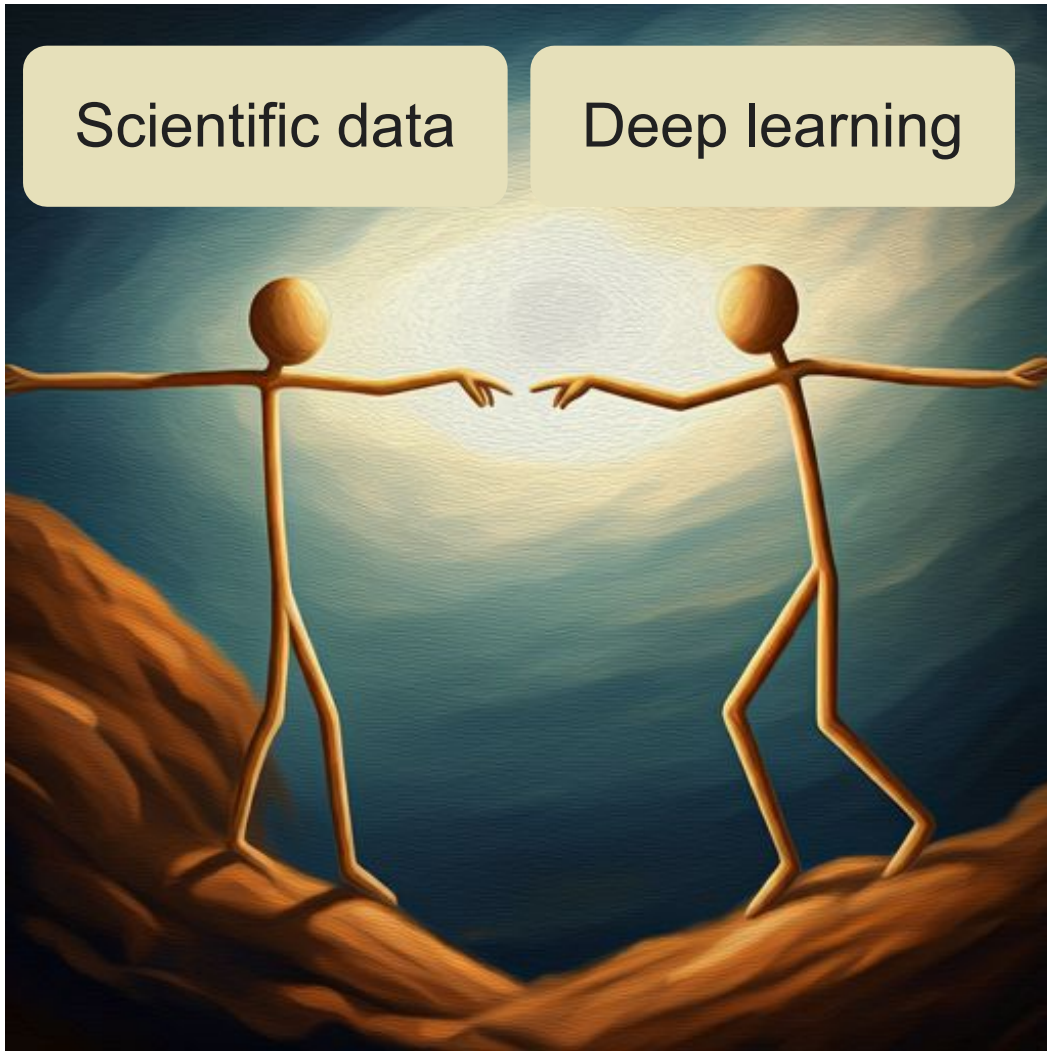
$$\sigma^2 \sim \Gamma^{-1}(\alpha, \beta)$$

Amini+2020 "Deep Evidential Regression"

$$\sigma_{\text{al}} \equiv w_{\text{St}} = \sqrt{\frac{\beta(1+\nu)}{\alpha\nu}}$$

Scientific data

Deep learning



Gen AI image

Other work offers comparisons of different UQ techniques

Compare aspects of predictive uncertainty distributions (but not the exact uncertainty value):

Scalia et al. 2019 “Evaluating Scalable Uncertainty Estimation Methods for DNN-Based Molecular Property Prediction.”

Tran et al. 2019 “Methods for comparing uncertainty quantifications for material property predictions.”

A toolbox for comparing UQ methods (but not the exact uncertainty value):

Chung et al. 2021 “Uncertainty Toolbox: an Open-Source Library for Assessing, Visualizing, and Improving Uncertainty Quantification.”

Compares exact aleatoric uncertainties (but not for a variety of data types):

Caldeira & Nord 2020 “Deeply Uncertain: Comparing Methods of Uncertainty Quantification in Deep Learning Algorithms.”

Uses a variety of data types and uncertainty injection (but does not compare exact uncertainty values):

Bramlage et al. 2023. “Plausible uncertainties for human pose regression”

Uncertainty Menu

To generate the 12 total experimental datasets, there are three categories.

Uncertainty Menu

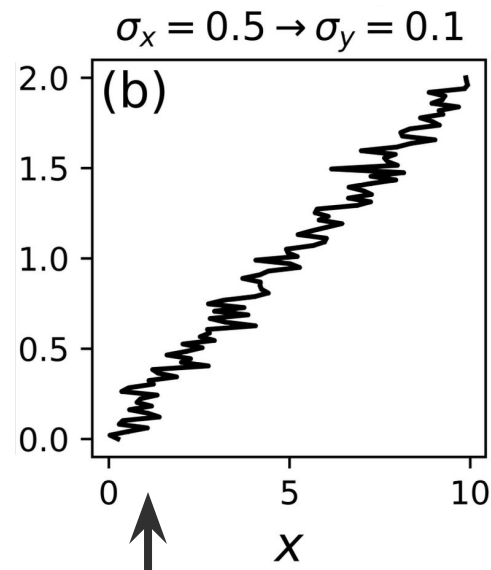
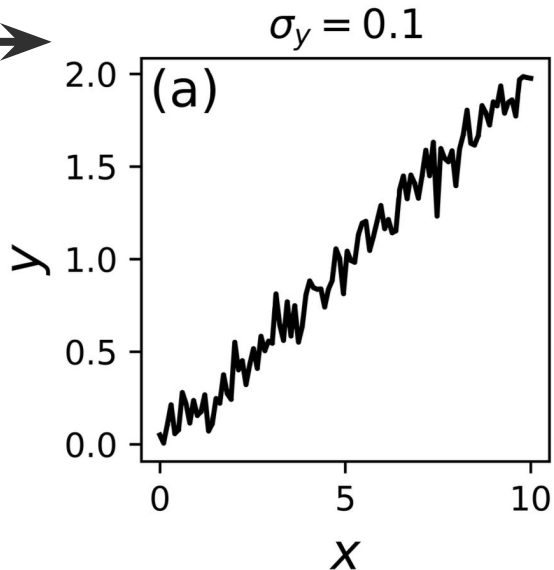
To generate the 12 total experimental datasets, there are three categories.

Injection

Output variable



Input variable



Uncertainty Menu

To generate the 12 total experimental datasets, there are three categories.

Injection

Output variable

Input variable

Dimensionality

0D: Tabular

2D: Imaging

Noise level

Low ($\sigma_Y = 0.01$)

Medium ($\sigma_Y = 0.05$)

High ($\sigma_Y = 0.1$)

Uncertainty Menu

Below I show two options for selecting from each category.

Injection

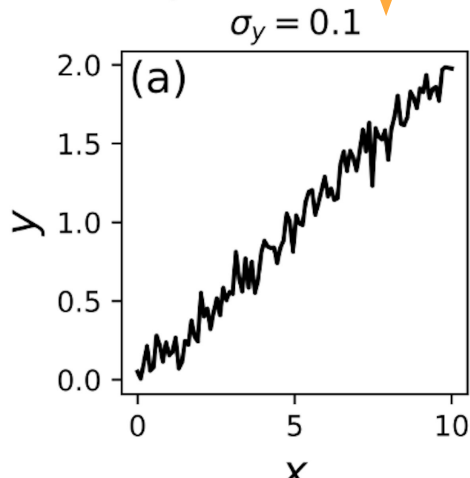
Output variable
Input variable

Dimensionality

0D: Tabular
2D: Imaging

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Uncertainty Menu

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Injection

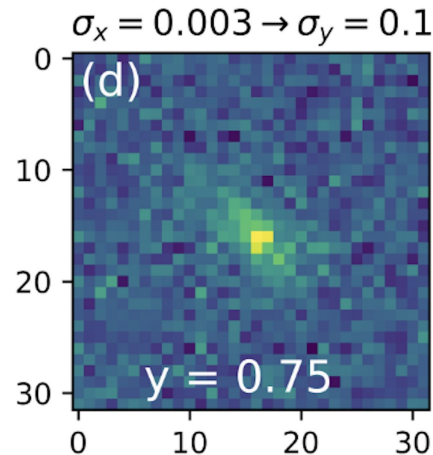
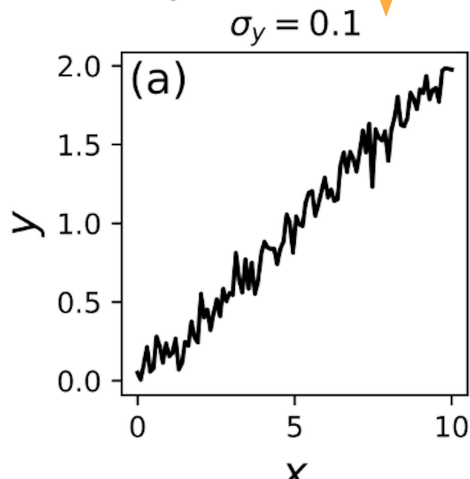
Output variable
Input variable

Dimensionality

0D: Tabular
2D: Imaging

Noise level

Low ($\sigma_Y = 0.01$)
Medium ($\sigma_Y = 0.05$)
High ($\sigma_Y = 0.1$)



I use DeepBench
to generate the
galaxy images.

Uncertainty Menu

For uncertainty on the input variable, I inject the uncertainty directly on the input and propagate it to the output variable.

Injection

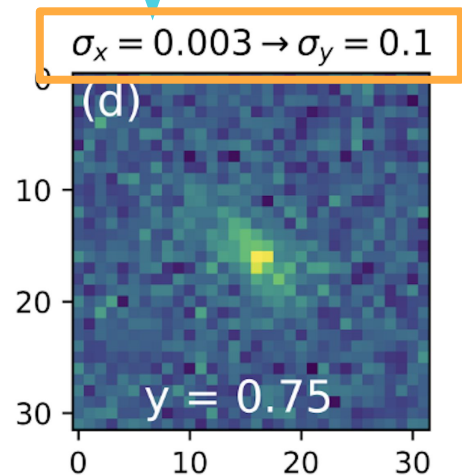
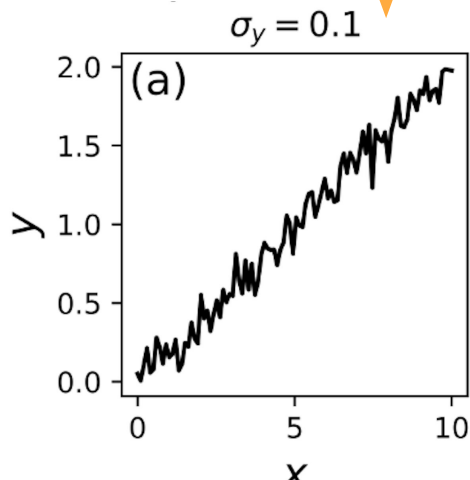
Output variable
Input variable

Dimensionality

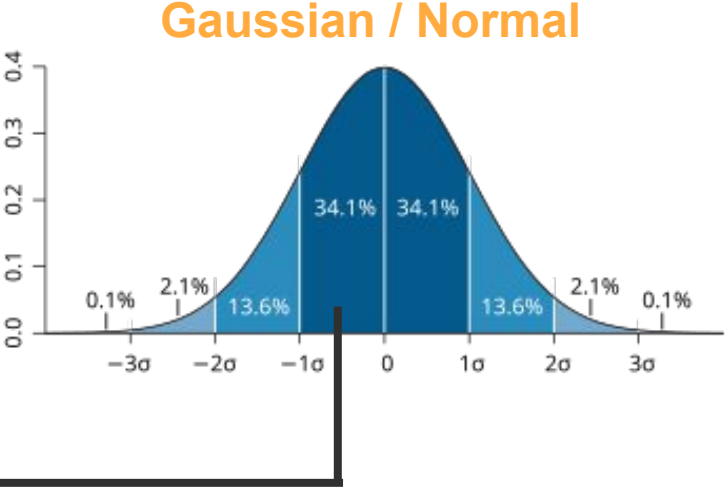
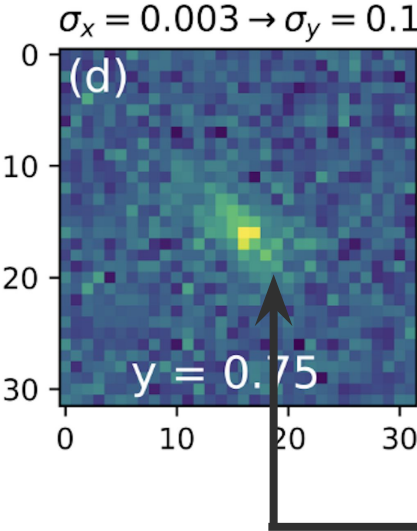
0D: Tabular
2D: Imaging

Noise level

Low ($\sigma_Y = 0.01$)
Medium ($\sigma_Y = 0.05$)
High ($\sigma_Y = 0.1$)



The uncertainty is injected for all data via a homoskedastic Gaussian distribution



i.e., the uncertainty is added to each pixel via a draw from a random normal with standard deviation $\sigma_x = 0.1$

Uncertainty Menu

Below I show two options for selecting from each category.

Injection

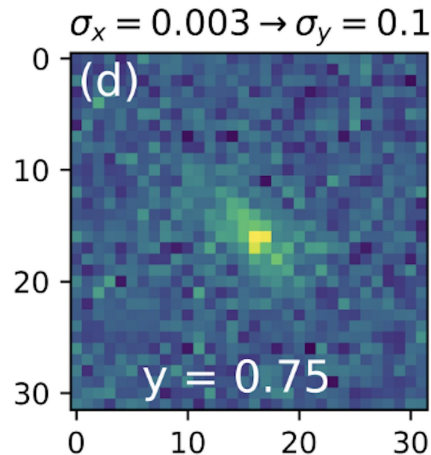
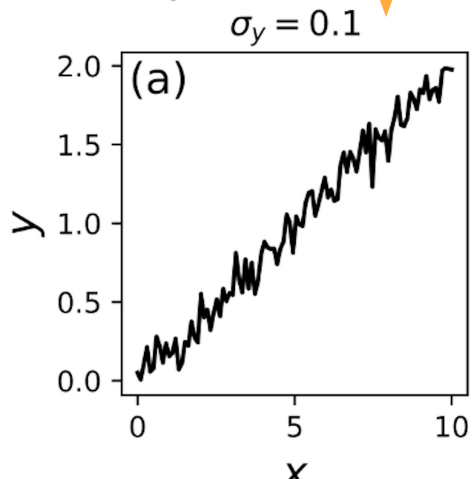
Output variable
Input variable

Dimensionality

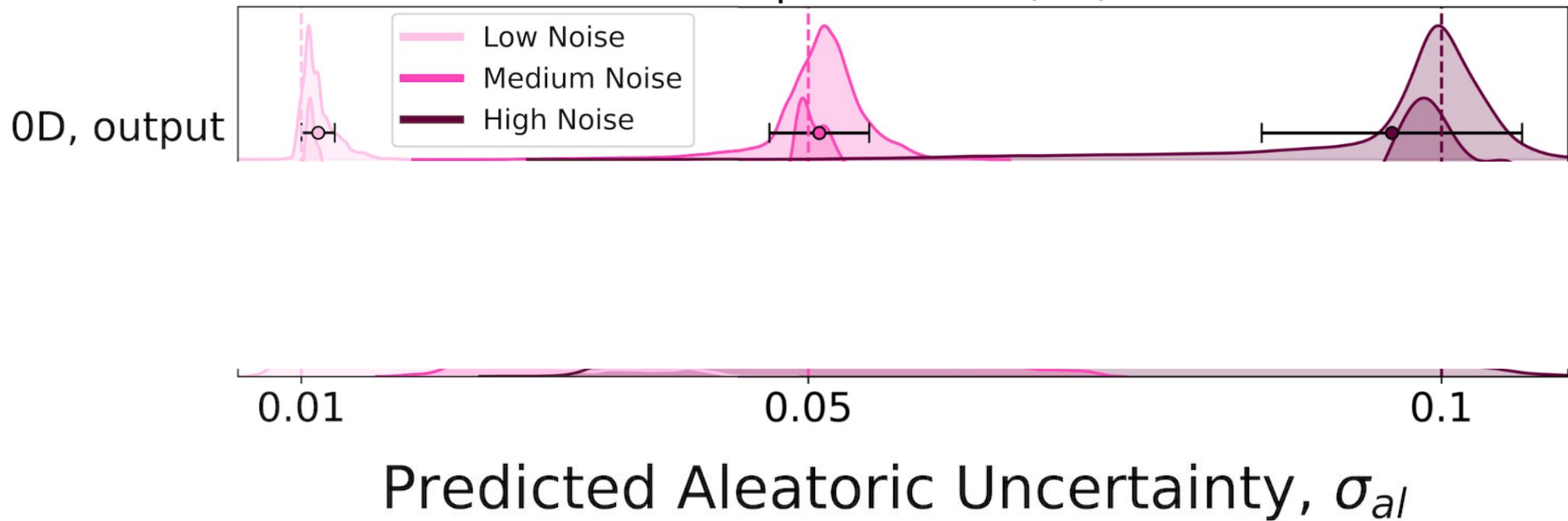
0D: Tabular
2D: Imaging

Noise level

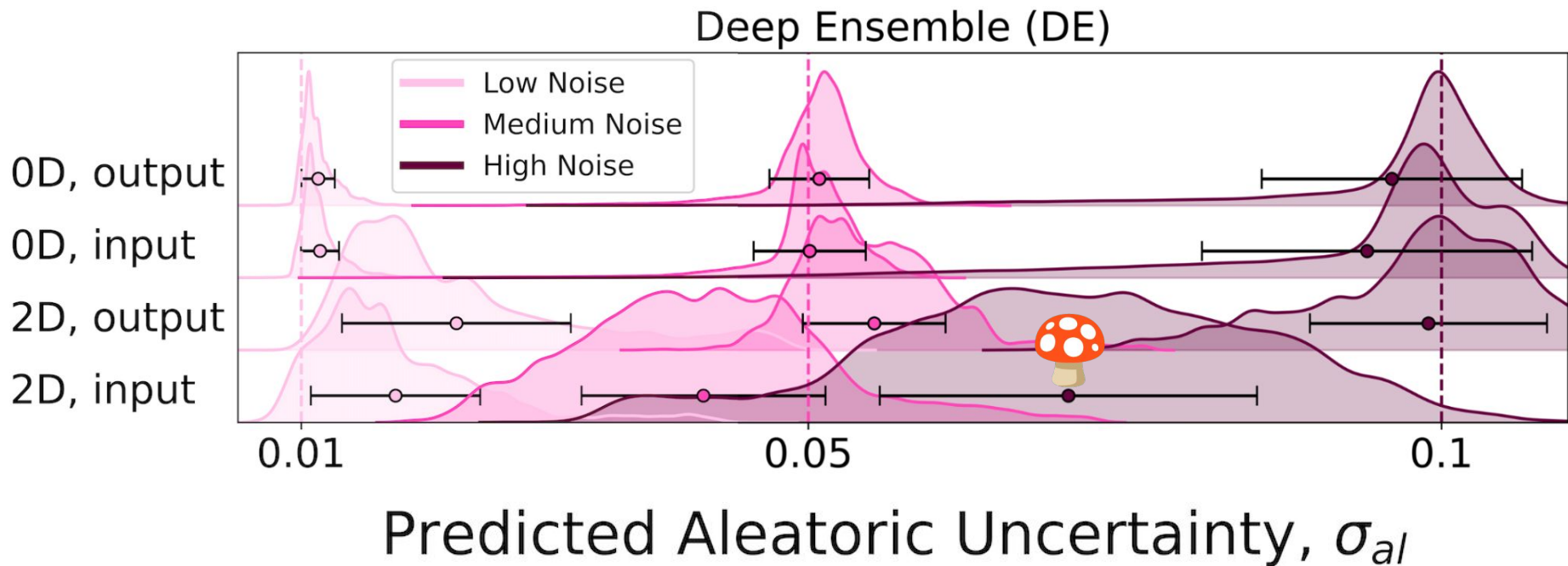
Low ($\sigma_Y = 0.01$)
Medium ($\sigma_Y = 0.05$)
High ($\sigma_Y = 0.1$)



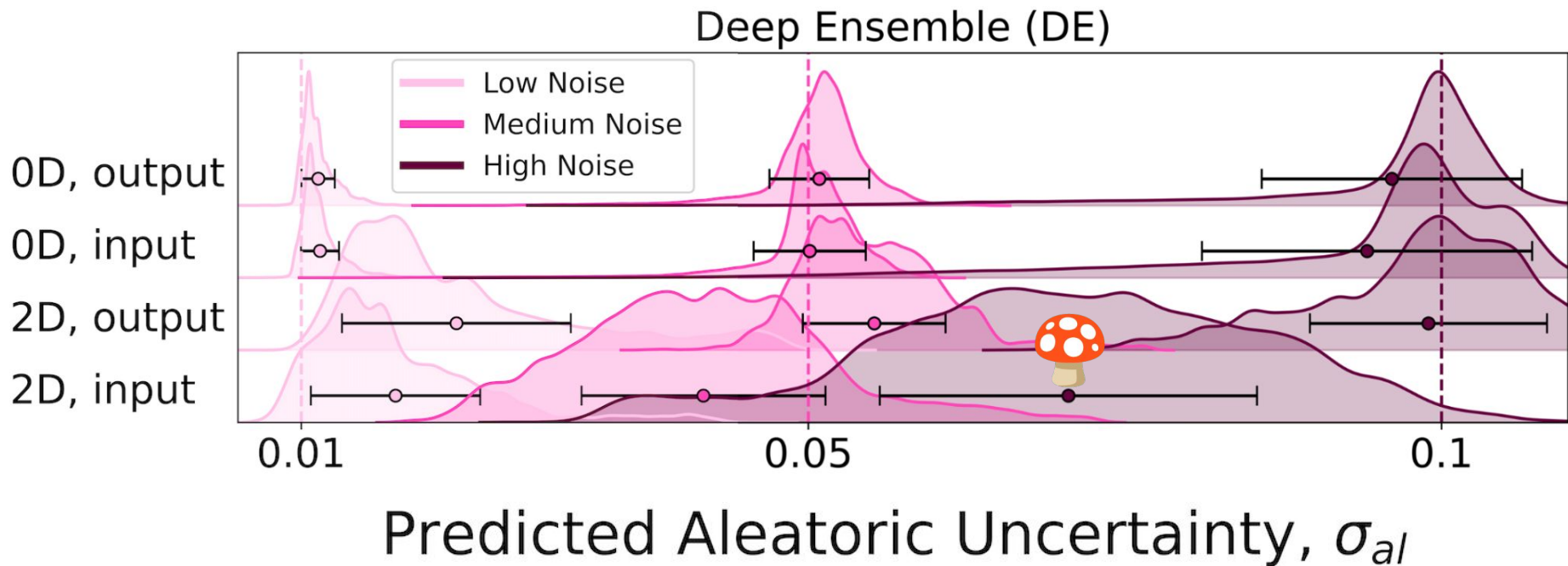
Deep Ensemble (DE)



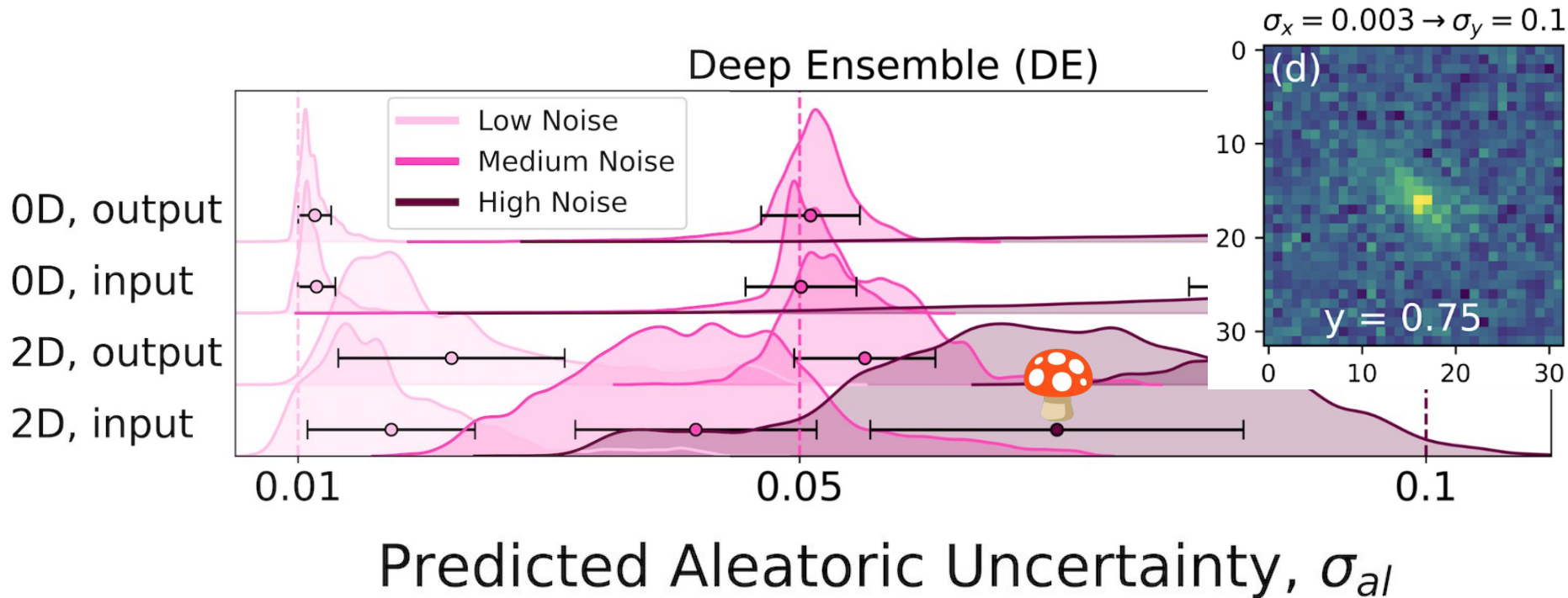
5 out of 12 experiments are miscalibrated for the Deep Ensemble



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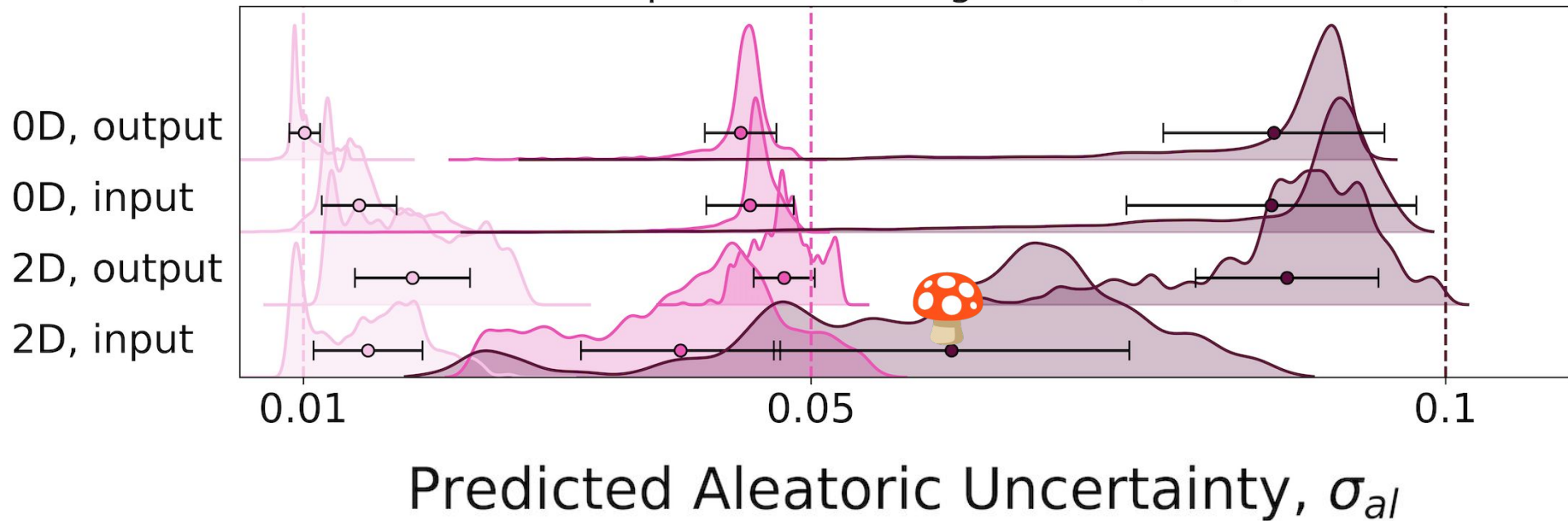


5 out of 12 experiments are miscalibrated for the Deep Ensemble

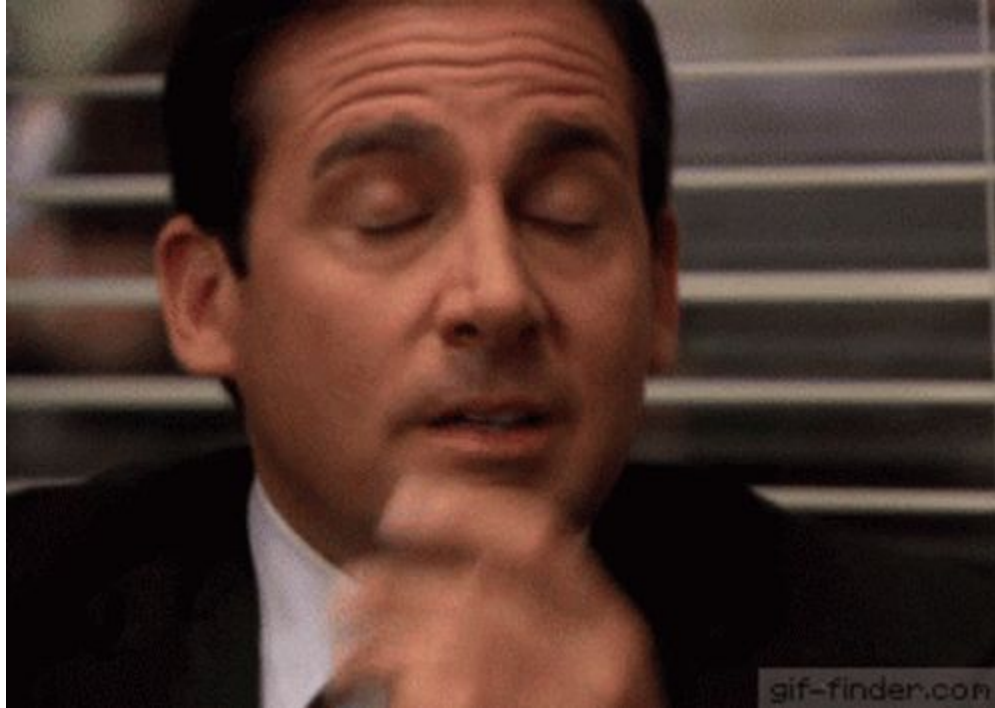


10 out of 12 experiments are miscalibrated for the Deep Evidential Regression

Deep Evidential Regression (DER)



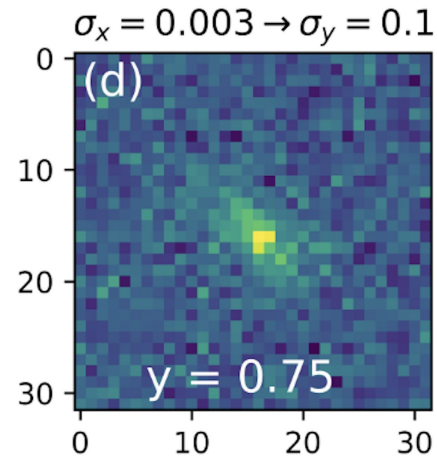
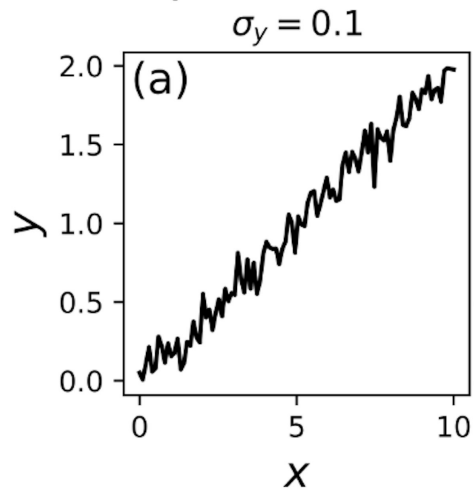
Both models are **overconfident** in most experiments; the Deep Evidential Regression is slightly worse



This problem is worse for higher dimensional (images) and higher noise data!



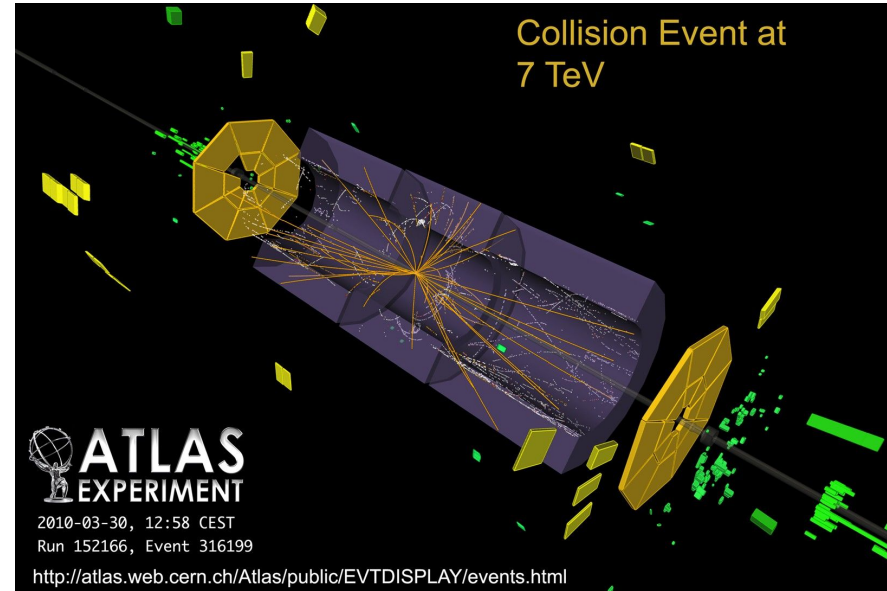
Caveat: All the results presented here apply only to the (simplistic) set of experiments



Real world data can be even messier and more uncertain

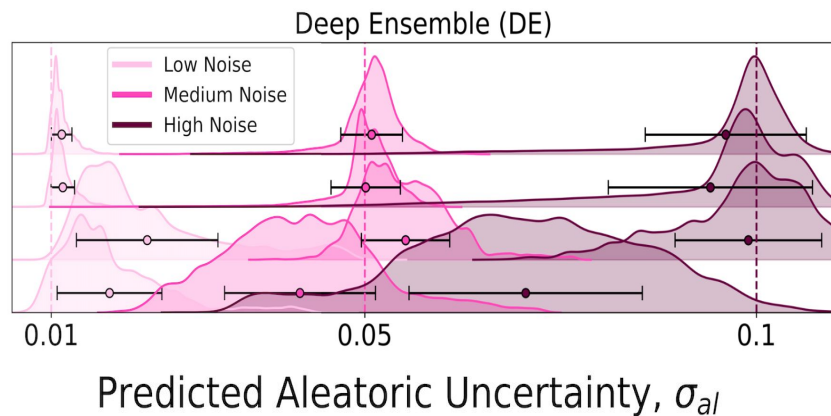
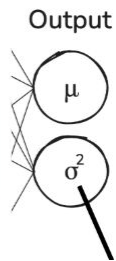
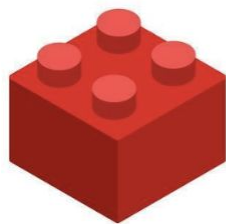
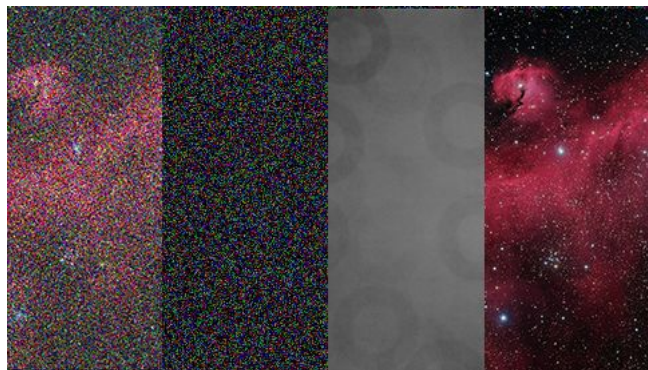


Credit: Science: NASA, ESA, CSA,
Tommaso Treu (UCLA); Image
Processing: Zolt G. Levay (STScI)

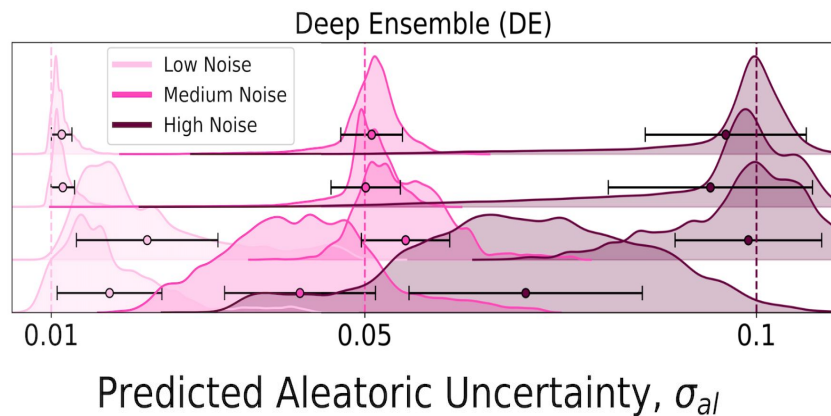
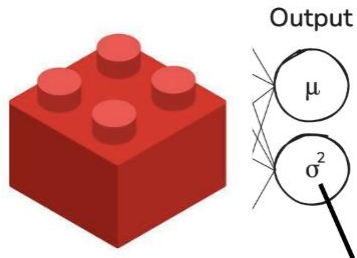
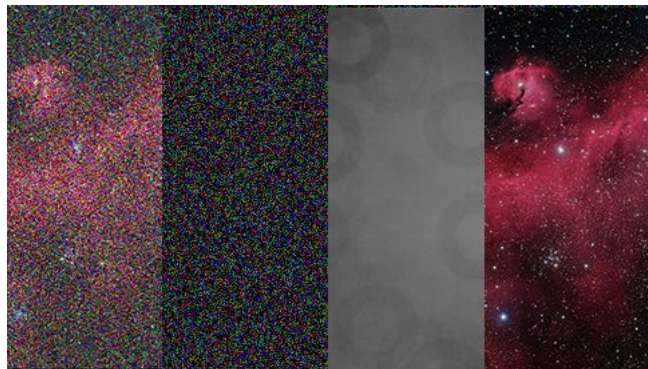


ATLAS Collaboration, CERN
Particle data are in tabular format

Conclusion: Scientific imaging and other datasets offer a great opportunity to test UQ methods (DE and DER); we find that they are mostly miscalibrated in aleatoric uncertainty prediction for this set of experiments.



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arXiv



paper repo



DeepUQ pypi

Bonus slides

Concerns for the field of UQ:

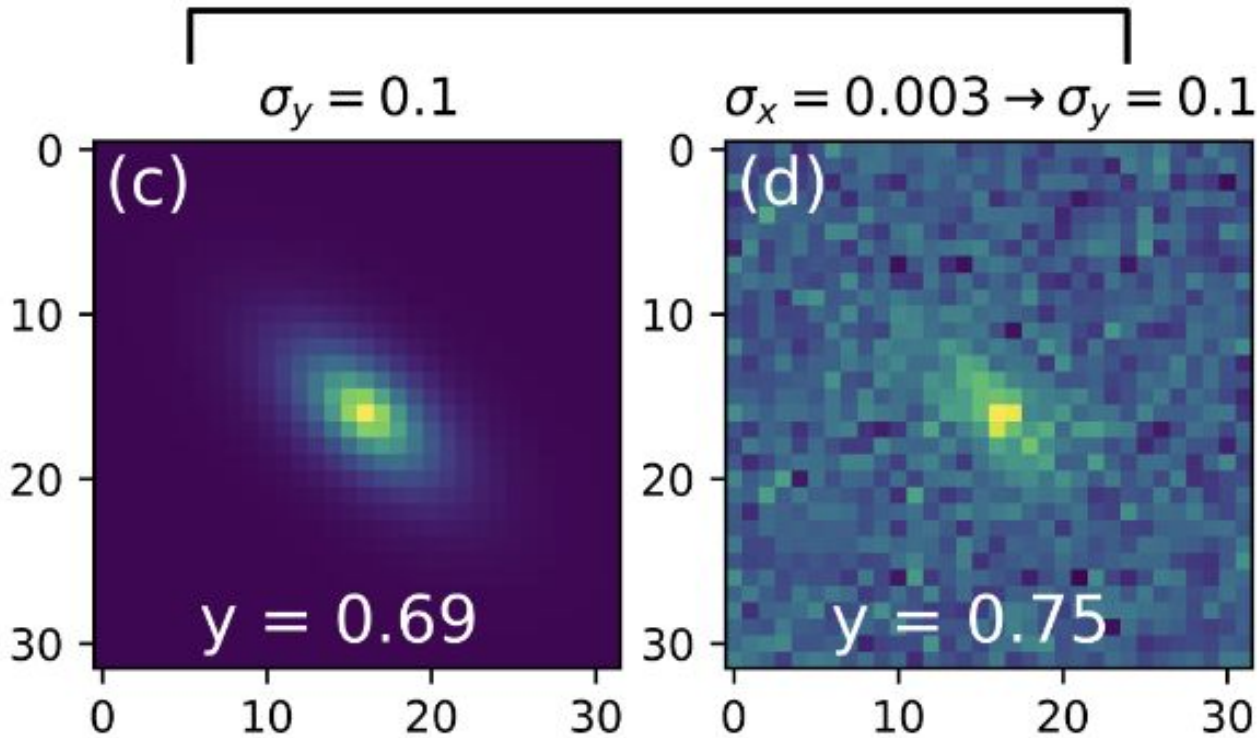
- Taxonomies are confusing/conflicting, how do we define different types of uncertainties? Aleatoric, epistemic, oh my!
- Independence of uncertainty types should be questioned (is aleatoric independent from epistemic? Is there more overlap that we're currently considering?)
- Are notions of uncertainty in physics/astronomy/science aligning with the deep learning science on uncertainty quantification? What work is to be done?



What do we need?

- Standardized datasets with known uncertainties to test the performance of these UQ methods
- ^More complex versions of this
- Expanding this sort of work to epistemic uncertainties

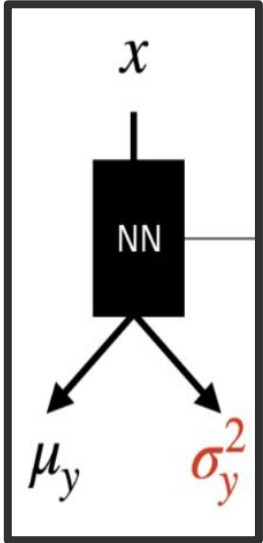
2D Data



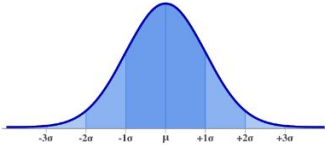
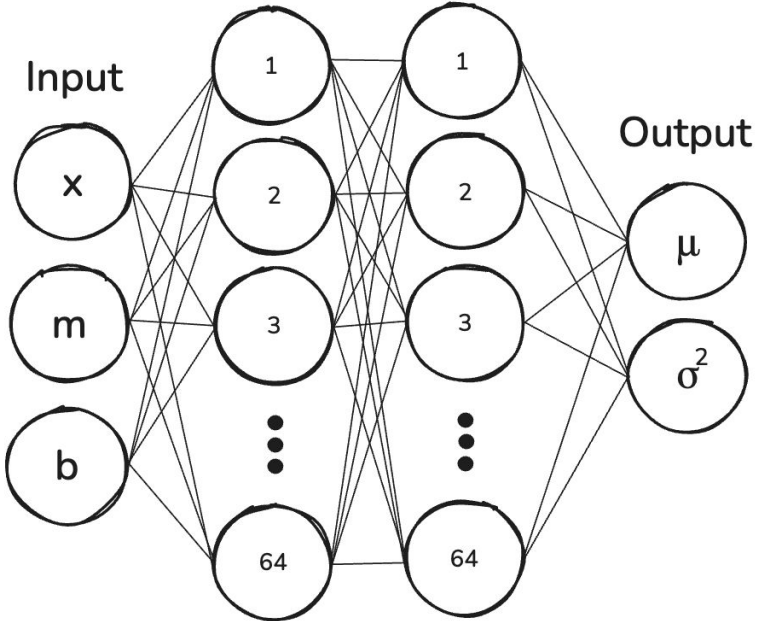
Output variable

Input variable

Fully connected layer architecture is simple

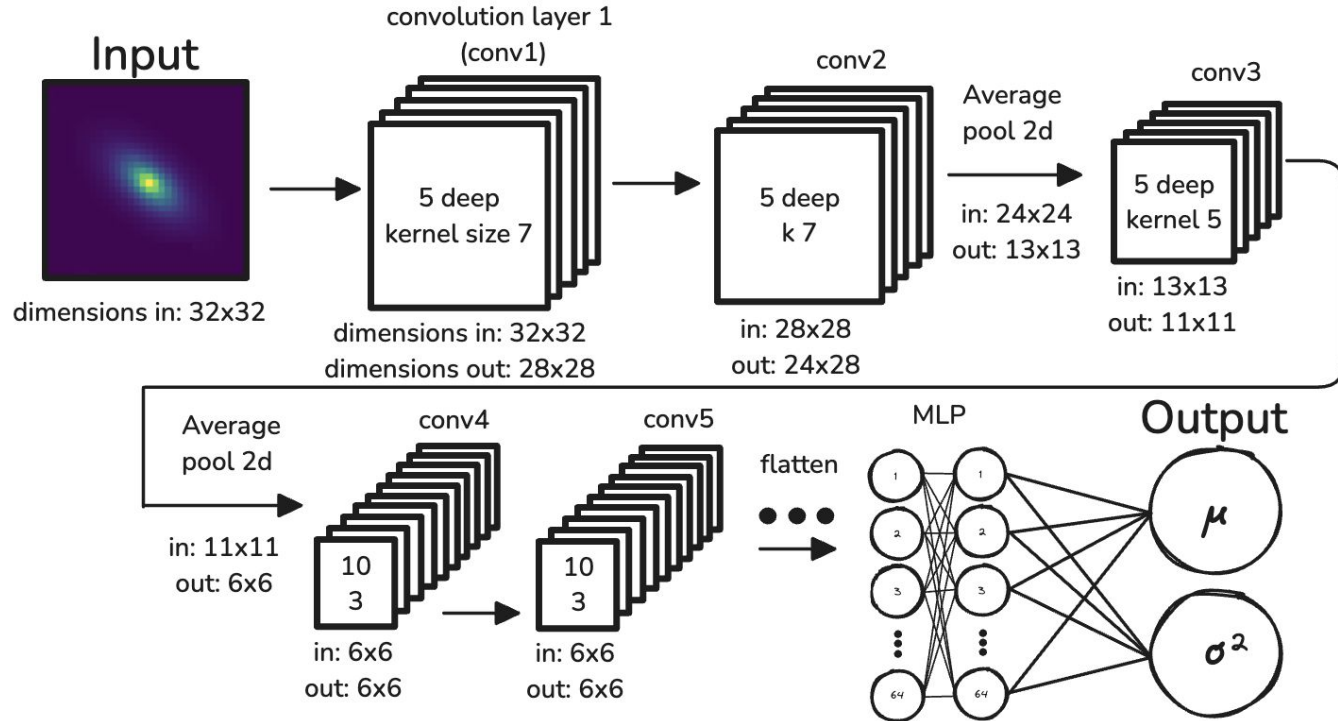


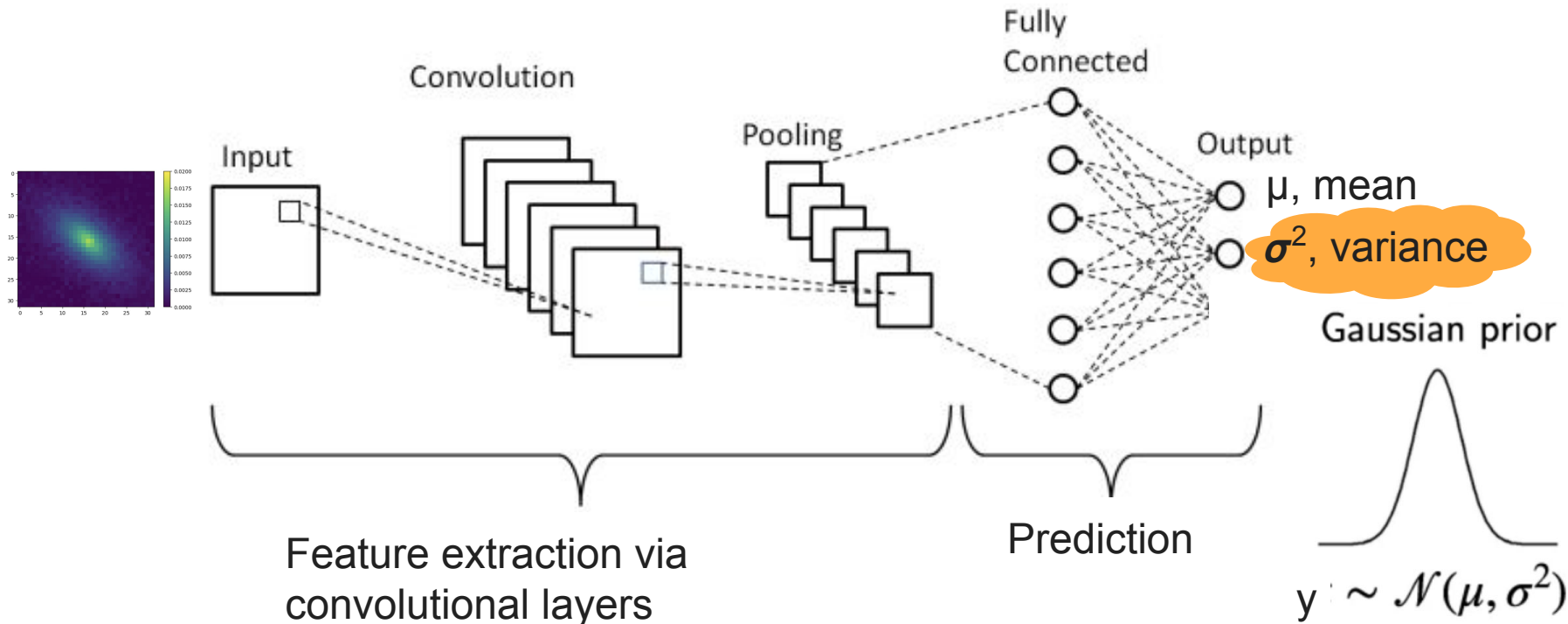
Fully connected layers



Normal(μ, σ^2)

The CNN architecture adds convolutional layers on top of the existing MLP





Questions like how does the uncertainty itself behave, does it reproduce the expected profile?