

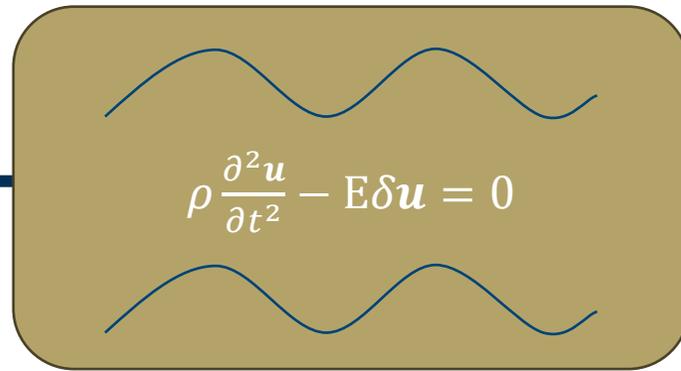
# PETAL: Physics Emulation Through Averaged Linearizations for Solving Inverse Problems

Jihui Jin · Etienne Ollivier · Richard Touret  
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# Inverse Problems

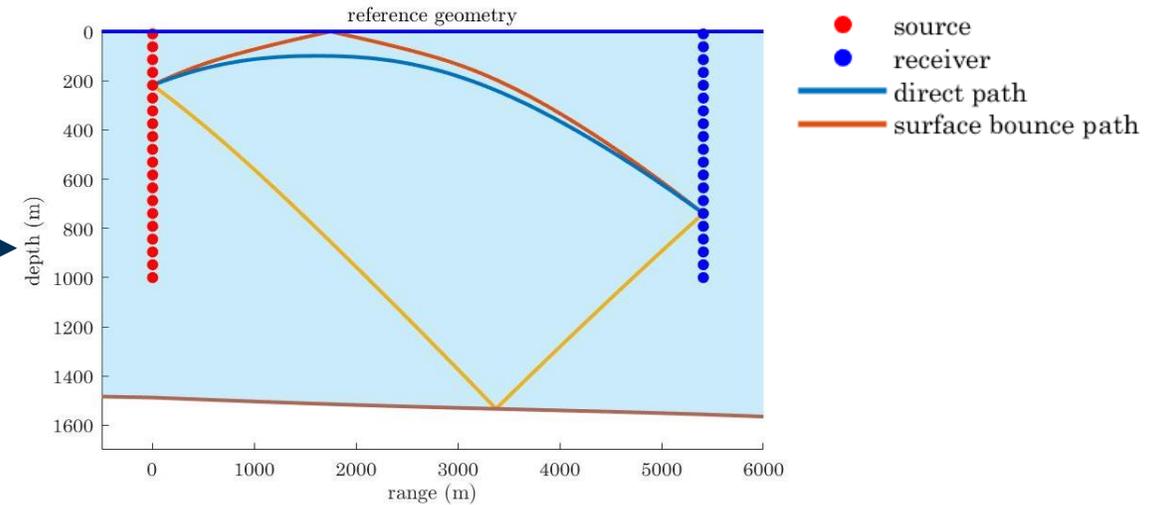


$x$



$F$

$$y = F(x)$$



$y$

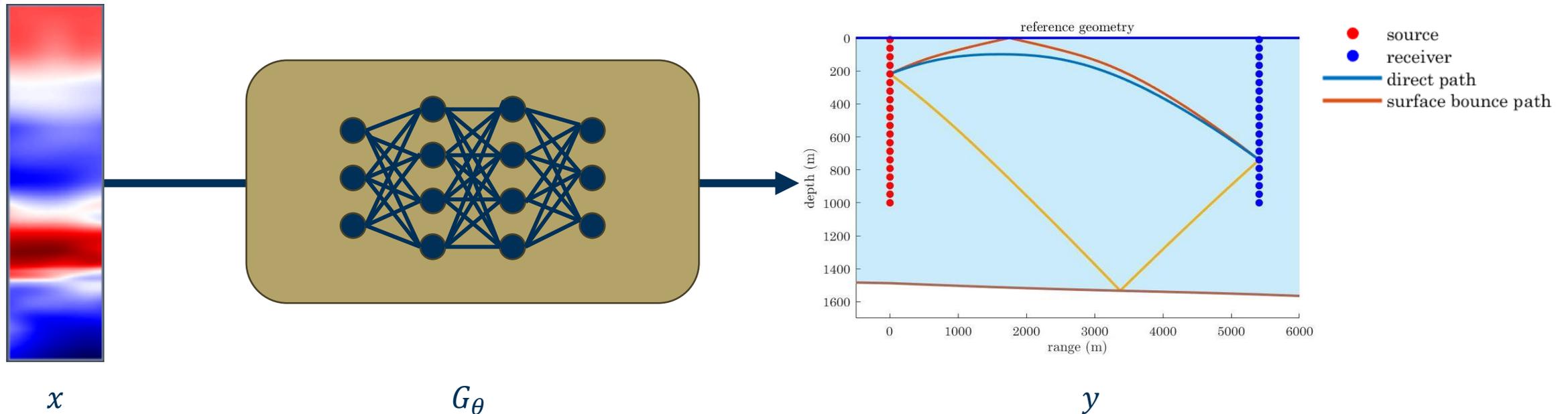
- $x$  – underlying signal of interest (Sound Speed Profile)
- $y$  – observables (arrival times observed at receivers)
- $F$  – “Forward” model that maps signal to observables

# Neural Adjoint: Forward Model Surrogate

- Physics-based Forward Model
- Train a **Neural Net** surrogate model

$$F: x \rightarrow y$$

$$G_\theta: x \rightarrow y$$



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$$\hat{x} = \arg \min_x \frac{1}{2} |G_{\theta}(x) - y|^2$$

- Solve for iteratively

$$x^{k+1} = x^k - \lambda d^k$$

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- Descent direction

$$d^k = J_G(x)^\top (G_\theta(x) - y)$$

GPU acceleration (Fast!)

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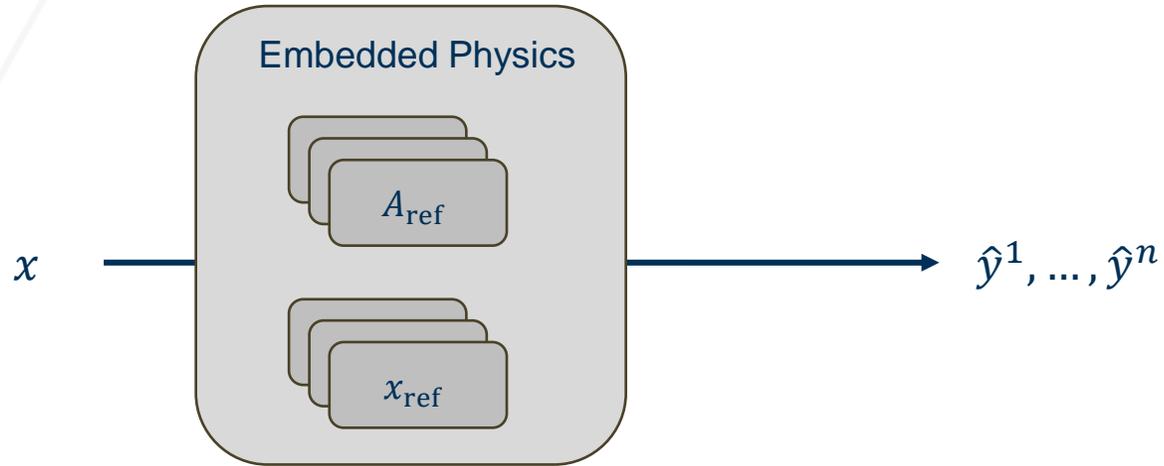
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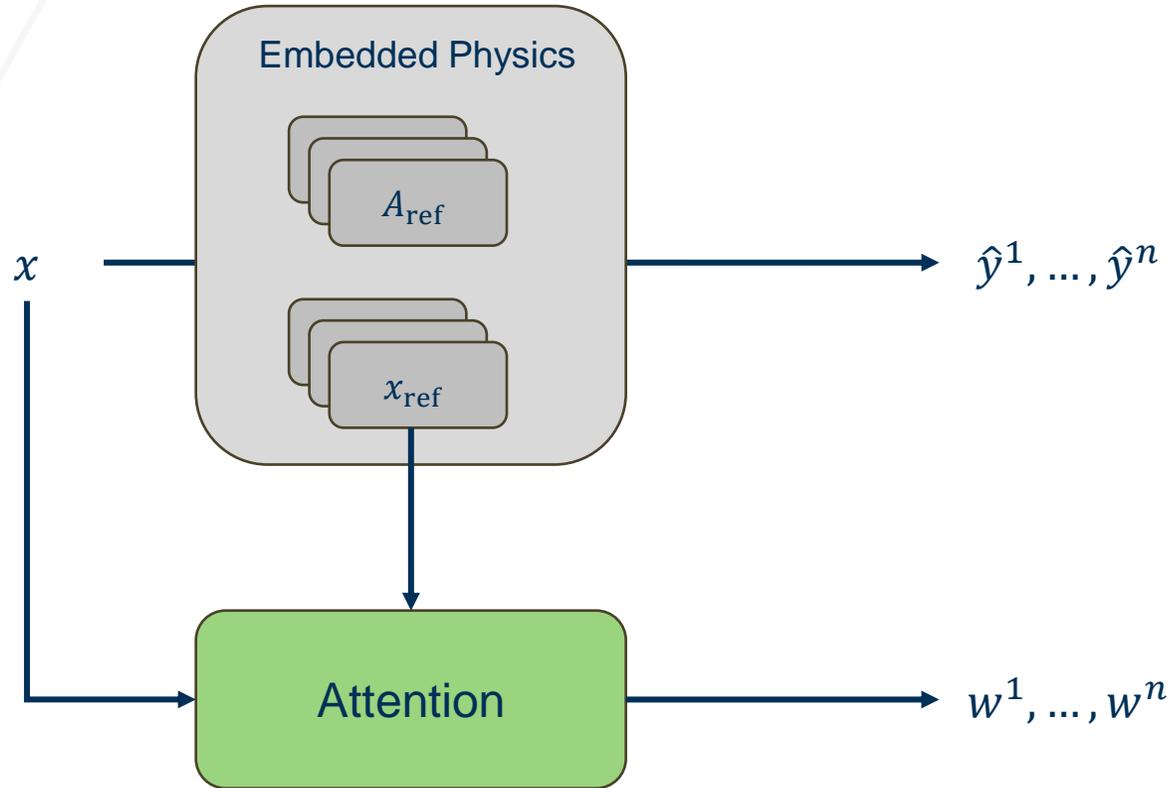
**Black box: no physics**

# PETAL – Embedding Physics



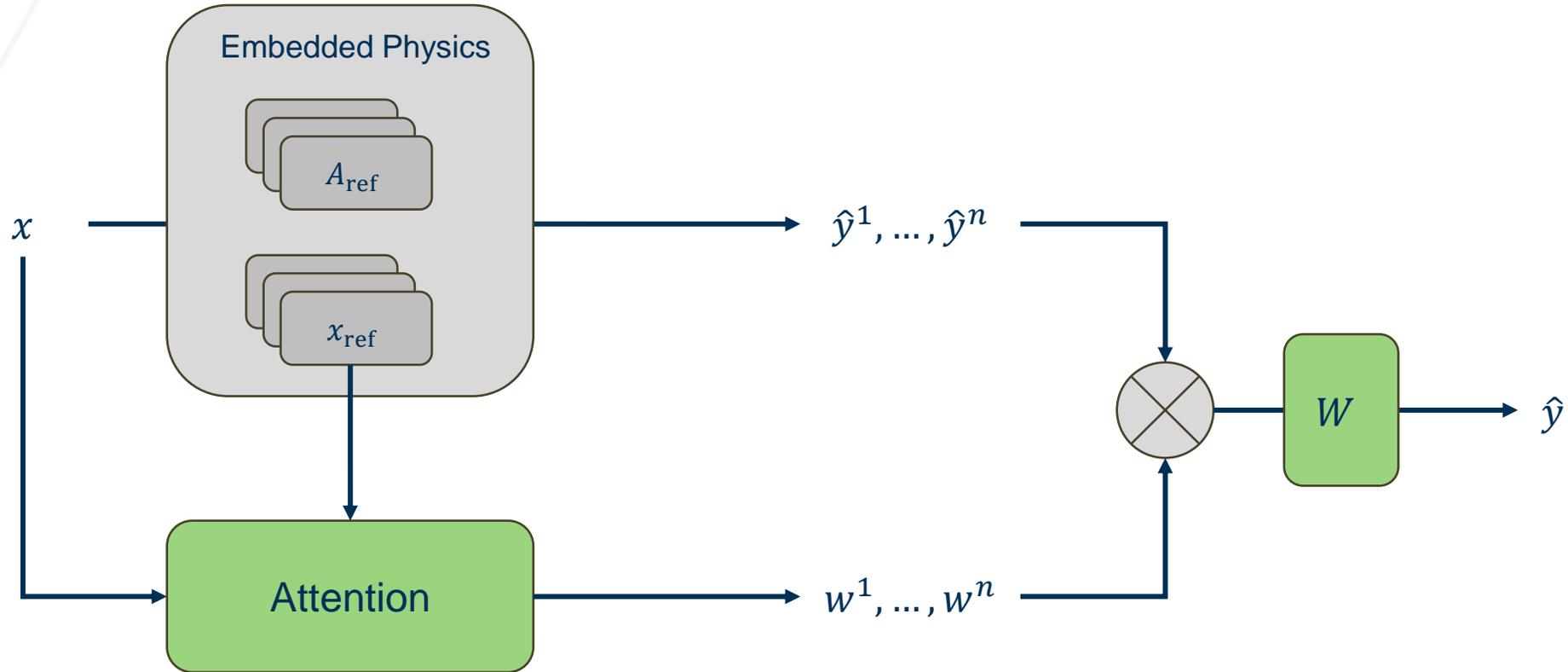
- Ensemble of cheap approximations of physics based forward model
  - $y = J_F(x_{\text{ref}})^\top (x - x_{\text{ref}}) + y_{\text{ref}}$   
 $y = A_{\text{ref}}(x - x_{\text{ref}}) + y_{\text{ref}}$

# PETAL



- Compute weights via a learned attention module

# PETAL



- Take a weighted average over the set of reference models

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- Replace  $F$  with  $G_\theta$

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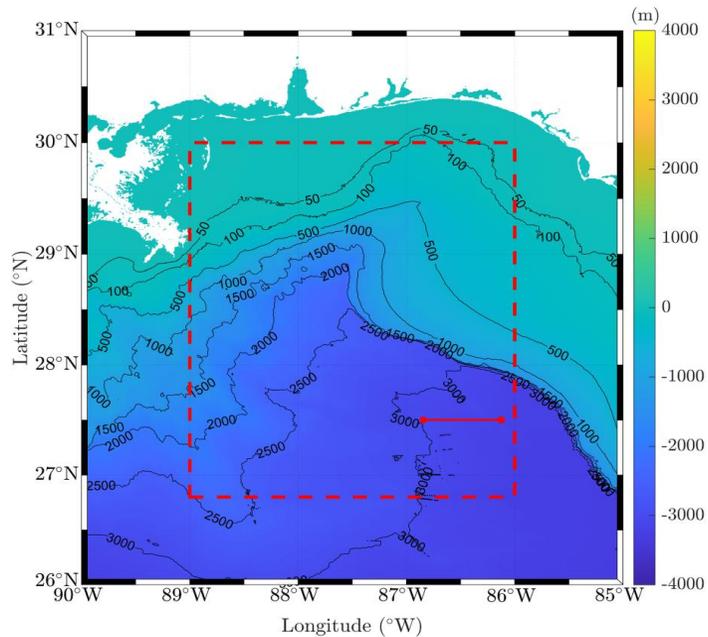
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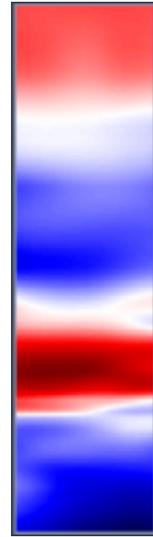
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**Embedded Physics via Linearizations**

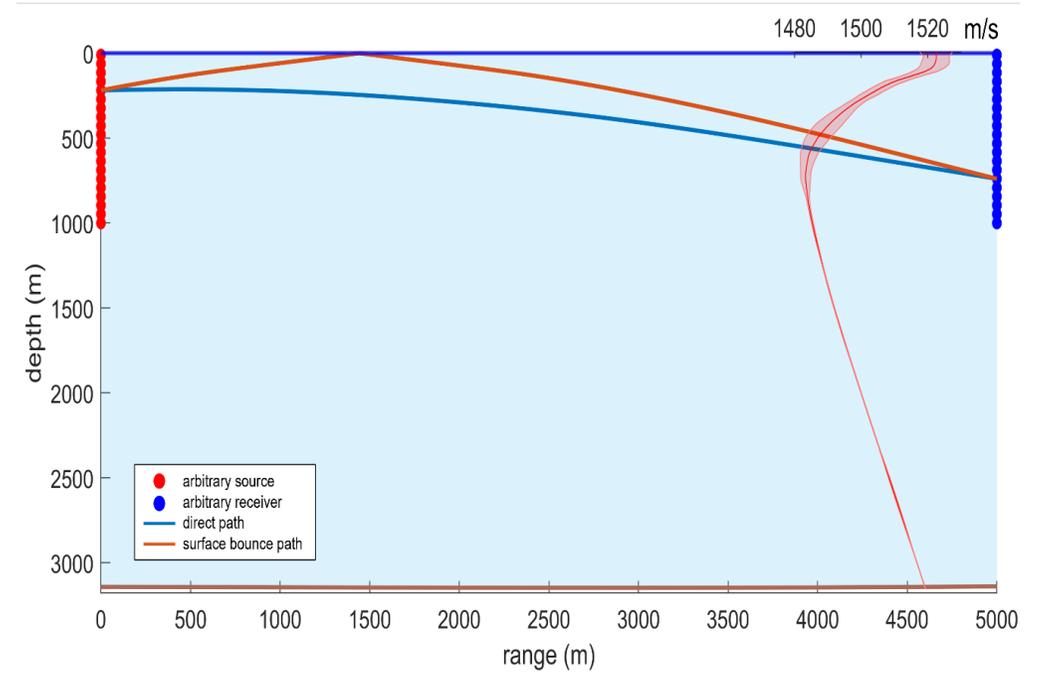
# Experimental Set Up



Gulf of Mexico



Data



Forward Model

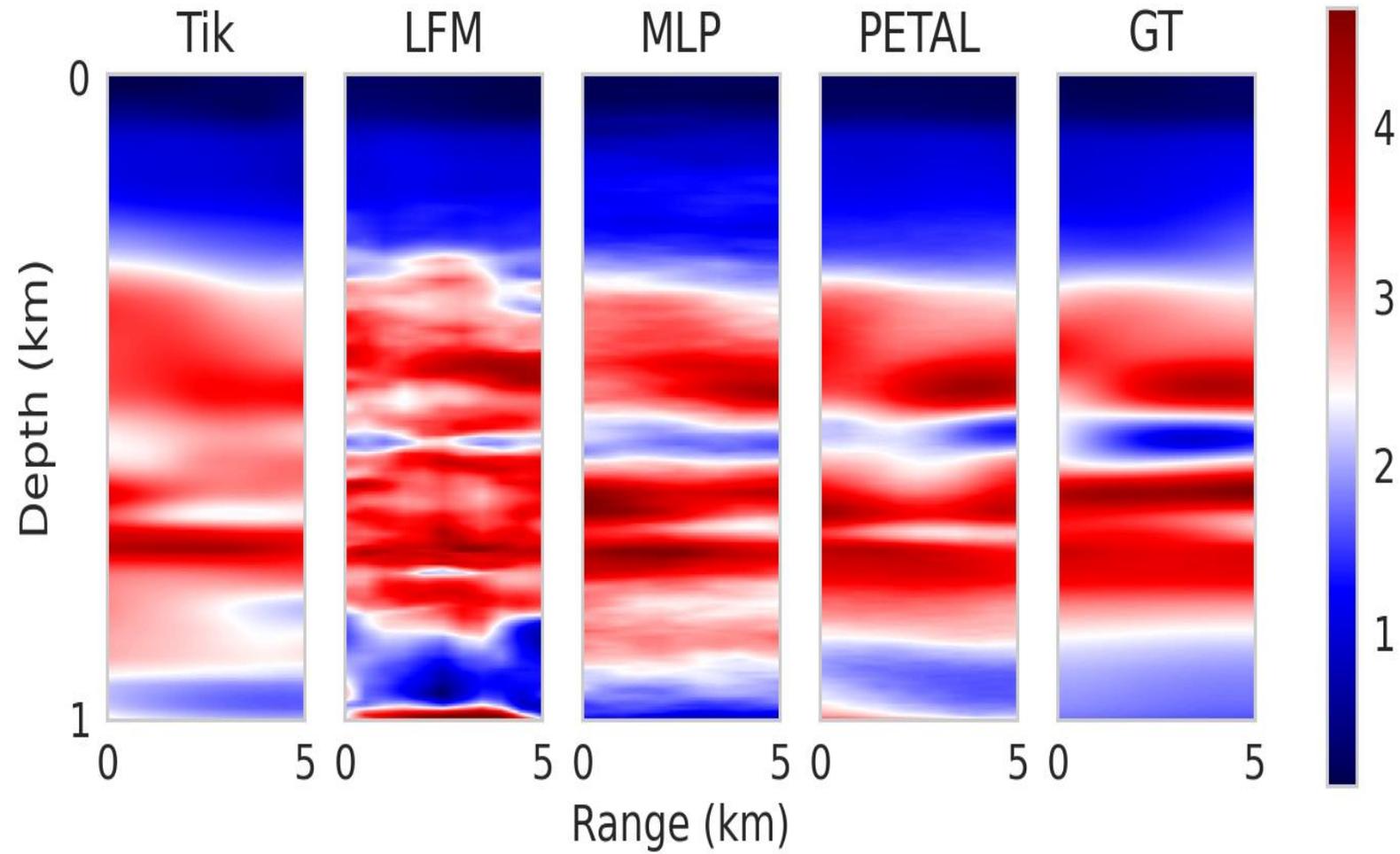
- Data collected from simulations of the Gulf of Mexico
- Forward Model: Direct and surface bounce path between source-receiver pairs
- Data: Sound Speed Profiles
- Observables: Arrival times

# Results

	Low Variability		Med Variability		High Variability	
	Avg	Tik	Avg	Tik	Avg	Tik
Tik	0.647	---	0.773	---	0.881	---
LFM	0.620	0.597	0.584	0.580	0.617	0.630
MLP	0.384	0.378	0.406	0.409	0.424	0.428
PETAL (Ours)	<b>0.365</b>	<b>0.339</b>	<b>0.360</b>	<b>0.346</b>	<b>0.361</b>	<b>0.374</b>

- Tik – Classical Inversion with linearized forward model + Tikhonov regularization
- LFM – Optimization framework with linearized forward model
- MLP – Neural adjoint optimization framework with generic learned surrogate
- PETAL – Proposed model in neural adjoint optimization framework

# Results



# Conclusion

- Introduce the Neural Adjoint method for solving inverse problems
- Introduce a novel architecture that embeds physics into the surrogate
- Demonstrate its efficacy on a ocean acoustic tomography problem