

Cosmology from Galaxy Redshift Surveys with PointNet

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Abstract

General setting

- The Λ CDM model of cosmology: free parameters
- Galaxy redshift surveys: positions of millions of galaxies

→ Parameter constraints

Goals of this work

- Comparison between
 - Hand crafted features (standard approach)
 - Learned features
- Higher precision constraints

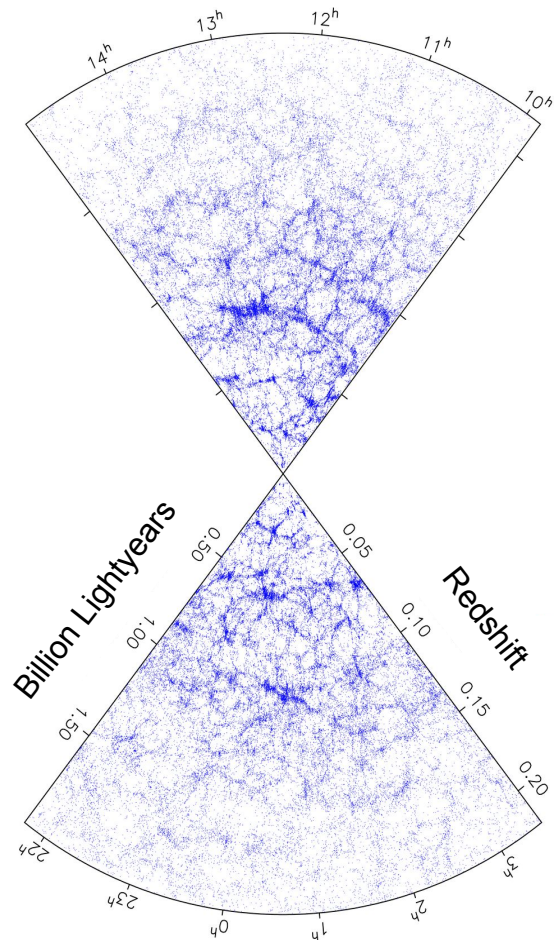


Image credit: 2dF Galaxy Redshift Survey

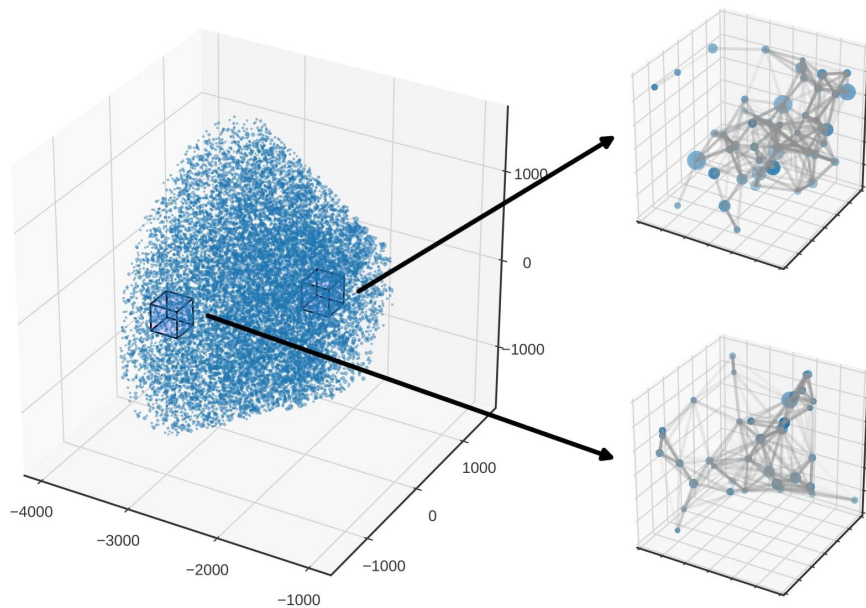
Dataset

Cosmological aspects

- Dark matter only N-body simulations
→ Halo catalogs
- Parameters
 - Ω_M Present-day matter fraction
 - σ_8 Clumpiness of the matter distribution

Format

- Point clouds
- Features
 - Positions only (x,y,z)
 - Positions and masses (x,y,z,M)



Features

Two-point statistics (*hand crafted*)

- Standard summary statistic
 - Real space: *correlation function*
 - Fourier space: *power spectrum*
- Sufficient for Gaussian random fields

Point cloud networks (*learned*)

- PointNeXt architecture
- Automatic extraction of relevant features
- Hierarchical
- Can easily include additional features

Both cases

- Input to multilayer perceptrons (MLPs)
- Direct regression of the cosmological parameters (MSE loss)

Results

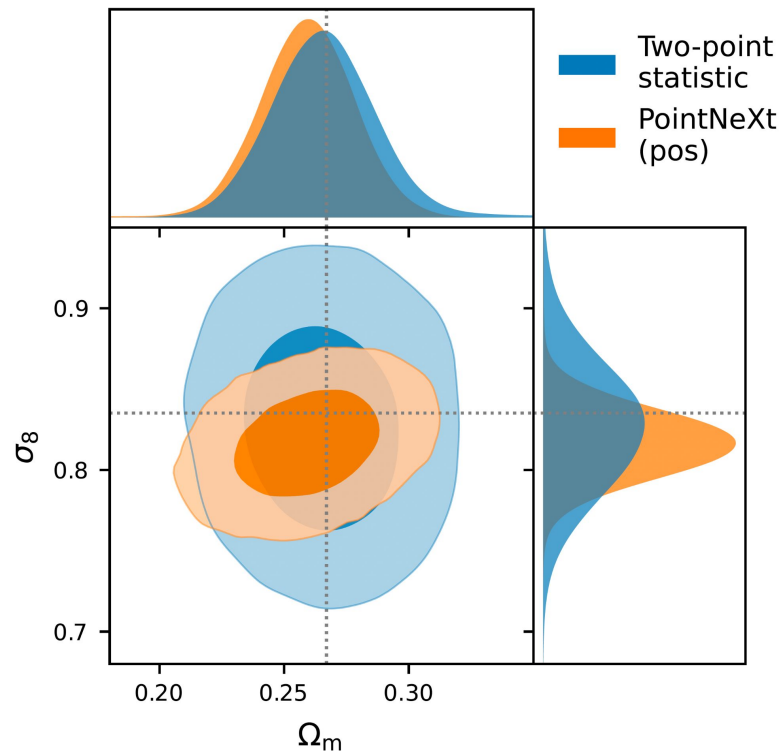
Equal numbers of points

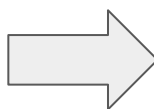
- MSE on test set
- Posterior conditioned on a mock observation

→ **The networks outperform the correlators**

# points	PointNeXt (pos)	PointNeXt (pos+M)	Two-point
8 000	3.6	1.3	8.3
16 000	2.4	0.67	3.3
32 000	1.3	0.58	1.8

MSE in multiples of 10^{-3}



 **Promising application of Deep Learning**