RL for Mitigating Cascading Failures: Targeted Exploration via Sensitivity Factors

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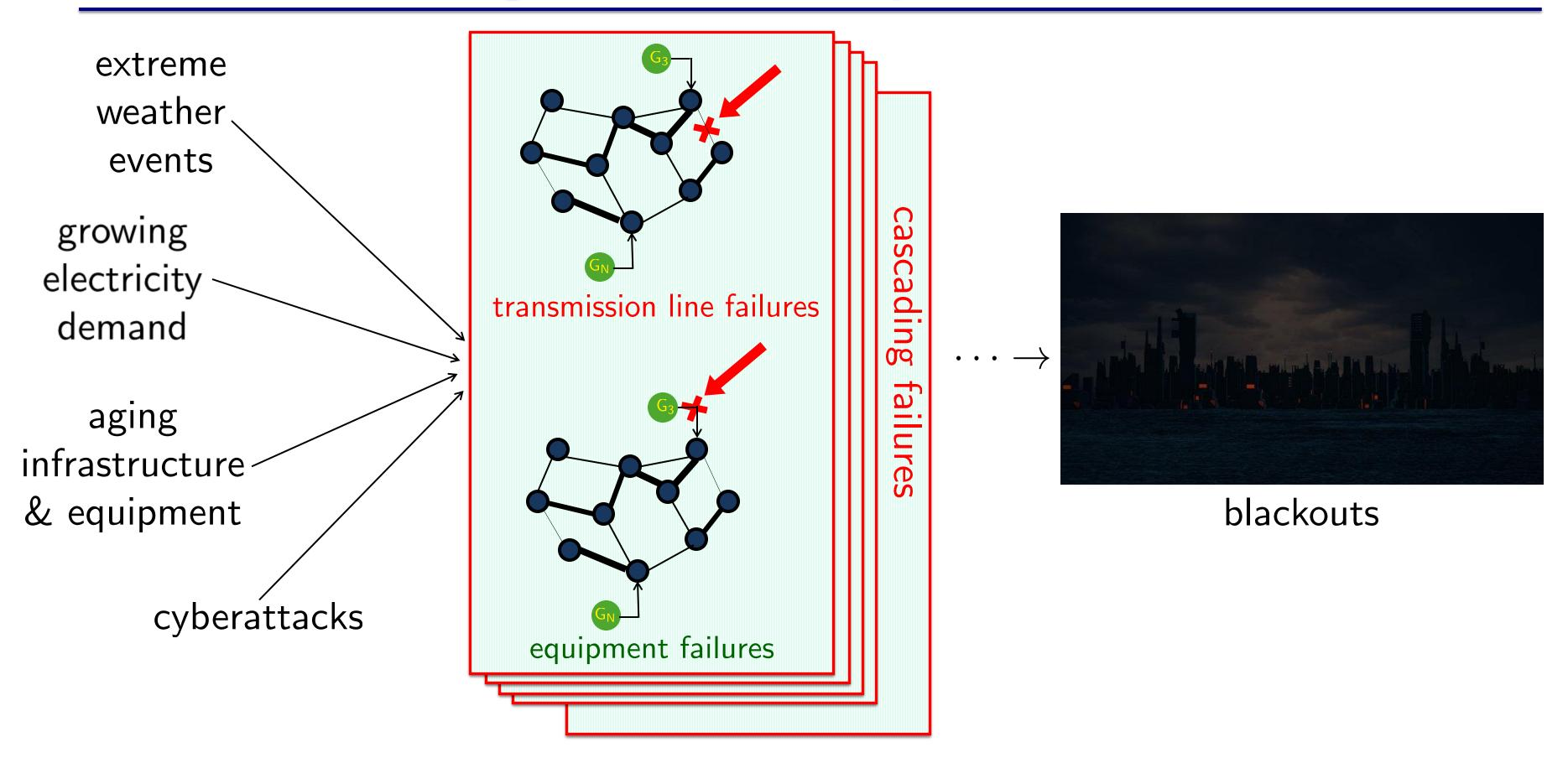


Mitigating and Adapting to Climate Change Necessitates Enhancing Grid Reliability and Resilience



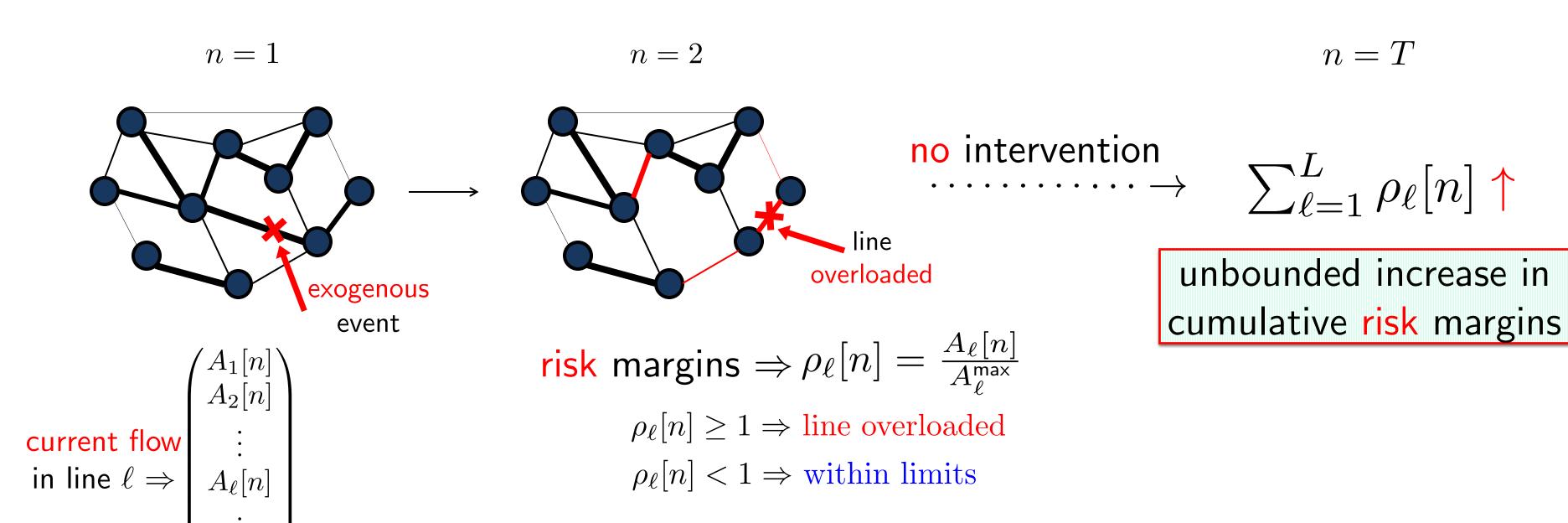
wildfires hurricanes heatwaves

Factors Affecting Grid Reliability

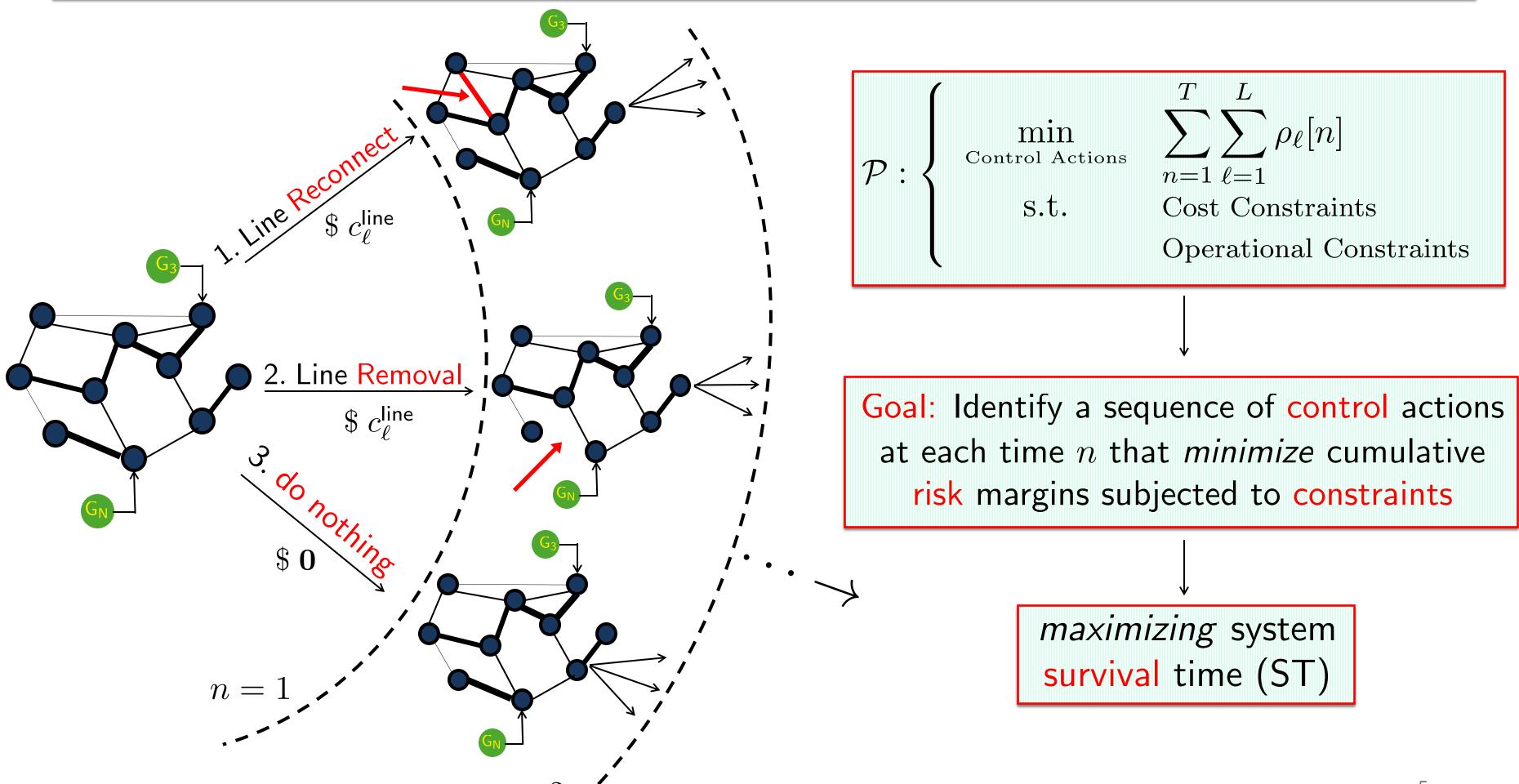


Focus: mitigating cascading failures

Mismanaged Line Flows: A Pathway to Cascading Failures



Controlling Line Flows via Topology Control Actions



Cascading Failure Mitigation via MDPs and Model-Free RL

State Space
$$S$$
:

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$$S$$
: $\mathbf{S}[n] \triangleq [\mathbf{X}[n-(\kappa-1)],\ldots,\mathbf{X}[n]]^{\top} \cdots \rightarrow \begin{cases} \text{sliding window of size } \kappa \\ \text{of past power-grid features} \end{cases}$

Action Space A:

- One action for reconnecting line $\ell \in [L]$ $\cdots \rightarrow |\operatorname{Total}|\mathcal{A}| = 2L + 1$
- One action for removing line $\ell \in [L]$
- do nothing

Reward Dynamics
$$\mathcal{R}$$
:

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$$\mathcal{R}$$
: $r[n] \stackrel{\triangle}{=} \sum_{\ell=1}^L \left(1 - \rho_\ell^2[n]\right) \cdots \rightarrow$ promotes lower risk margins

$$-\mu_{\text{line}}\left(\sum_{\ell=1}^{L}c_{\ell}^{\text{line}}\cdot W_{\ell}[n]\right)\cdots
ightarrow \mu_{\text{line}}$$
 promotes stricter cost requirements

Leverage model-free RL with function approximation to learn a remedial action policy

Exploring Topology Actions: Challenges from Repeated Simulated Blackouts

Grid topology control is sensitive to environmental changes

```
Algorithm 1 Canonical \epsilon-greedy Exploration
```

```
1: Input: \epsilon_1, \mathcal{A}, Q(s,a)

2: Output: Action a

3:

4: if \mu \sim \mathcal{U}(0,1) < \epsilon_1 then

5: a \sim \text{Uniform}(\mathcal{A}) \qquad \triangleright \text{Random-Explore} \qquad \rightarrow

6: else

7: Select a based on Q(s,a') \triangleright Q-guided Exploit

8: end if
```

Sequences of random topology actions quickly result in simulated blackouts

- Episodes terminate prematurely, limiting learning potential
- Restarting episodes with a random policy yields no meaningful progress

Inaccurate value function predictions for unvisited MDP states, particularly in long-horizon tasks like power-grid control

Targeted Topology Exploration via Physics-Guided RL

Targeted exploration is key for efficient exploration

```
Algorithm 1 Physics-Guided \epsilon-greedy Exploration
```

```
1: Input: \epsilon_1, \epsilon_2, \mathcal{A}, Q(s, a)
 2: Output: Action a
 3:
 4: if \mu \sim \mathcal{U}(0,1) < \epsilon_1 then
         if \zeta \sim \mathcal{U}(0,1) < \epsilon_2 then
 5:
                                                                                           Guide exploration using grid
             a \sim \text{Physics-Guided}(\mathcal{A}) \triangleright \text{Physics-Guided Explore}
 6:
                                                                                           sensitivity factors
         else
 7:
             a \sim \text{Uniform}(\mathcal{A})
                                                      ▶ Random-Explore

    Help express the mapping between

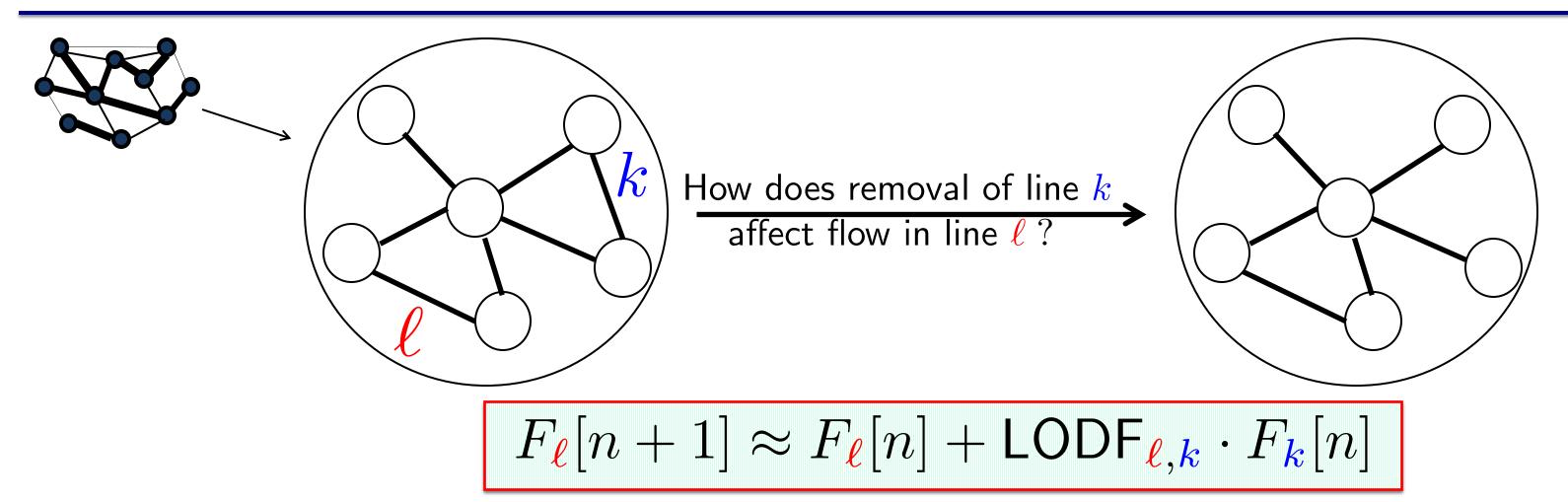
         end if
 9:
                                                                                                 MDP states S and actions A
                                                      \triangleright Q-guided Exploit
10: else
         Select a based on Q(s, a')

    Approximate the potential impact of

11:
12: end if
                                                                                                 actions \mathcal{A} on MDP reward r \in \mathcal{R}
```

Leverage sensitivity factors to search actions that reduce risk margins

Action Search using Line Outage Distribution Factors (LODF)



remove line k that reduce line flow in all other lines $\Rightarrow \sum_{\ell=1,\ell\neq k}^L \rho_\ell[n] \downarrow \cdots \rightarrow$ challenging optimization problem due to grid non-linearlities

remove line k that reduce line flow in maximally overloaded line $\Rightarrow \rho_{\ell_{\max}}[n] \downarrow$

$$F_{\ell_{\max}}[n+1] \approx F_{\ell_{\max}}[n] + \mathsf{LODF}_{\ell_{\max},k} \cdot F_{k}[n]$$

$$\ell_{\max} \triangleq \underset{\ell \in L}{\operatorname{arg\,max}} \ \rho_{\ell}[n]$$

Experiments - Grid2Op 36-bus Network

N=36 buses L=59 transmission lines $\leftarrow \cdots |\mathcal{A}_{\mathsf{line}}| = 119 \ (2L+1)$ T=8062 episode length

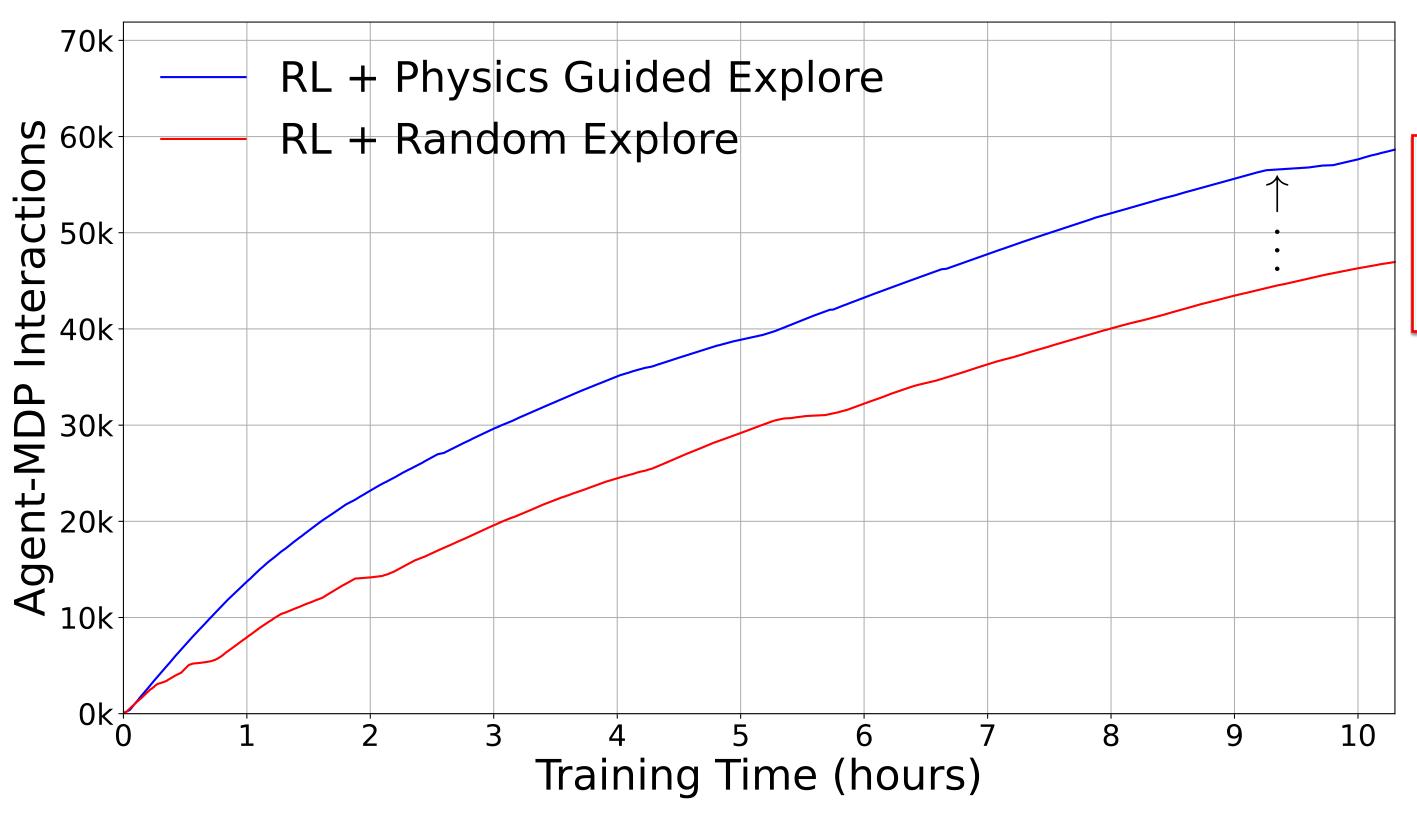
Action Space (\mathcal{A})	Agent Type	Avg. ST	Avg. Action Diversity	
_	Do-Nothing	4733.96	_	\mid \leftarrow \dots no action policy π
\mathcal{A}_{line} (60)	Re-Connection	4743.87	1.093 (1.821%)	$\leftarrow \cdots$ Always reconnect line policy π

$\mathcal{A}_{line} \ (119)$	$\pi_{m{ heta}}^{\sf rand}(0)$	5929.03	13.406 (11.265%)	$\leftarrow \cdots$ Random Exploration $\pi_{ heta}^{rand}$
$\mu_{line} = 0$	PG-RL $[\pi_{\boldsymbol{\theta}}^{physics}(0)]$	6657.09	17.062 (14.337 %)	$\frown \cdots$ Physics-Guided Exploration $\pi_{\theta}^{\text{physics}}$

$\mathcal{A}_{line} \ (119)$	$\pi_{m{ heta}}^{\sf rand}(1.5)$	4916.34	3.406 (2.862%)	$\leftarrow \dots$ Random Exploration
$\mu_{line} = 1.5$	PG-RL $[\pi_{\boldsymbol{\theta}}^{physics}(1.5)]$	6761.34	15.718 (13.208 %)	← Physics-Guided Exploration

PG-RL identifies impactful topological actions, leading to greater action diversity resulting in better grid-utilization along with a significant *increase* in survival time

Why is Physics-Guided Exploration More Effective?



each episode is more thoroughly explored for a given computational budget

Thank You! See you in the Poster Session

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- Code:
 - https://github.com/anmold-07/Physics-Guided-Blackout-Mitigation
- Extended Work including Generators Adjustment Actions:
 - A. Dwivedi, S. Paternain, A. Tajer, "Blackout Mitigation via Physics-Guided RL,"
 IEEE Transactions in Power Systems, DOI: 10.1109/TPWRS.2024.3472570, 2024