

Reusable Slotwise Mechanisms

Trang Nguyen^{1,2}, Amin Mansouri^{1,4}, Kanika Madan^{1,4}, Khuong Nguyen², Kartik Ahuja¹,
Dianbo Liu^{1,3}, and Yoshua Bengio^{1,4,5}

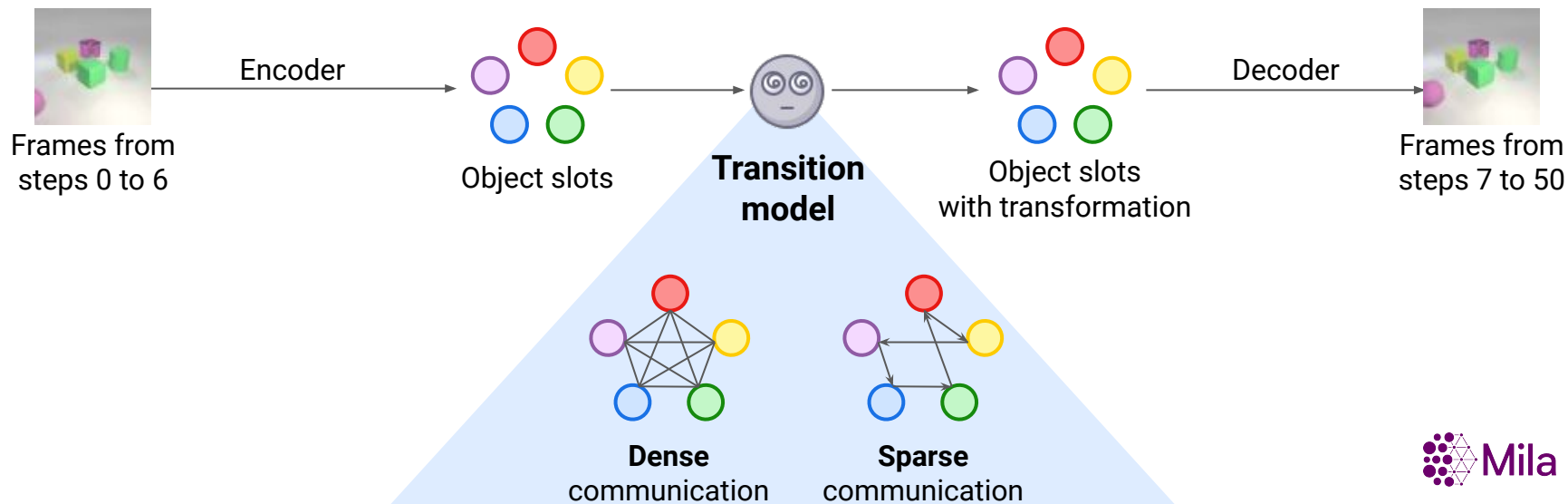
[1] Mila - Quebec AI Institute, [2] FPT Software AI Center, [3] National University of Singapore,
[4] University of Montreal, [5] CIFAR AI Chair

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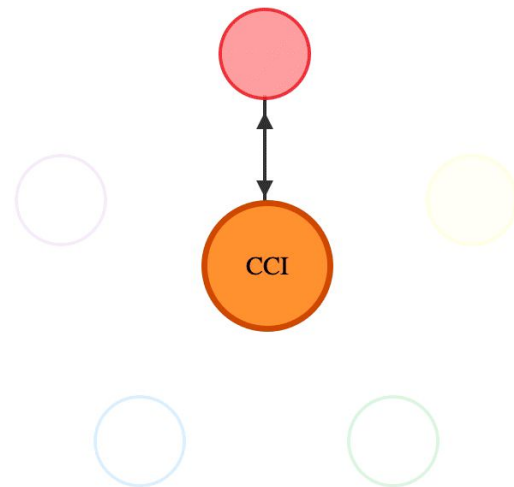
Background

- The ability to reason about the dynamics of objects helps in achieving robustness and generalization when presented with distribution shifts
- It requires representing scenes effectively and understanding the mechanisms that govern the interactions
- Prior works model interactions either through too dense or too sparse form of communication among slots



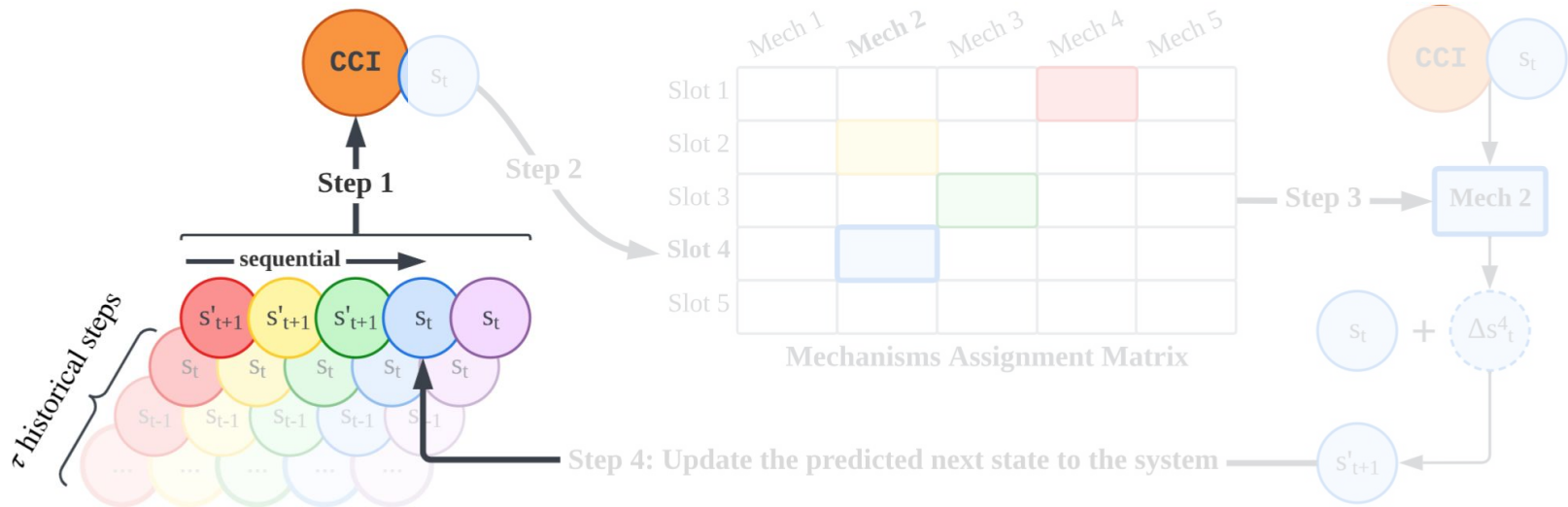
Reusable Slotwise Mechanisms (RSM)

- **Our goals:**
 - Leverage *context-dependent* communication among slots
 - Relaxing the inductive biases over communication density
 - Central Contextual Information (CCI) treats latest slots status as a spatiotemporal context.
- **CCI:**
 - ... is computed from latest slots
 - ... is used for selecting the relevant mechanism for each slot
 - ... provides context for determining the output of the selected mechanism, i.e., is provided along the object slots as input to the mechanism



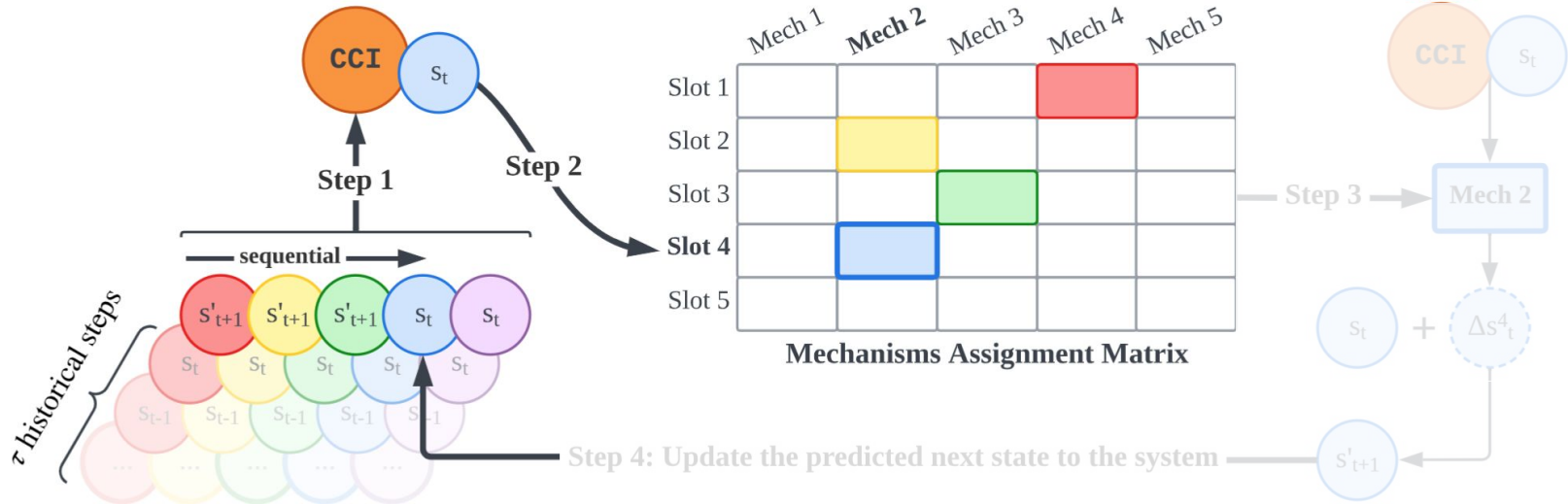
Reusable Slotwise Mechanisms (RSM)

- Step 1: Compute the CCI from historical steps



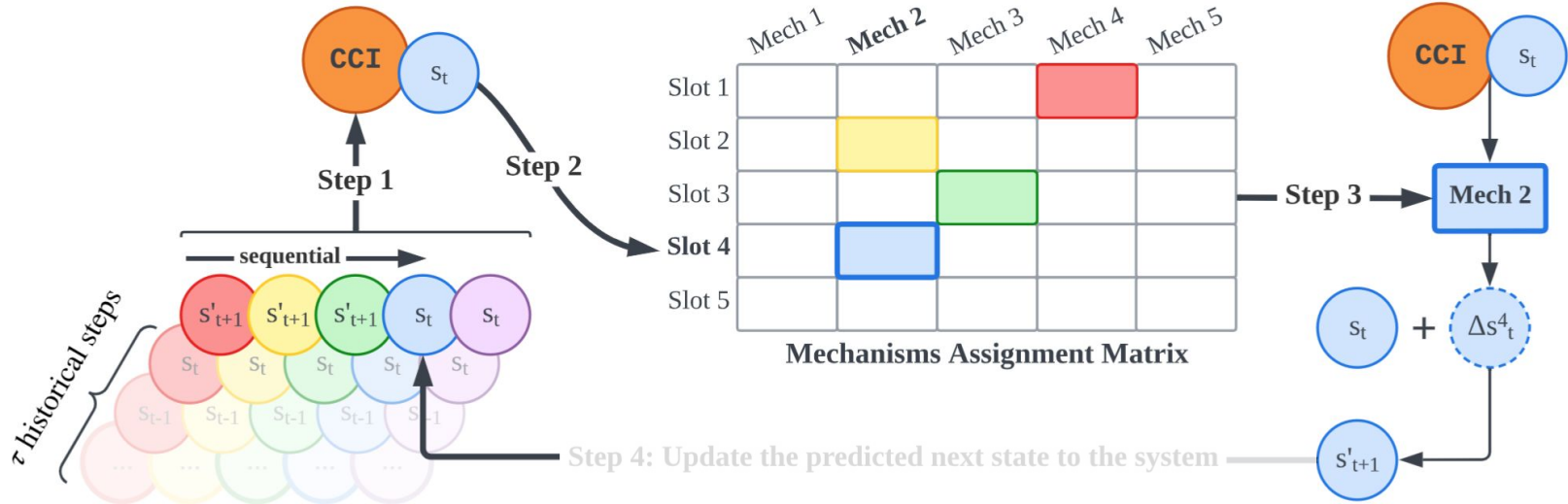
Reusable Slotwise Mechanisms (RSM)

- Step 2: Select a mechanism for the slot of interest



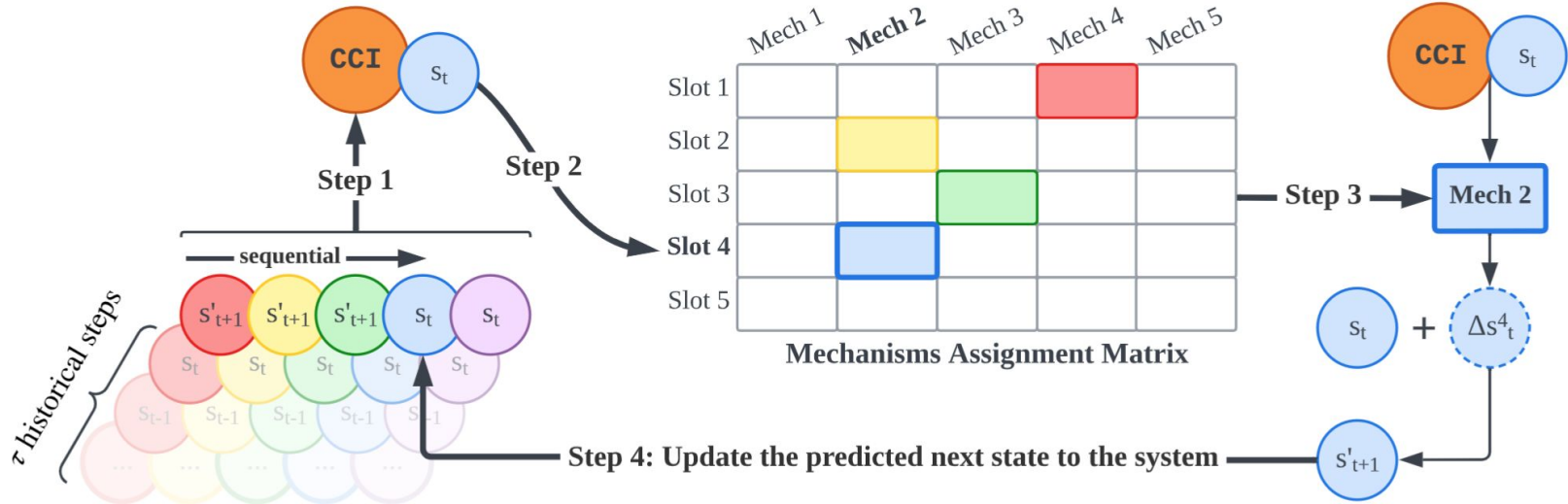
Reusable Slotwise Mechanisms (RSM)

- Step 3: Compute the transformation of slot from t to $t+1$







Reusable Slotwise Mechanisms (RSM)

- Step 4: Sync the predicted next state of slot to the system

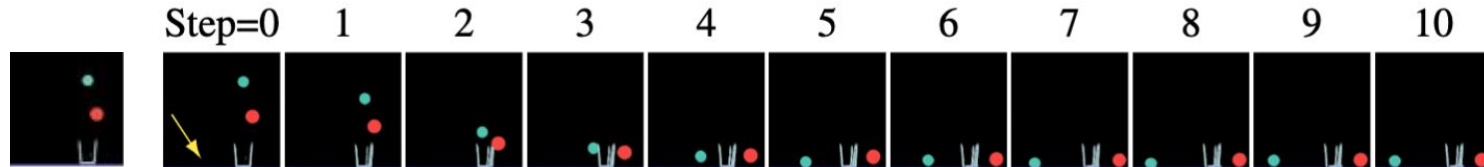


Experiments Setup

| | Video Prediction | Visual Question Answering | Action Planning | OOD Evaluation |
|-------------------------------------------------------------------------------------------|------------------|---------------------------|-----------------|----------------|
| OBJ3D  | ✓ | | | |
| CLEVRER  | ✓ | ✓ | | |
| PHYRE  | ✓ | | ✓ | ✓ |
| Physion  | ✓ | ✓ | | |

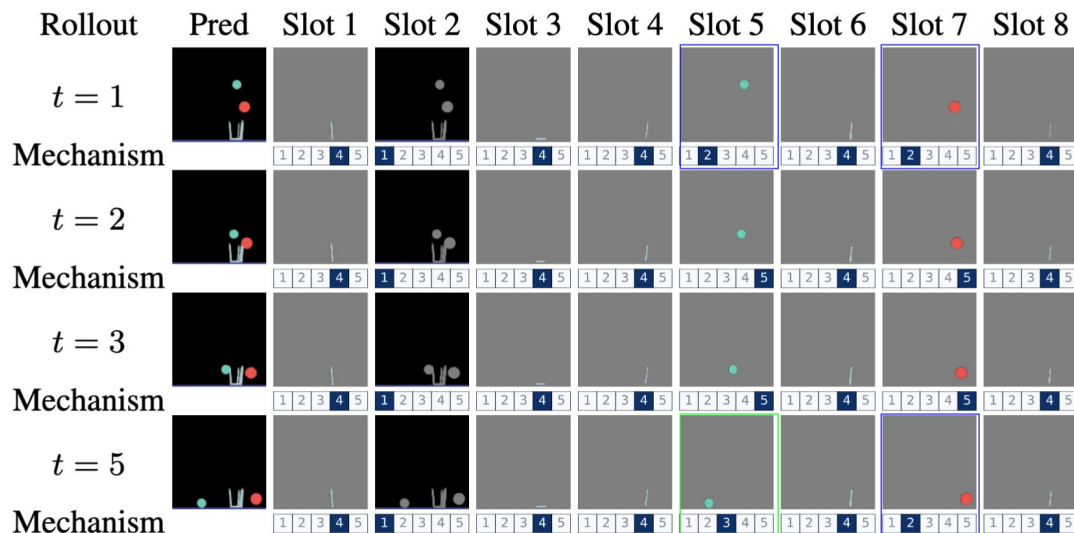
Experiment Results - Action planning

- RSM strategically positions a red ball at step 0 that helps the green ball make contact with the blue floor (indicated by the arrow).



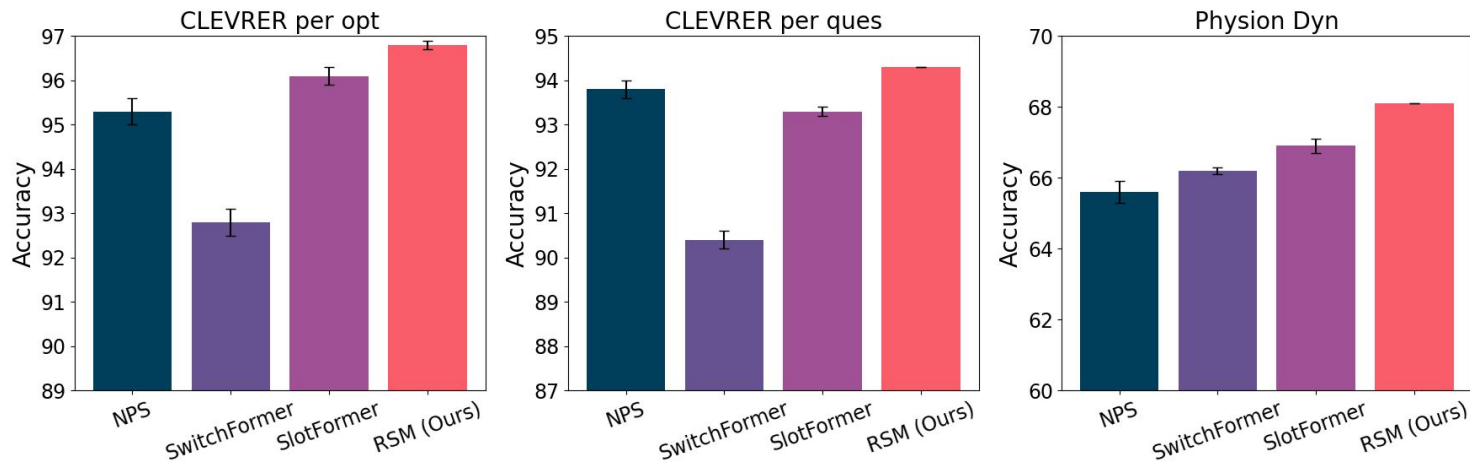
Experiment Results - Mechanism Selection

- RSM disentangles objects' dynamics into reusable mechanisms,
- Mechanisms can be expressed as Collision (2), Moving left or right (3), Idle (4), and Falling (5).



Experiment Results - Visual Question Answering

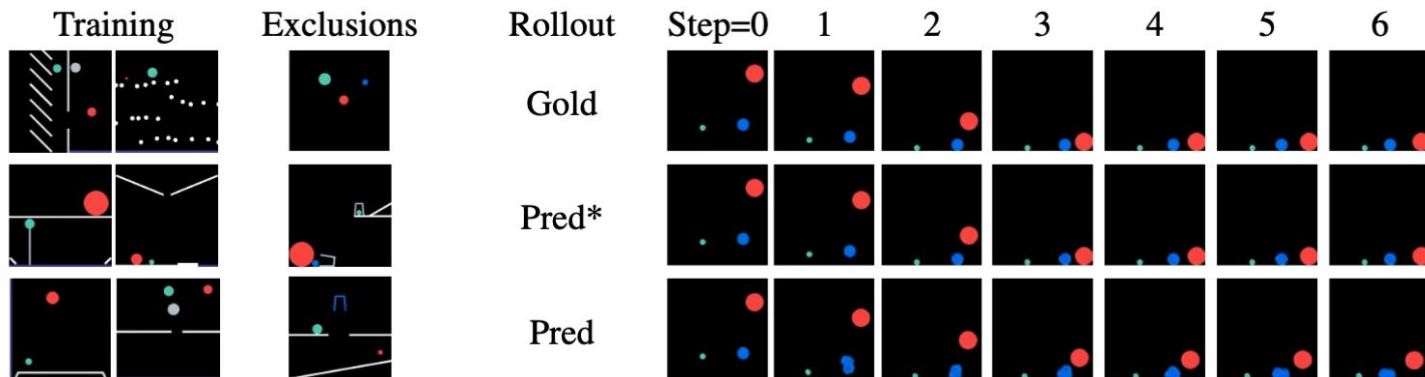
- RSM consistently outperforms all baselines in CLEVRER and Physion



Experiment Results - OOD Evaluation

- **OOD in Dynamics**

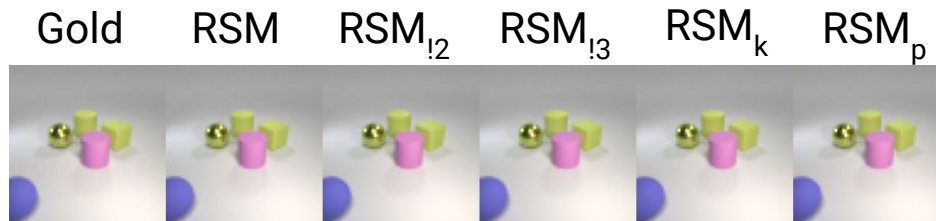
- The **Blue** moving objects only appear in the test set
- RSM generalizes the movements of the ball-shaped objects in OOD settings



Ablation Studies

The original RSM always demonstrates accurate future frame predictions compared to the modified versions

- **Gold:** Ground truth frames
- **RSM:** Original design of RSM
- **RSM_{I₂}:** Omit the CCI in step 2
- **RSM_{I₃}:** Omit the CCI in step 3
- **RSM_k:** Randomly selecting the mechanisms
- **RSM_p:** Slots are updated in parallel



Summary

- RSM relaxes the inductive biases in communication sparsity among slots using a bottleneck called Central Contextual Information (CCI)
- RSM is advantageous over the baselines in various tasks, both iid and OOD scenarios
- There is a promise for exploring more sophisticated stochastic attention mechanisms for information integration

Thank you!

