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# A Unified Generalization Analysis of Re-Weighting and Logit-Adjustment for Imbalanced Learning

Zitai Wang, Qianqian Xu\*, Zhiyong Yang,  
Yuan He, Xiaochun Cao, Qingming Huang\*



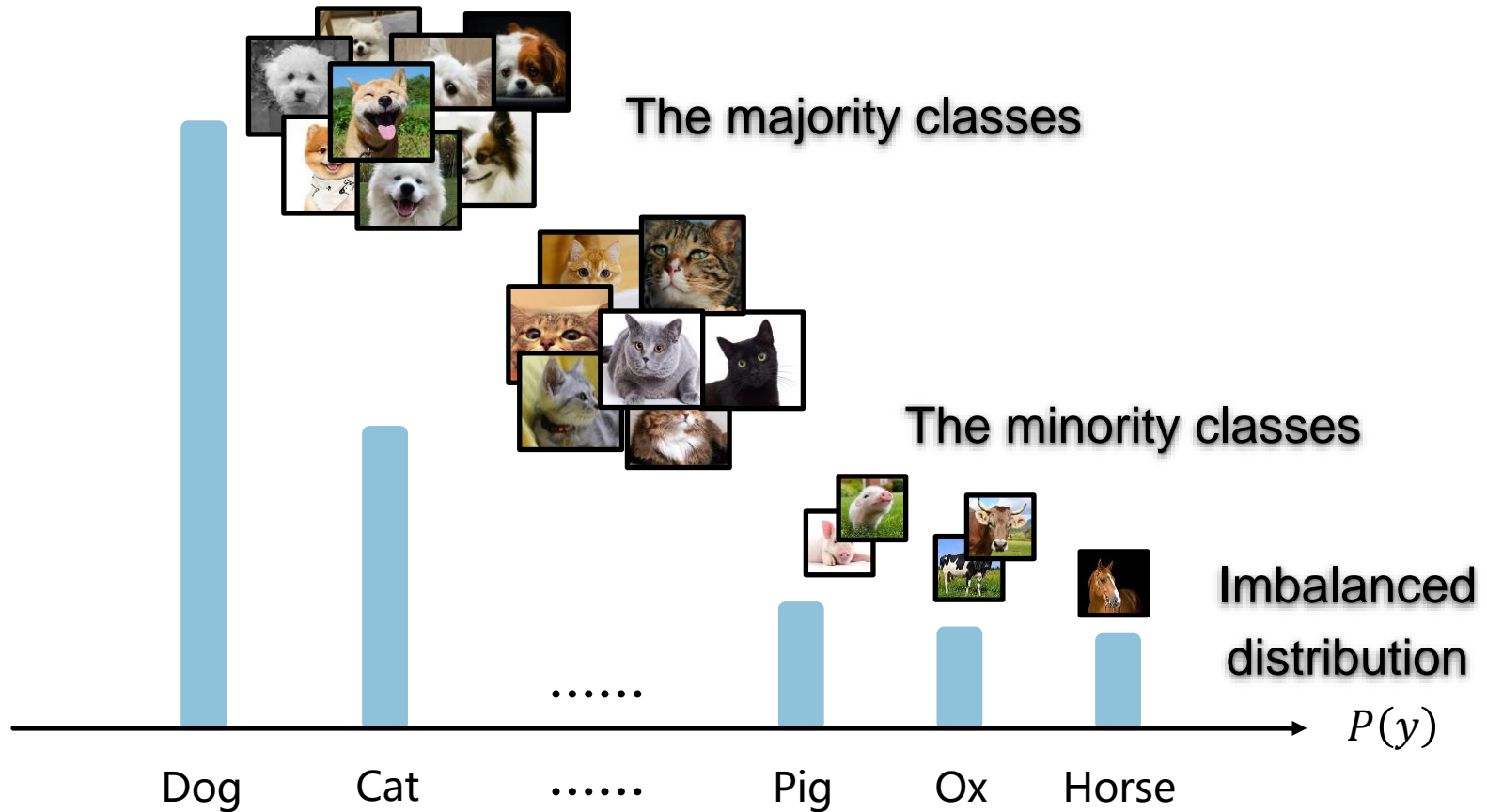
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**Zitai Wang**

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# Background

- Real-world datasets are generally imbalanced



**A naïve ERM learning process will be biased!**

# Background

□ **Balanced Accuracy is a common metric in this case**



99 Dogs



One Ox

A classifier only predicts dogs

**Accuracy**

$$\frac{1}{N} \sum_{i=1}^N \mathbb{I}[f(x_i) = y_i]$$

× **99 / 100 = 99%, good model**

**Balanced Accuracy**

$$\frac{1}{C} \sum_{y=1}^C \frac{1}{N_y} \sum_{i=1}^{N_y} \mathbb{I}[f(x_i) = y_i]$$

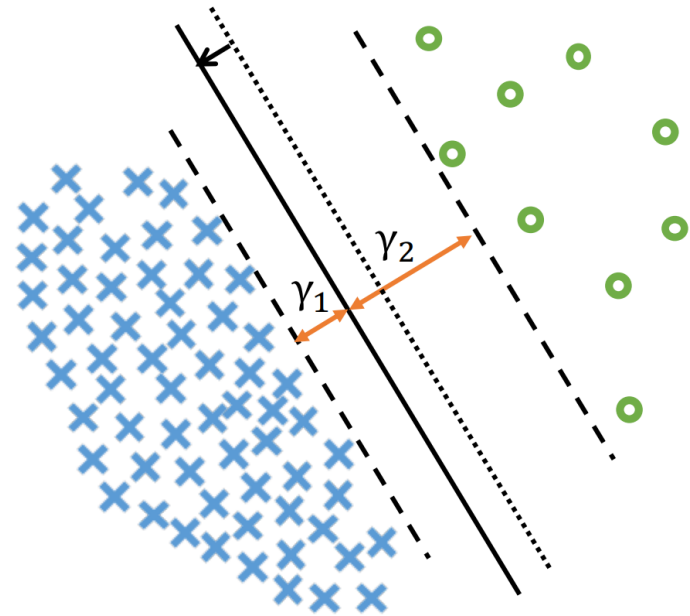
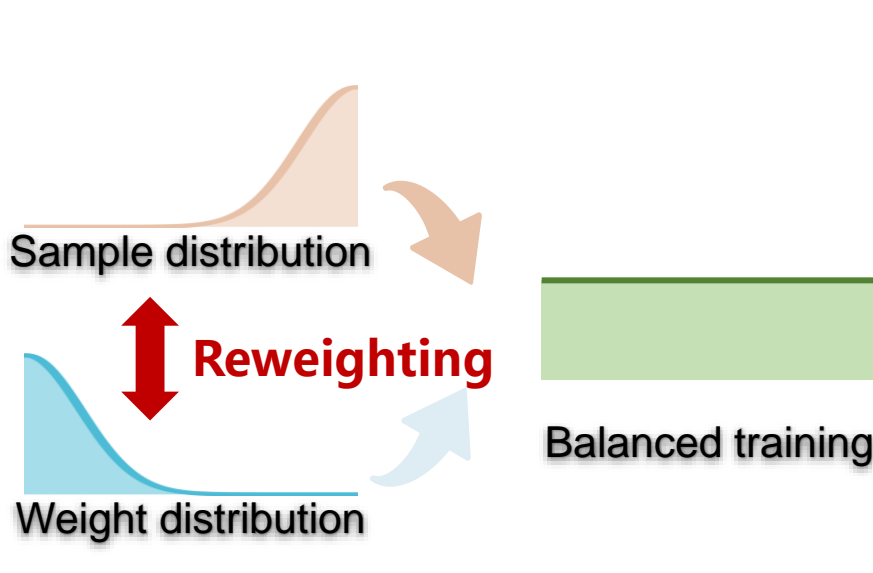
✓ **(0 + 1) / 2 = 50%, bad model**

**How to improve model performance on Balanced Acc.?**

# Prior arts

## □ Loss-modification approaches

- Re-weighting [1, 2]
- Logit adjustment [3, 4, 5]



[1] Combining statistical learning with a knowledge-based approach, ICML, 1999.

[2] Class-balanced loss based on effective number of samples, CVPR, 2019.

[3] Learning imbalanced datasets with label-distribution-aware margin loss, NeurIPS 2019.

[4] Long-tail learning via logit adjustment, ICLR, 2021

[5] Label-imbalanced and group-sensitive classification under overparameterization, NeurIPS 2021

# Prior arts

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## □ A unified formulation for RW and LA

- $\alpha_y = 1, \beta_y = 1, \Delta_y = 0 \rightarrow$  **Naïve CE loss**
- $\alpha_y = (1 - p)/(1 - p^{N_y}), \beta_y = 1, \Delta_y = 0 \rightarrow$  **CB loss [2]**
- $\alpha_y = 1, \beta_y = 1, \Delta_y = \tau \log \pi_y \rightarrow$  **LA loss [4]**
- $\alpha_y = 1, \beta_y = (N_y/N_1)^{\gamma}, \Delta_y = 0 \rightarrow$  **CDT loss [6]**

$$L_{\text{VS}}(f(\mathbf{x}), y) = \underbrace{-\alpha_y}_{\text{Reweighting term}} \log \left( \frac{e^{\beta_y f(\mathbf{x})_y + \Delta_y}}{\sum_{y'} e^{\beta_{y'} f(\mathbf{x})_{y'} + \Delta_{y'}}} \right)$$

**multiplicative adjustment term**      **additive adjustment term**

[2] Class-balanced loss based on effective number of samples, CVPR, 2019.

[4] Long-tail learning via logit adjustment, ICLR, 2021

[6] Identifying and compensating for feature deviation in imbalanced deep learning, Arxiv, 2020

# Limitation of prior arts

- Theoretical insights are still fragmented and coarse-grained, failing to explain some empirical results

## Proposition (Union bound for Imbalanced Learning)

Given a function set  $\mathcal{F}$  and a  $\mu$ -Lipschitz continuous loss  $L: \mathbb{R} \times \mathcal{C} \rightarrow [0, M]$ , then for any  $\delta \in (0, 1)$ , with probability at least  $1 - \delta$  over the training set  $\mathcal{S}$ , the following generalization bound holds for all  $g \in \mathcal{G}$ :

$$\mathcal{R}_{bal}^L(f) = \frac{1}{C} \sum_{y=1}^C \mathcal{R}_y^L(f) \lesssim \frac{1}{C} \sum_{y=1}^C \left( \hat{\mathcal{R}}_y^L(f) + \mu \hat{\mathcal{C}}_{\mathcal{S}_y}(\mathcal{F}) + 3M \sqrt{\frac{\log 2C/\delta}{2N_y}} \right)$$

Balanced risk

Generation bound for each class, where **the Lipschitz Continuity is the only property of  $L$  utilized, which is global in nature**

# Main work

- **Theoretical insights:** propose local Lipschitz continuity and construct a fine-grained generalization bound

## Theorem (Data-Dependent Bound for Imbalanced Learning)

Given a function set  $\mathcal{F}$  and a loss function  $L: \mathbb{R} \times \mathcal{C} \rightarrow [0, M]$  with **local Lipschitz constants**  $\{\mu_y\}_{y=1}^c$ , then for any  $\delta \in (0, 1)$ , with probability at least  $1 - \delta$  over the training set  $\mathcal{S}$ , the following generalization bound holds for all  $g \in \mathcal{G}$ :

$$\mathcal{R}_{bal}^L(f) \lesssim \frac{1}{C\pi_C} \left[ \hat{\mathcal{R}}^L(f) + 3M \sqrt{\frac{\log \frac{2C}{\delta}}{2N}} \right] + \frac{\hat{\mathcal{C}}_{\mathcal{S}}(\mathcal{F})}{C\pi_C} \sum_{y=1}^c \mu_y \sqrt{\pi_y}$$

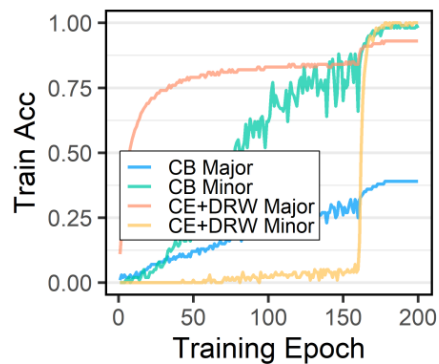
The diagram illustrates the decomposition of the balanced risk  $\mathcal{R}_{bal}^L(f)$  into two main components. The first component,  $\frac{1}{C\pi_C} \left[ \hat{\mathcal{R}}^L(f) + 3M \sqrt{\frac{\log \frac{2C}{\delta}}{2N}} \right]$ , is labeled as "Terms depending on training". The second component,  $\frac{\hat{\mathcal{C}}_{\mathcal{S}}(\mathcal{F})}{C\pi_C} \sum_{y=1}^c \mu_y \sqrt{\pi_y}$ , is labeled as "Loss dependent, where  $\mu_y$  captures how the loss handles each class".

# Main work

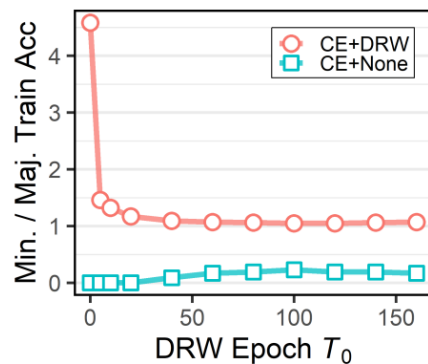
□ **Theoretical insights:** the fine-grained generalization

bound is consistent with some empirical results

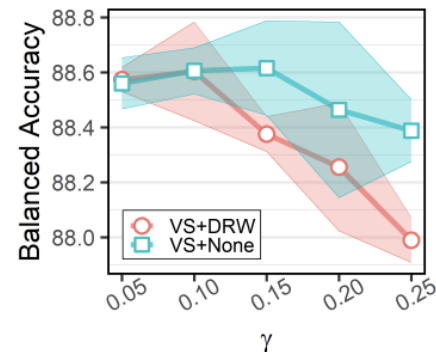
- Deferred scheme is necessary
- Reweighting term and multiplicative adjustment term might be incompatible



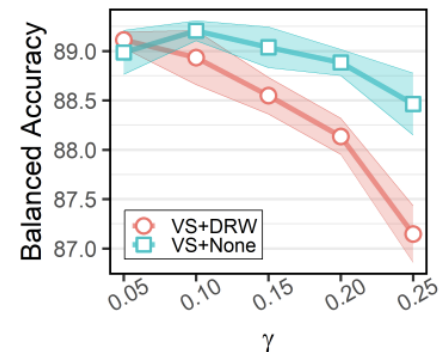
(a) CIFAR-100 LT ( $\rho = 100$ )



(b) CIFAR-100 LT ( $\rho = 100$ )



(a) CIFAR-10 LT



(b) CIFAR-10 Step



# Main work

## □ Improved algorithm: a principled learning algorithm induced by the theoretical insights

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**Algorithm 1:** Principled Learning Algorithm induced by the Theoretical Insights

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**Require:** Training set  $\mathcal{S} = \{(x_i, y_i)\}_{i=1}^N$  and a model  $f$  parameterized by  $\Theta$ .

- 1: Initialize the model parameters  $\Theta$  randomly.
  - 2: **for**  $t = 1, 2, \dots, T$  **do**
  - 3:    $\mathcal{B} \leftarrow \text{SampleMiniBatch}(\mathcal{S}, m)$  ▷ A mini-batch of  $m$  samples
  - 4:   **if**  $t < T_0$  **then** ▷ Adjust logits during the initial phase
  - 5:     Set  $\alpha = 1, \beta_y, \Delta_y$
  - 6:   **else**
  - 7:     Set  $\alpha_y \propto \pi_y^{-\nu}, \beta_y = 1, \Delta_y, \nu > 0$
  - 8:   **end if**
  - 9:    $L(f, \mathcal{B}) \leftarrow \frac{1}{m} \sum_{(\mathbf{x}, y) \in \mathcal{B}} L_{\text{vs}}(f(\mathbf{x}), y)$  ▷ Calculate the loss
  - 10:    $\Theta \leftarrow \Theta - \eta \nabla_{\Theta} L(f, \mathcal{B})$  ▷ One SGD step
  - 11:   Optional: anneal the learning rate  $\eta$ . ▷ Required when  $t = T_0$
  - 12: **end for**
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- ✓ **Reweighting is deferred and aligns with the bound**
- ✓  **$\beta_y = 1$  when reweighting is used**

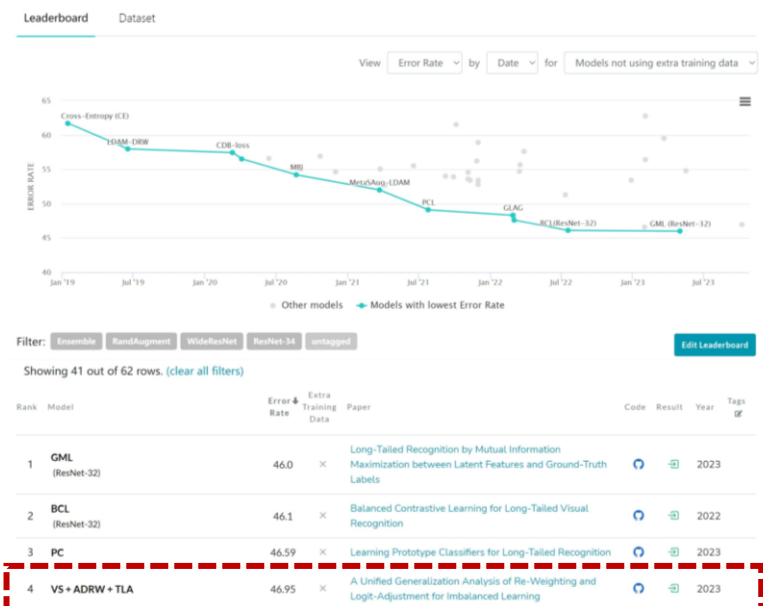
# Main work

- Improved algorithm: a principled learning algorithm induced by the theoretical insights

Dataset	CIFAR-10		CIFAR-100	
Imbalance Type	LT	Step	LT	Step
w/o SAM				
CE	71.5 $\pm$ 0.4	64.8 $\pm$ 0.9	38.3 $\pm$ 0.4	38.6 $\pm$ 0.2
LDAM	73.8 $\pm$ 0.4	65.8 $\pm$ 0.6	39.9 $\pm$ 0.7	39.2 $\pm$ 0.0
VS	78.8 $\pm$ 0.2	76.1 $\pm$ 0.7	41.8 $\pm$ 0.7	<b>46.2</b> $\pm$ 0.3
CE+DRW	75.8 $\pm$ 0.3	72.2 $\pm$ 0.8	40.8 $\pm$ 0.6	45.4 $\pm$ 0.4
LDAM+DRW	77.7 $\pm$ 0.4	77.8 $\pm$ 0.5	<b>42.7</b> $\pm$ 0.5	45.3 $\pm$ 0.6
VS+DRW	<b>80.1</b> $\pm$ 0.1	<b>78.2</b> $\pm$ 0.2	41.3 $\pm$ 0.4	44.0 $\pm$ 0.3
CE+ADRW	78.6 $\pm$ 0.5	75.5 $\pm$ 0.6	41.8 $\pm$ 0.6	46.5 $\pm$ 0.3
LDAM+ADRW	79.1 $\pm$ 0.2	78.5 $\pm$ 0.4	<b>43.0</b> $\pm$ 0.2	45.8 $\pm$ 0.2
VS+TLA+DRW	<b>80.8</b> $\pm$ 0.2	<b>80.0</b> $\pm$ 0.1	43.0 $\pm$ 0.4	<b>46.8</b> $\pm$ 0.1
VS+TLA+ADRW	<b>81.1</b> $\pm$ 0.2	<b>80.9</b> $\pm$ 0.2	<b>43.4</b> $\pm$ 0.6	<b>47.8</b> $\pm$ 0.1
w/ SAM				
CE+DRW	80.5 $\pm$ 0.2	79.5 $\pm$ 0.3	44.7 $\pm$ 0.6	48.5 $\pm$ 0.3
LDAM+DRW	81.6 $\pm$ 0.2	81.2 $\pm$ 0.7	45.2 $\pm$ 0.3	<b>49.1</b> $\pm$ 0.2
VS	<b>82.6</b> $\pm$ 0.2	<b>83.2</b> $\pm$ 0.4	<b>45.9</b> $\pm$ 0.3	47.4 $\pm$ 0.3
CE+ADRW	82.6 $\pm$ 0.2	<b>82.8</b> $\pm$ 0.9	44.9 $\pm$ 0.6	48.9 $\pm$ 0.2
LDAM+ADRW	<b>83.0</b> $\pm$ 0.1	82.4 $\pm$ 0.3	<b>46.3</b> $\pm$ 0.4	<b>49.3</b> $\pm$ 0.4
VS+TLA+ADRW	<b>83.6</b> $\pm$ 0.2	<b>83.8</b> $\pm$ 0.1	<b>46.4</b> $\pm$ 0.6	<b>49.1</b> $\pm$ 0.2

- Rank 4<sup>th</sup> if using more techniques (models with extra training data or ensemble are filtered)

Long-tail Learning on CIFAR-100-LT ( $\rho=100$ )



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# Thanks for your listening!

