

# DIFFERENTIABLE LEARNING UNDER TRIAGE

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**FOR SOFTWARE SYSTEMS**



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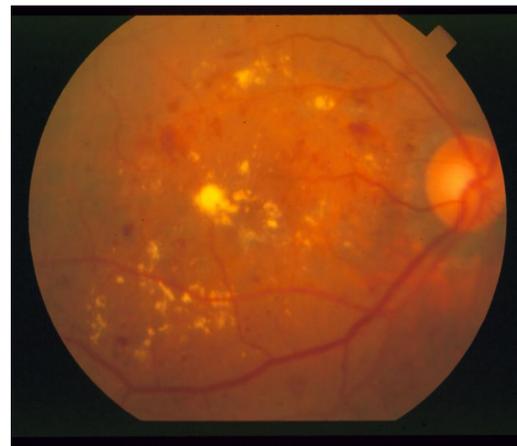
# WHAT IS ALGORITHMIC TRIAGE?

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- Machine learning models have surpassed human performance on many tasks.
- There are still some cases on which human has better performance.
- **Algorithmic triage**: balance human and algorithmic predictions.

**AI models from Microsoft and Google already surpass human performance on the SuperGLUE language benchmark**

*[<https://venturebeat.com/>]*



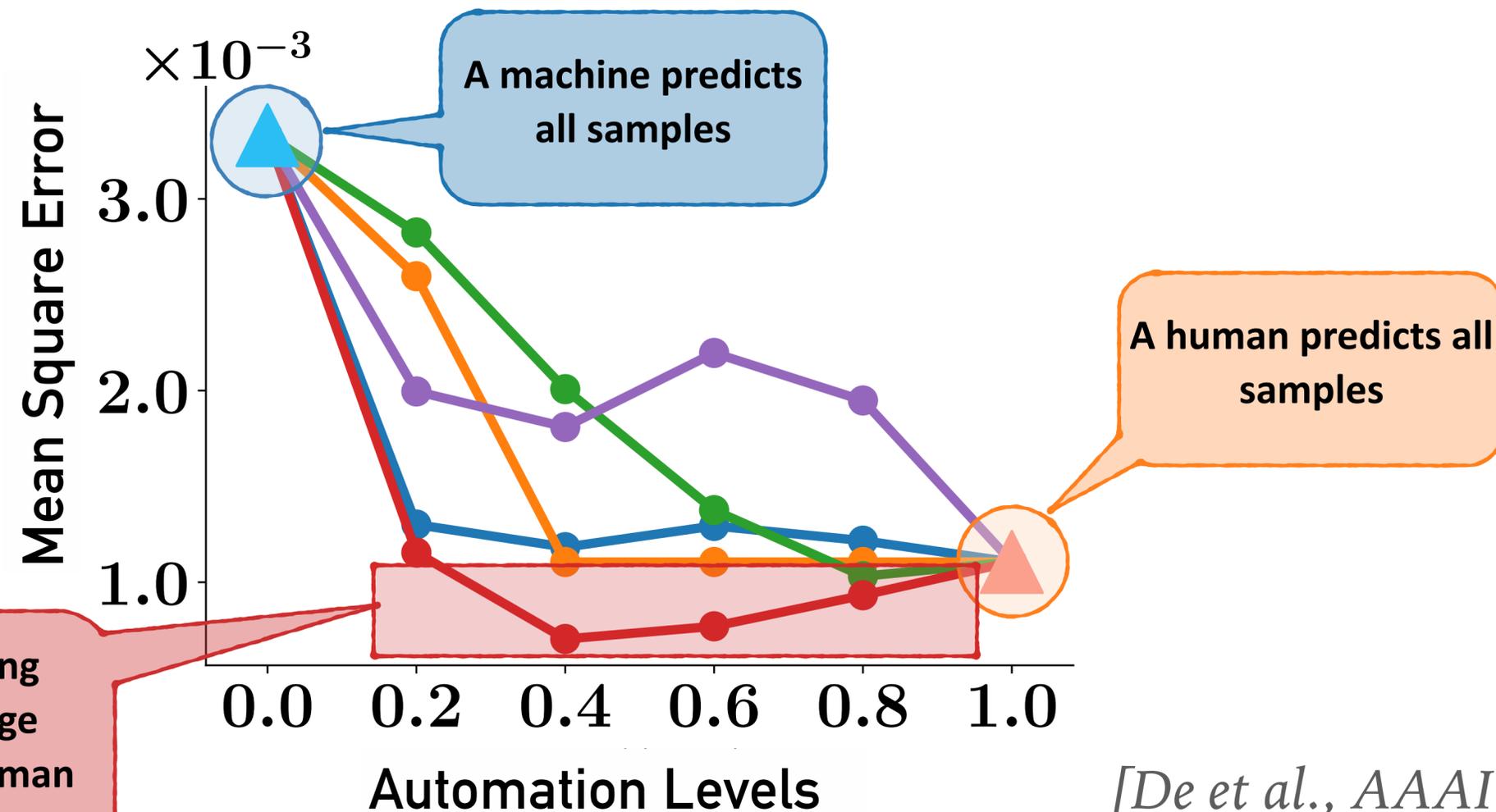
**Delving Deep into Rectifiers:  
Surpassing Human-Level Performance on ImageNet Classification**

*[He et al., CVPR 2015]*

**A difficult sample for machine due to the existence of yellow spots which suggest the presence of Drusen disease. In this case however, the yellow spots are due to diabetic retinopathy.**

# WHY ALGORITHMIC TRIAGE?

- By working together, **humans** and **machines** are likely to achieve a better performance than each of them on their own.



A human and a machine working together using algorithmic triage perform better than both the human and machine working on their own.

[De et al., AAI 2020]

# LEARNING UNDER ALGORITHMIC TRIAGE

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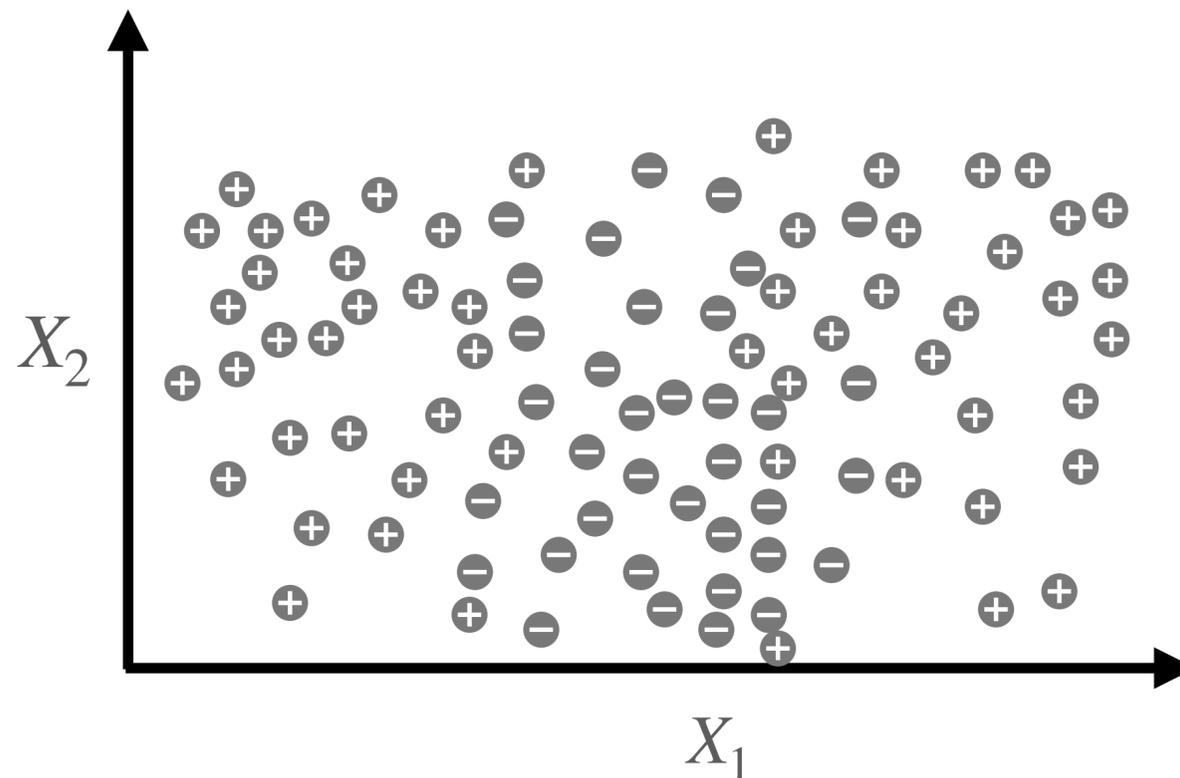
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Example Task: Binary Classification. For simplicity, assume that human performs uniformly good across the feature space.

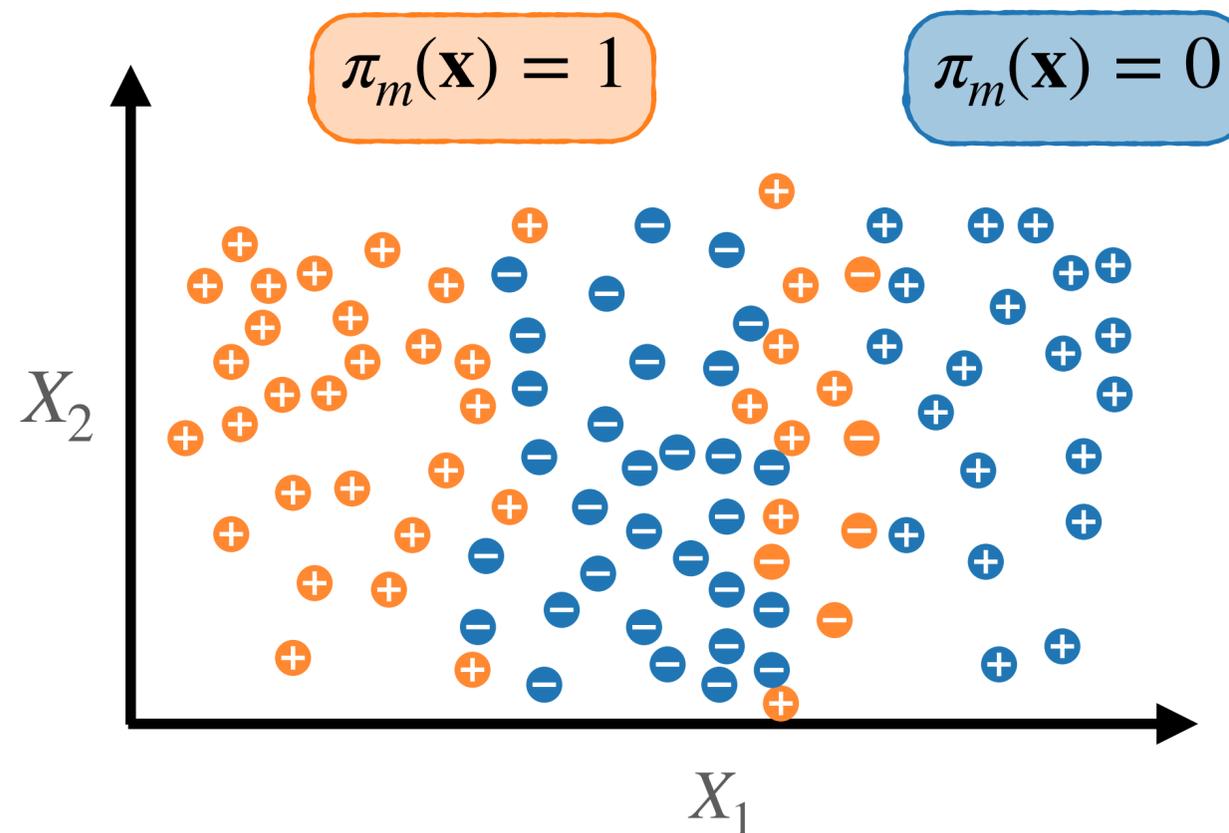


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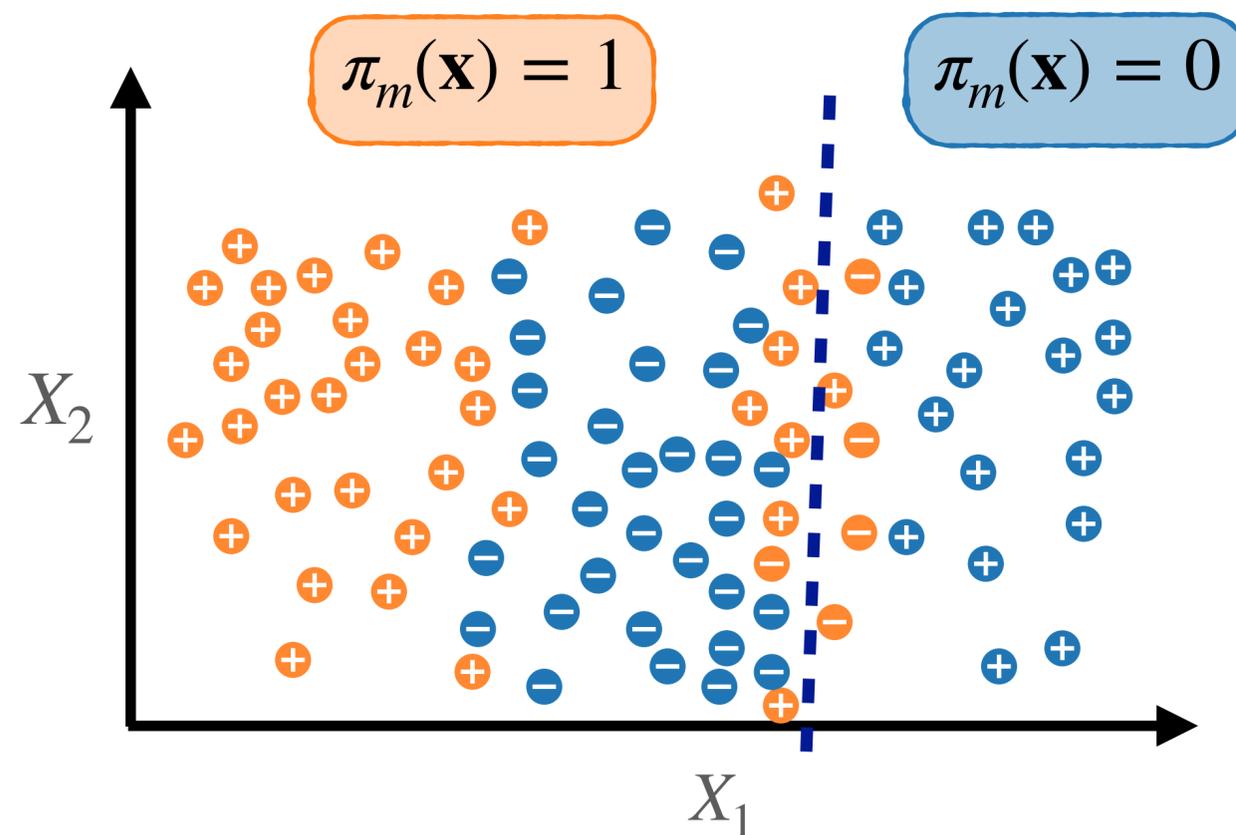


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The machine is only trained on the samples for which  $\pi_m(\mathbf{x}) = 0$ .



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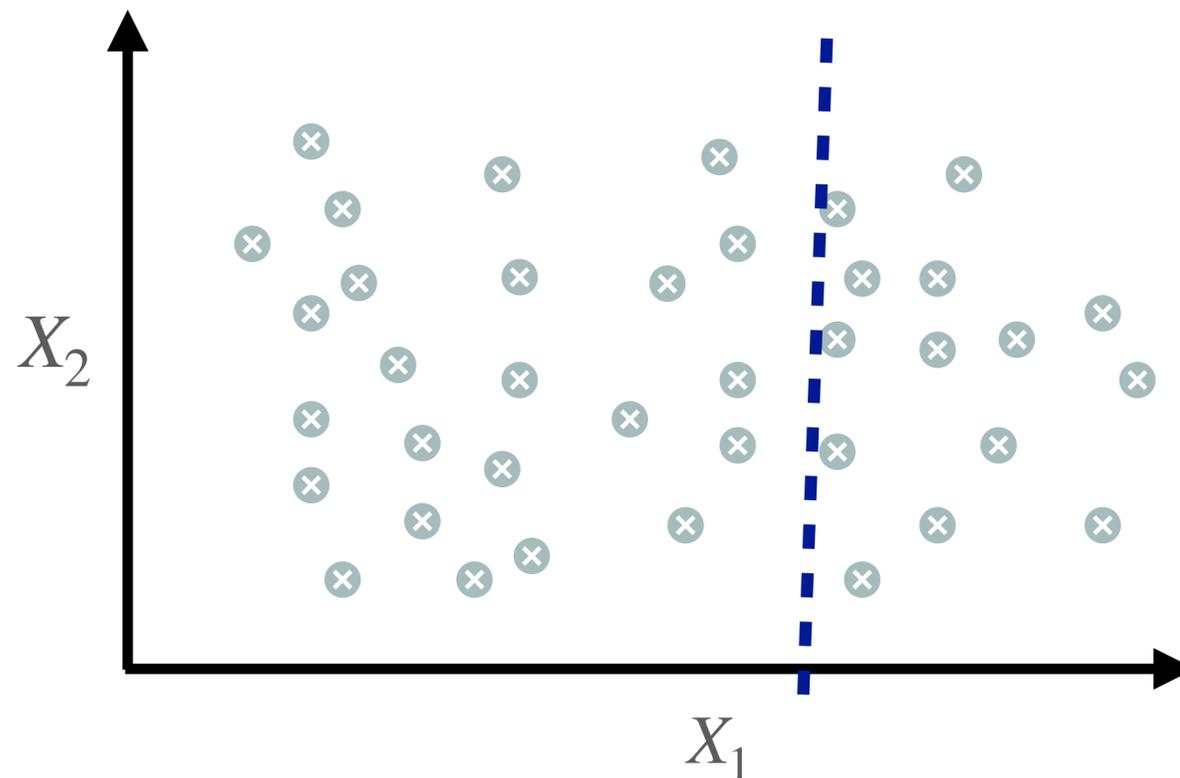
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An **unseen sample** is predicted by either the **human** or the **machine**.



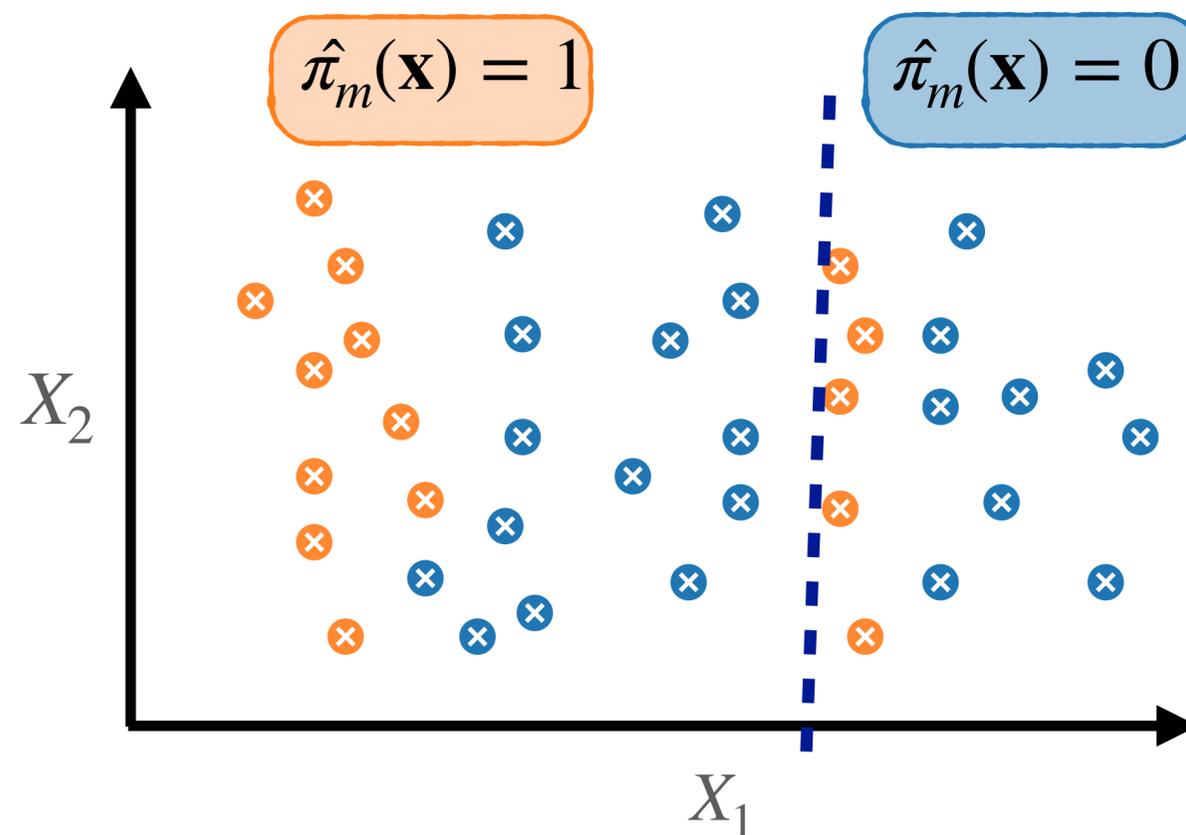
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When is a machine **trained under full automation suboptimal** given a desired level of triage?

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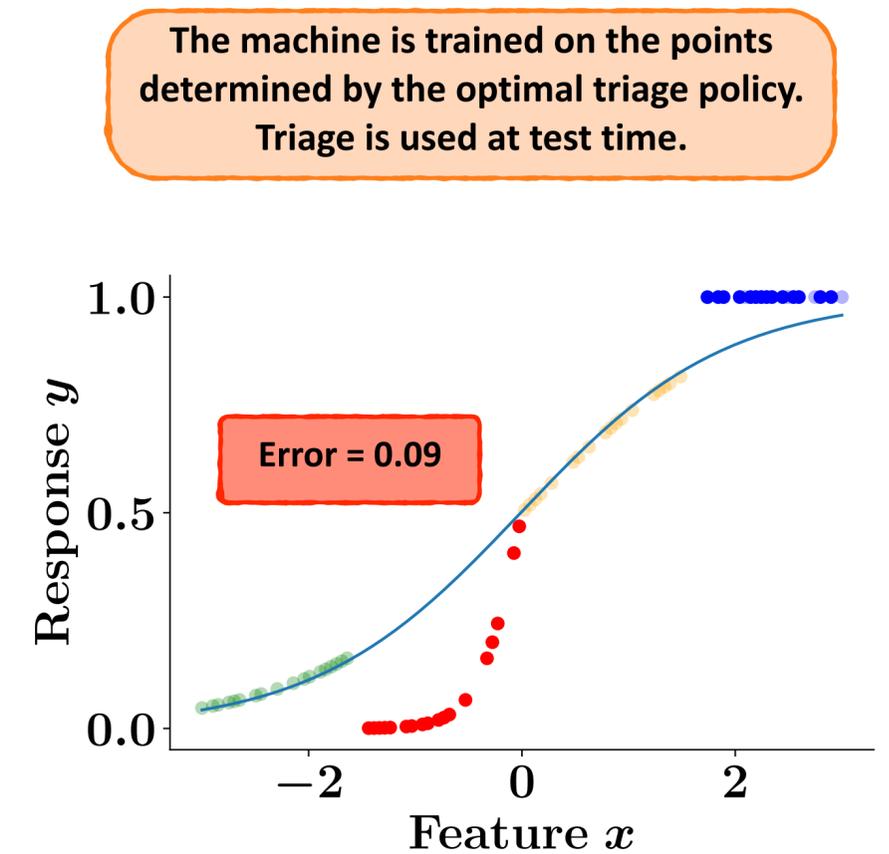
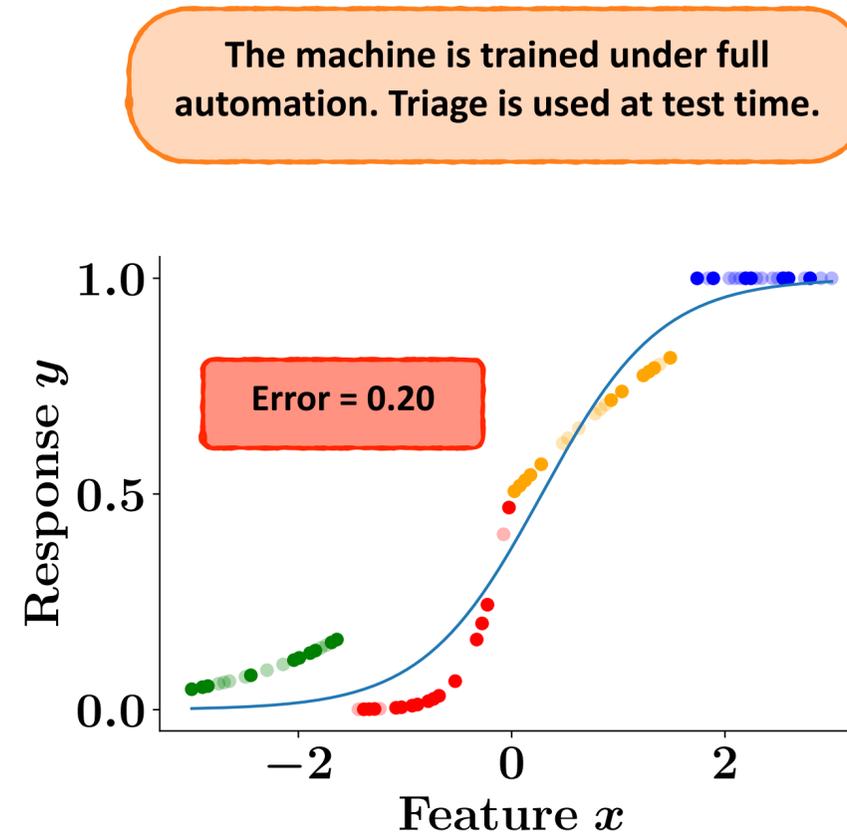
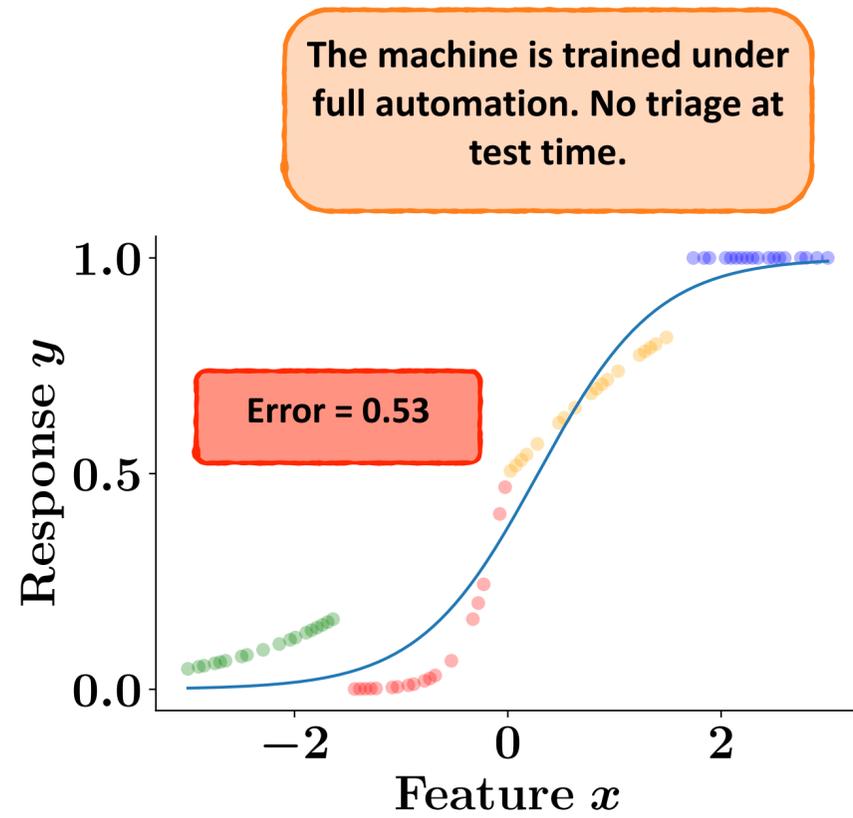
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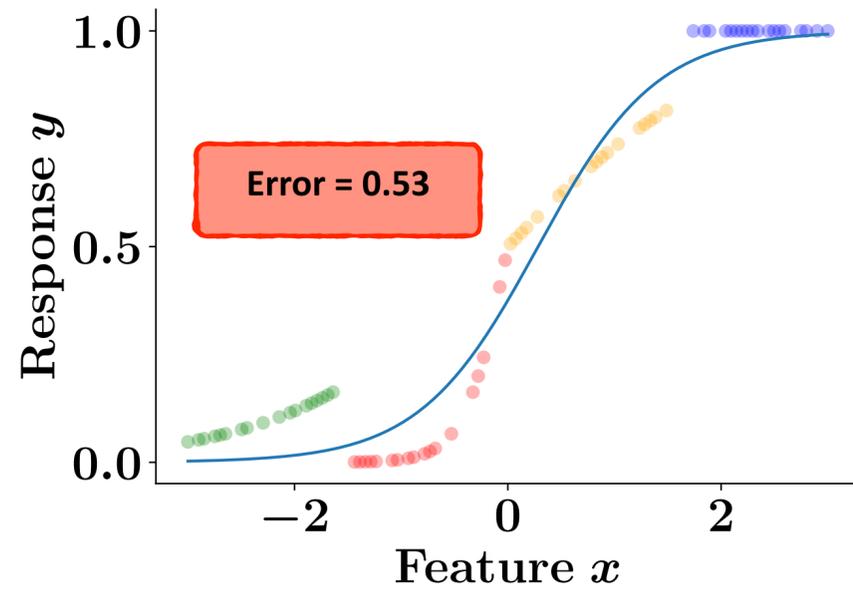
Is there a **scalable algorithm** for optimizing the machine under algorithmic triage?

# ALGORITHMIC TRIAGE IS BENEFICIAL!



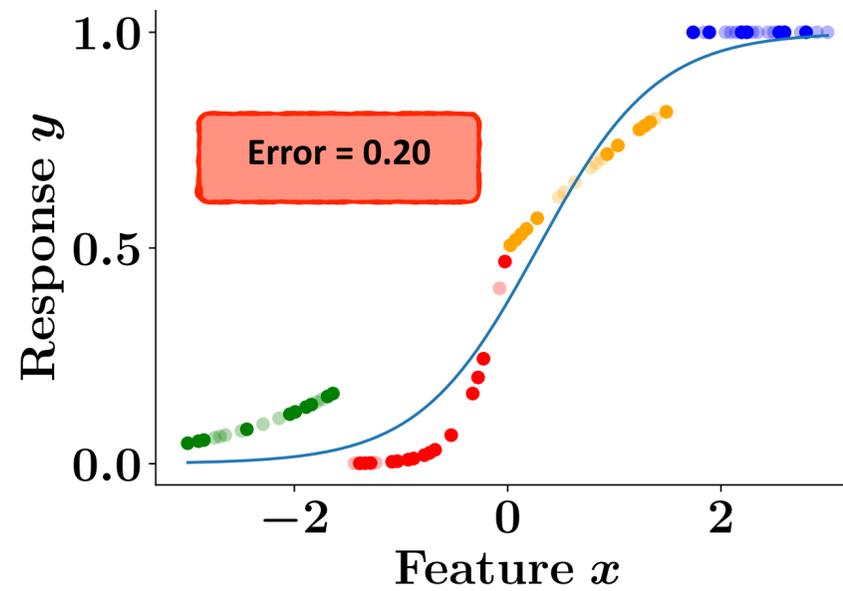
# ALGORITHMIC TRIAGE IS BENEFICIAL!

The machine is trained under full automation. No triage at test time.

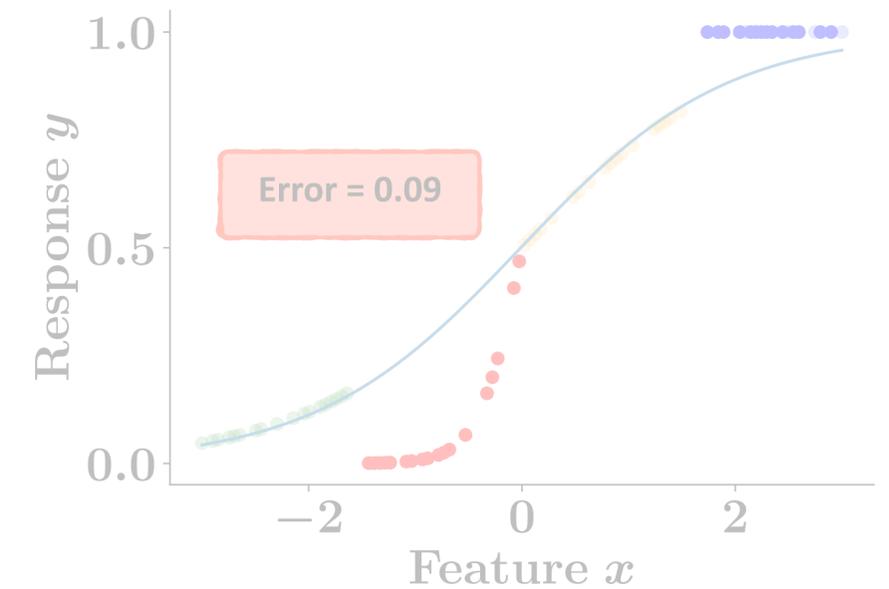


Error reduced by 62%!

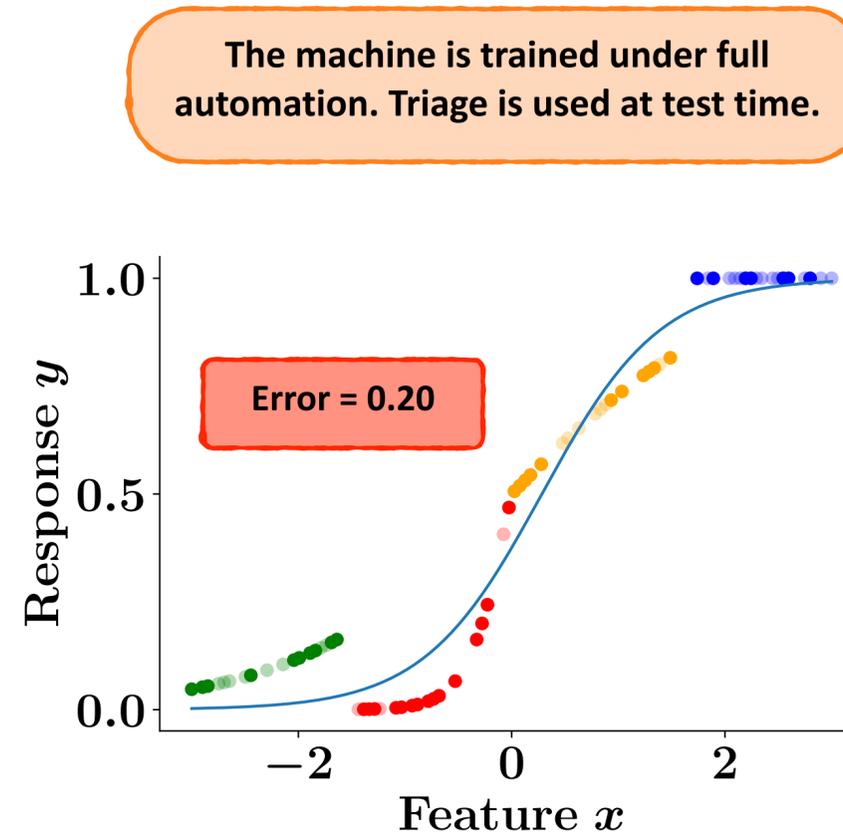
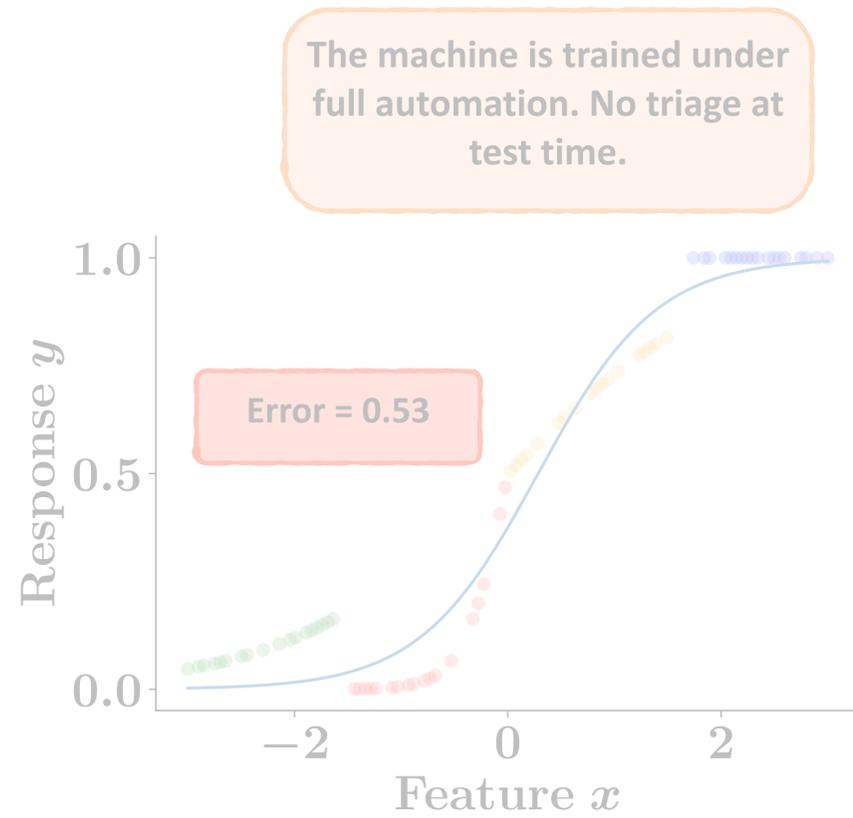
The machine is trained under full automation. Triage is used at test time.



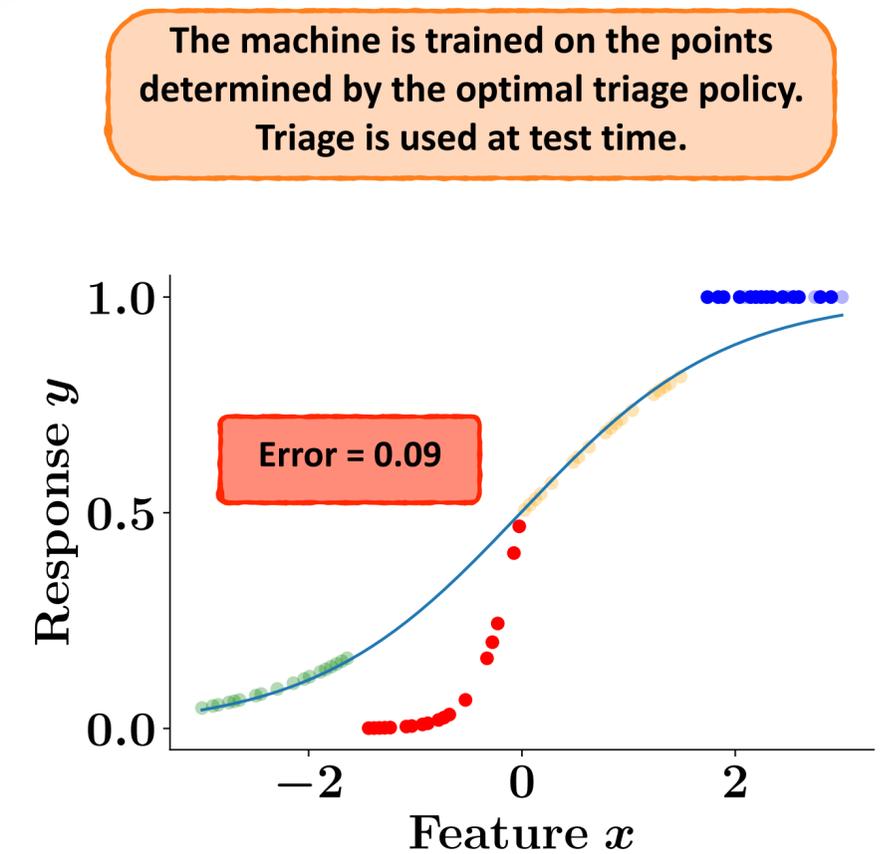
The machine is trained on the points determined by the optimal triage policy. Triage is used at test time.



# ALGORITHMIC TRIAGE IS BENEFICIAL!

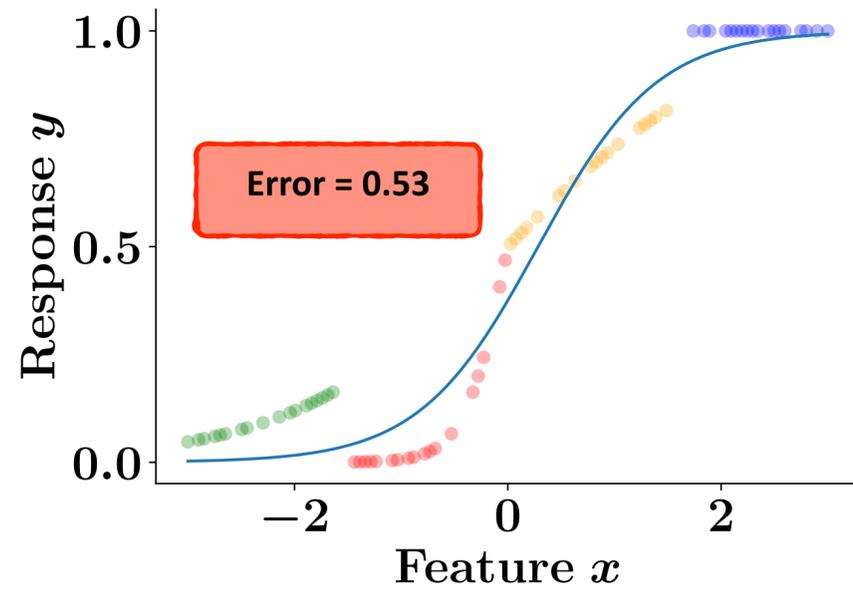


**Error reduced by 55%!**



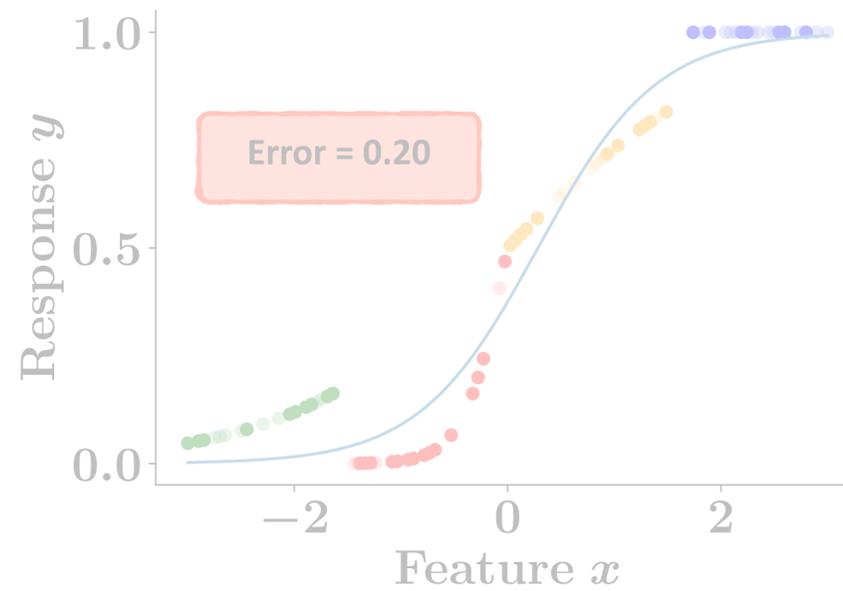
# ALGORITHMIC TRIAGE IS BENEFICIAL!

The machine is trained under full automation. No triage at test time.

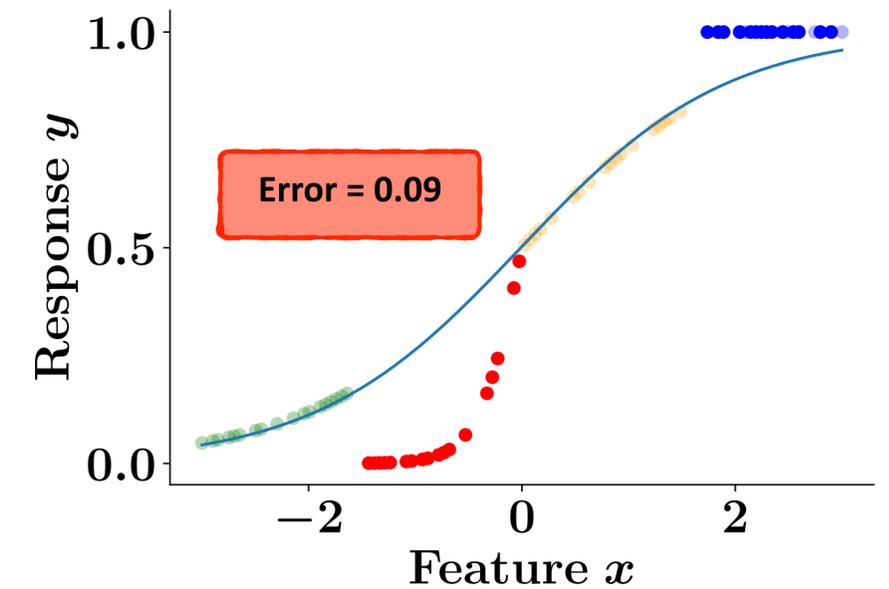


Error reduced by 83%!

The machine is trained under full automation. Triage is used at test time.

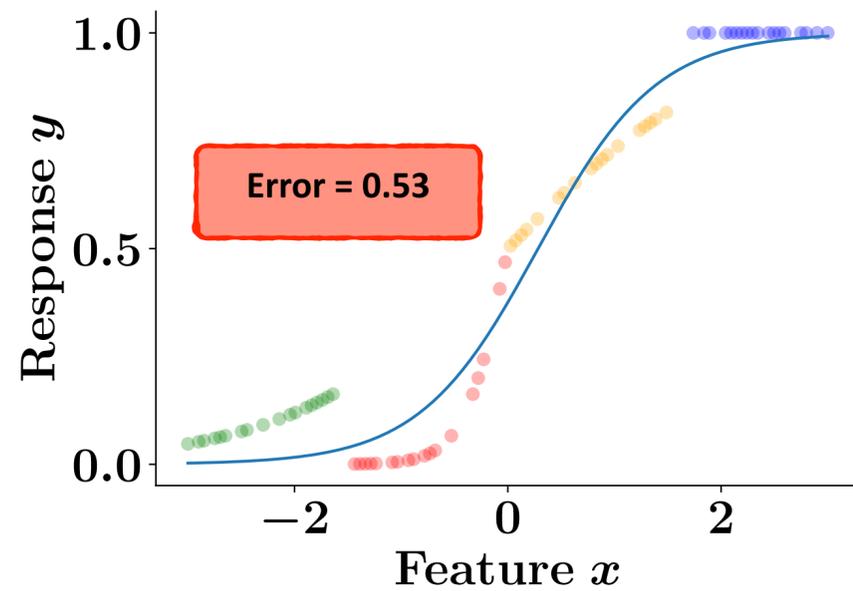


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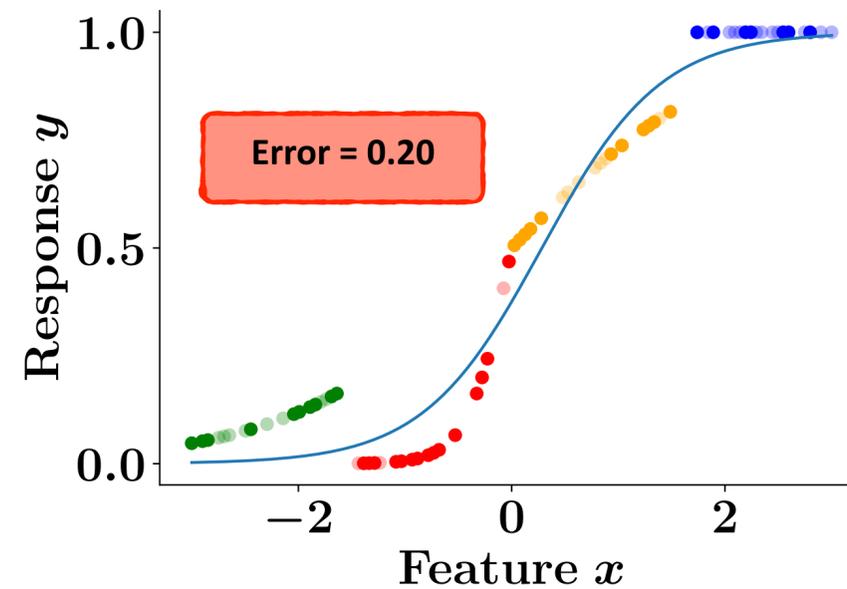
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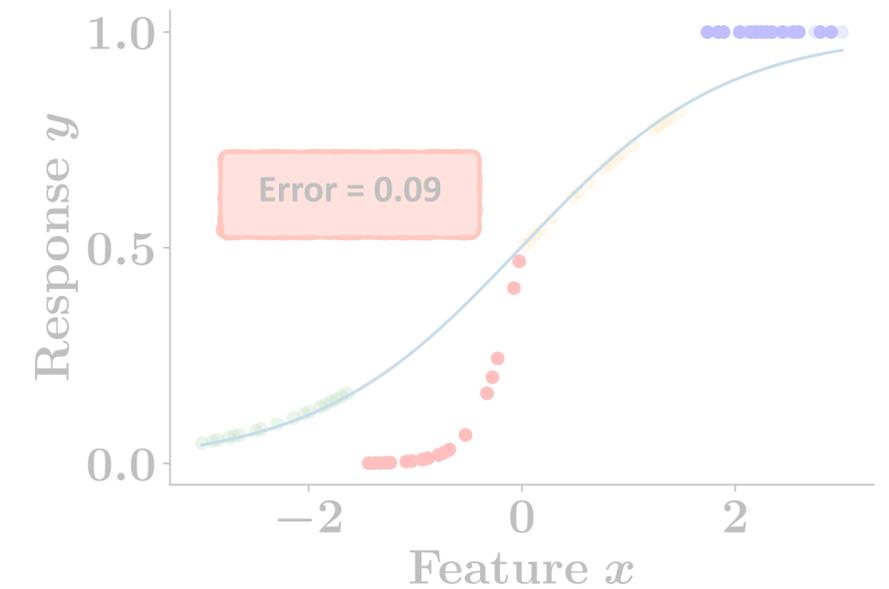


As long as there exists a subset of samples on which human has better performance than machine, triage is beneficial! (Proposition 2)

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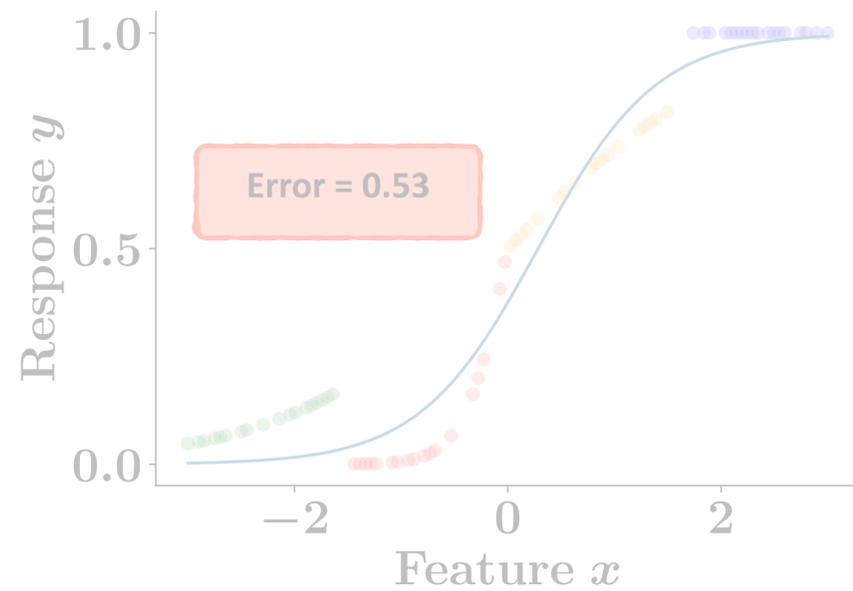


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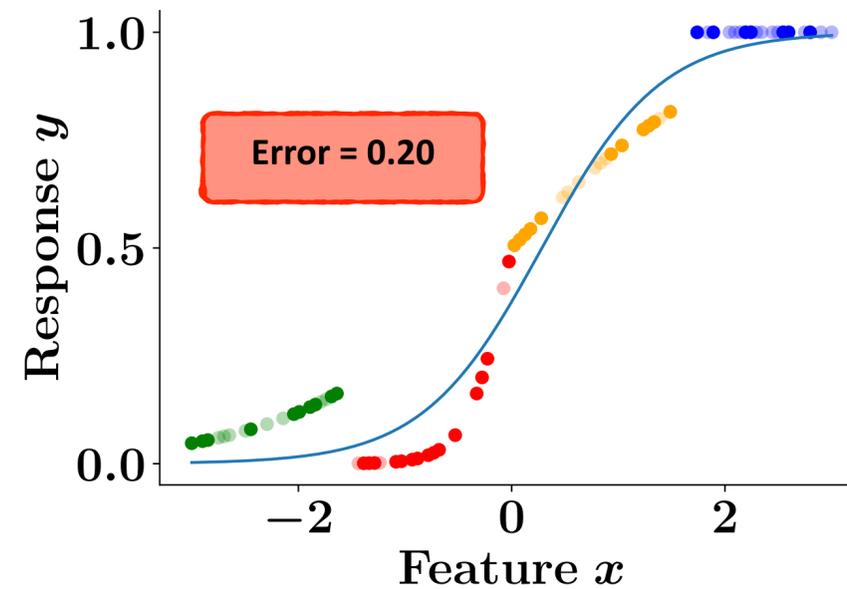
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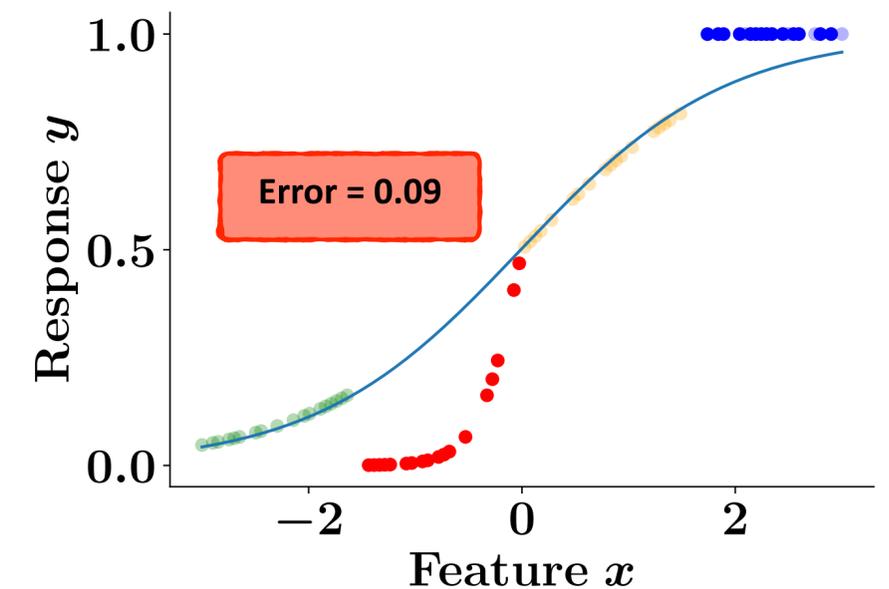
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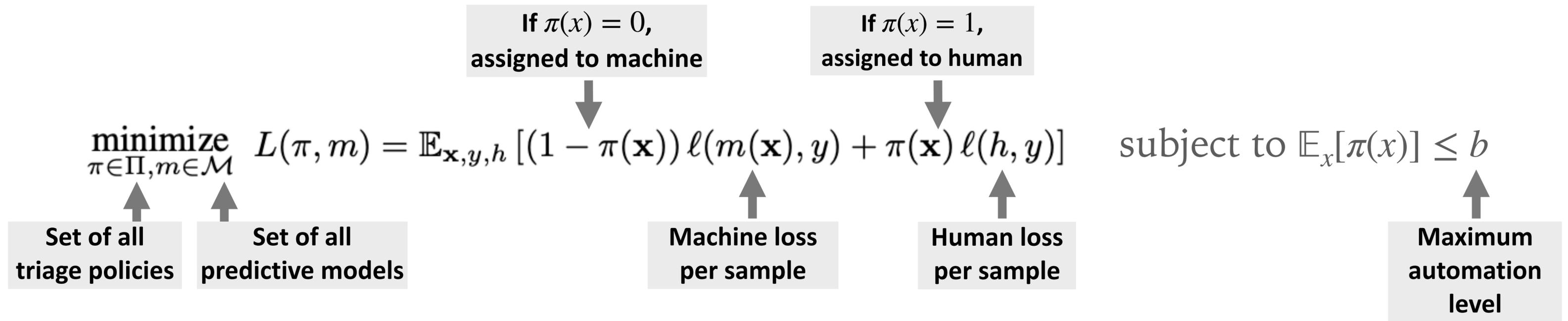
As long as the machine trained under full automation is not able to perfectly predict the points which are assigned to human, we benefit from training and testing the machine model under triage (Proposition 4).

The machine is trained on the points determined by the optimal triage policy. Triage is used at test time.



# SUPERVISED LEARNING UNDER TRIAGE

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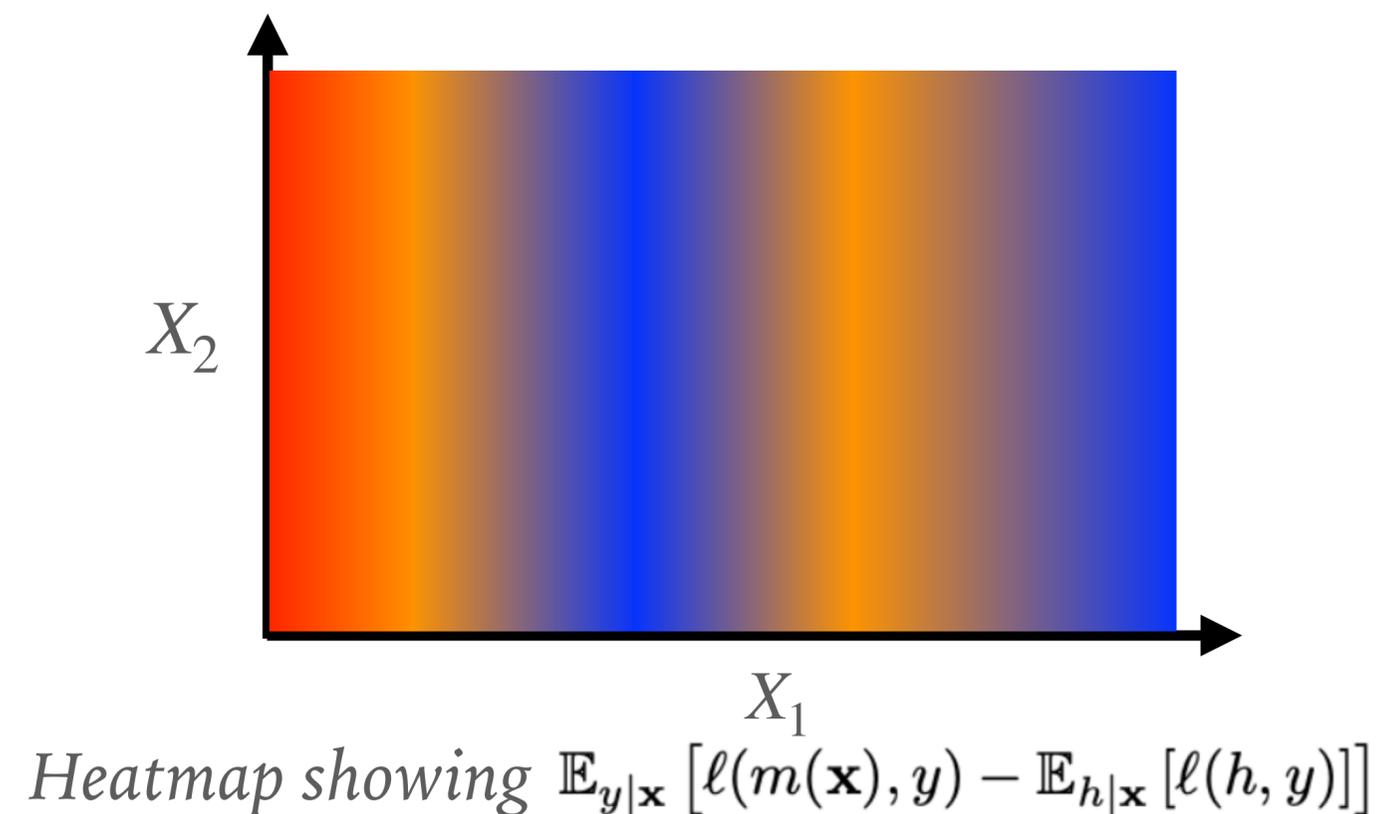
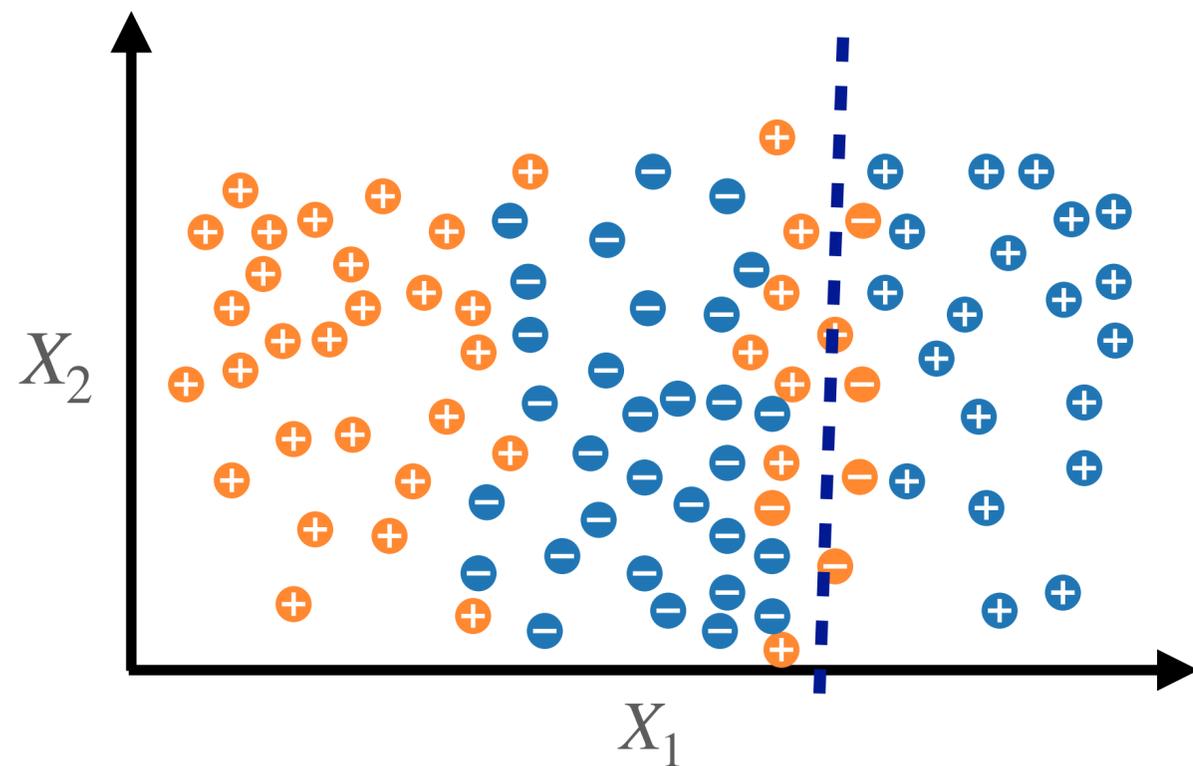


- $\pi(\mathbf{x}) : \mathcal{X} \rightarrow \{0, 1\}$ : the triage policy
- $m(\mathbf{x}) : \mathcal{X} \rightarrow \mathcal{Y}$ : the predictive model

# WHAT IS THE OPTIMAL TRIAGE POLICY?

- A **deterministic threshold rule** on the difference between the model and human loss on a per instance level:

$$\pi_{m,b}^*(\mathbf{x}) = \begin{cases} 1 & \text{if } \mathbb{E}_{y|\mathbf{x}} [\ell(m(\mathbf{x}), y) - \mathbb{E}_{h|\mathbf{x}} [\ell(h, y)]] > t_{P,b,m} \\ 0 & \text{otherwise,} \end{cases}$$

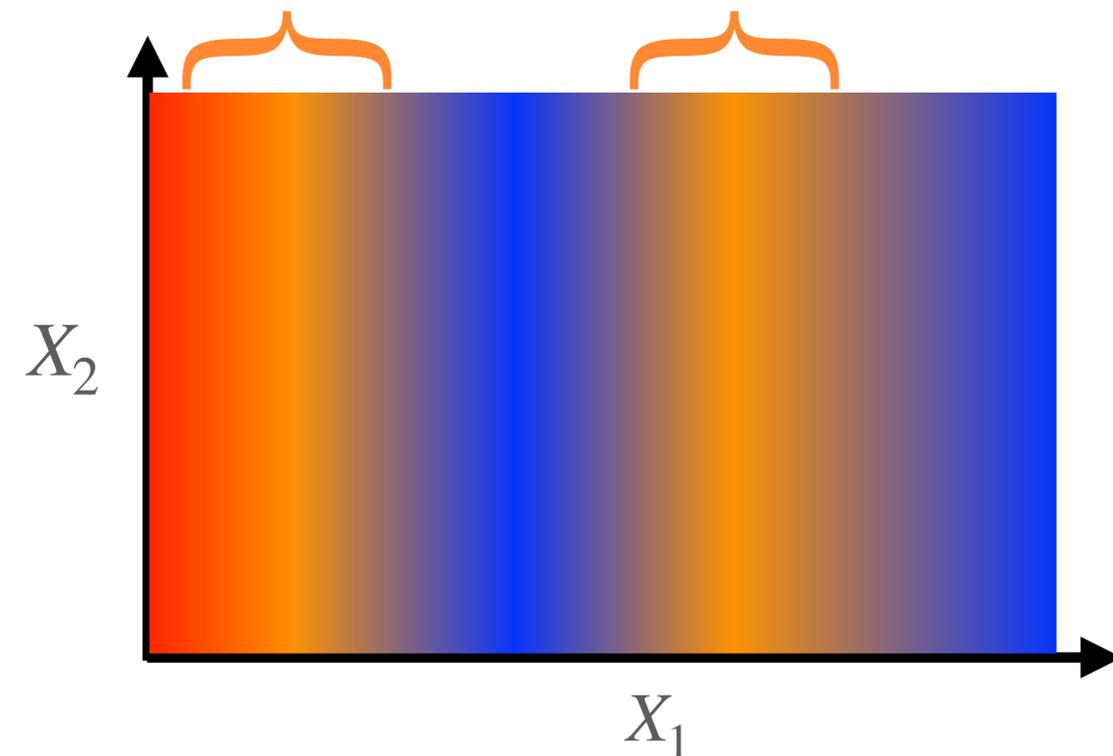
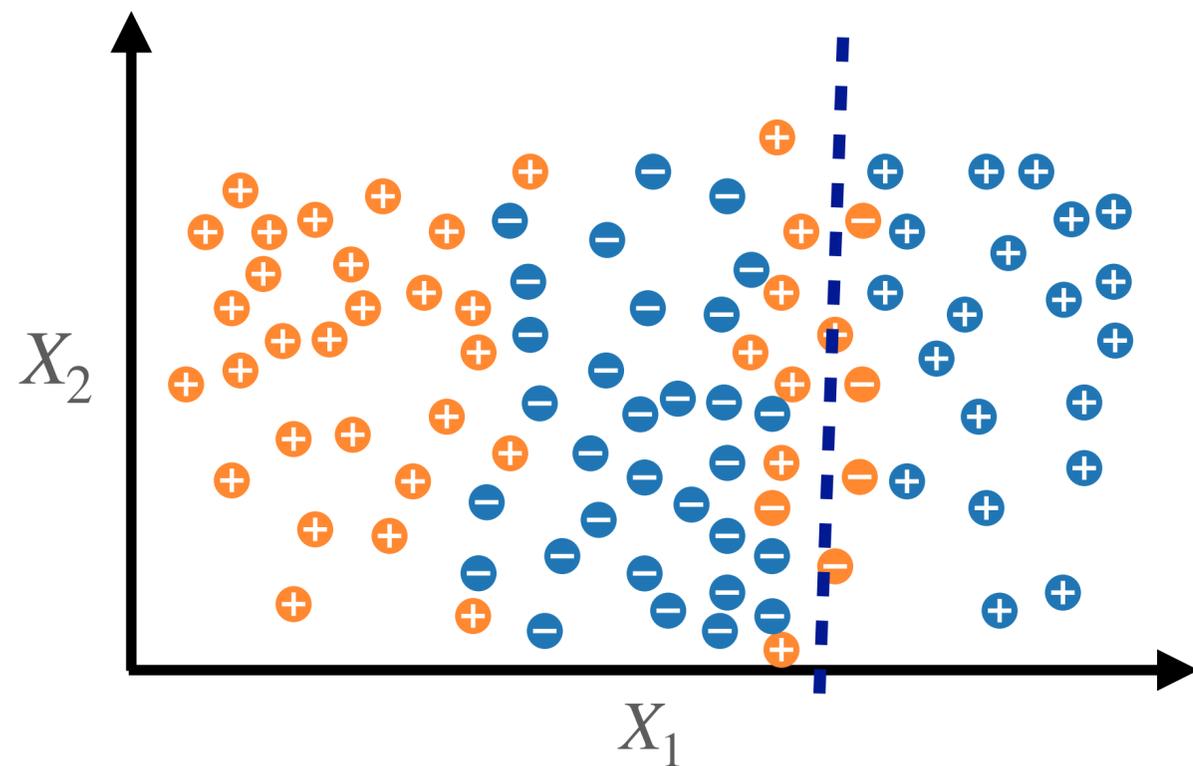


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$$\pi_m(\mathbf{x}) = 1$$



Heatmap showing  $\mathbb{E}_{y|\mathbf{x}} [\ell(m(\mathbf{x}), y) - \mathbb{E}_{h|\mathbf{x}} [\ell(h, y)]]$

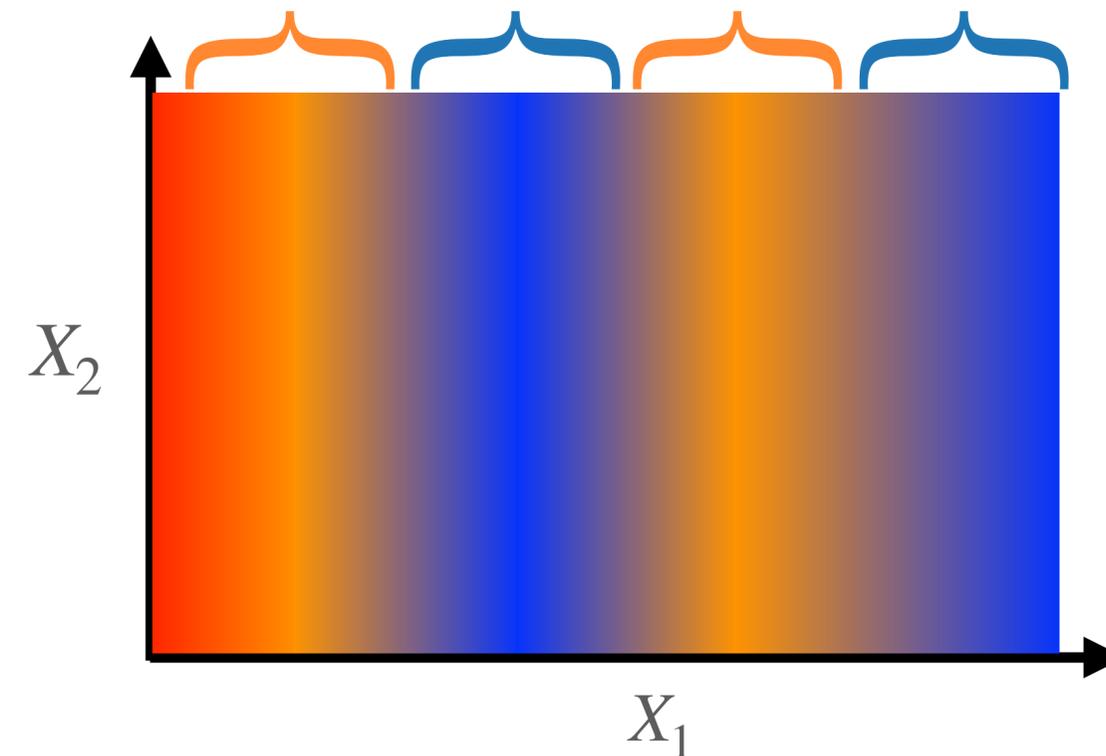
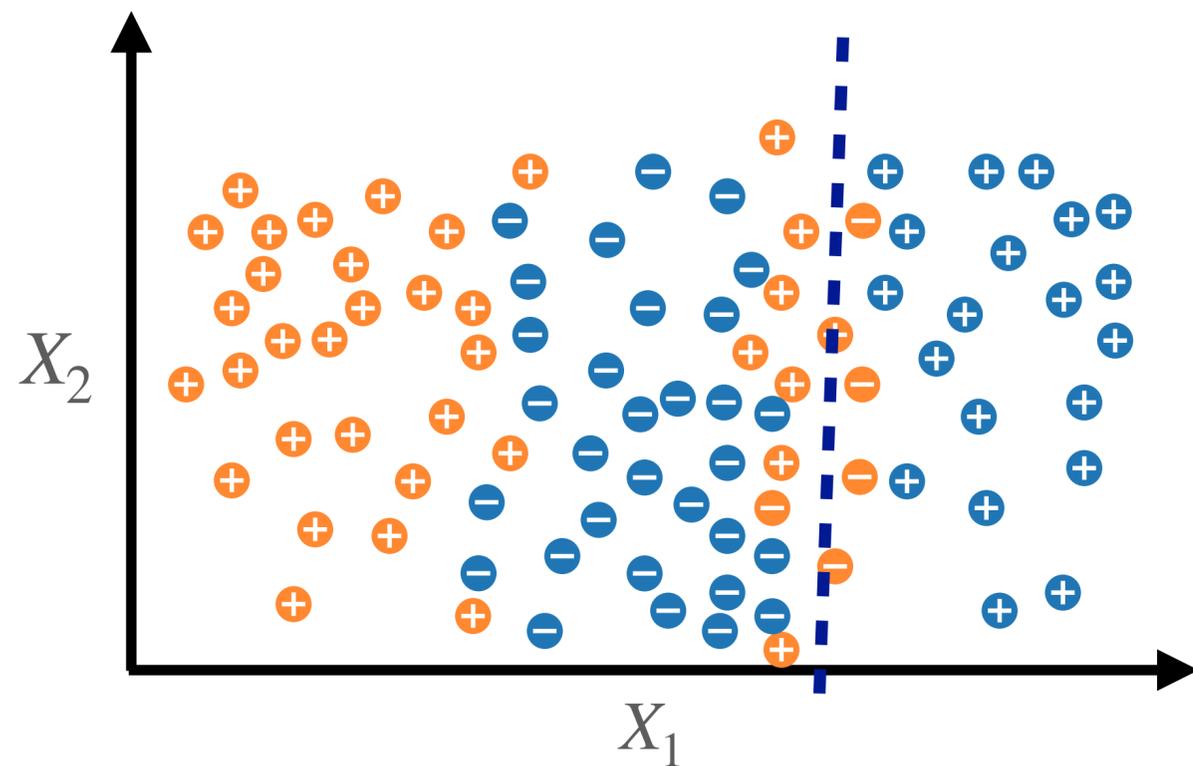
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# SIMPLE, SCALABLE, EASY TO IMPLEMENT ALGORITHM

---

**function** TRAINMODEL( $\theta'$ ,  $\mathcal{D}$ ,  $M$ ,  $B$ ,  $b$ ,  $\alpha$ )

$\theta^{(0)} \leftarrow \theta'$

**for**  $i = 0, \dots, M - 1$  **do**

$\mathcal{D}^{(i)} \leftarrow$  the  $i$ 'th mini batch of  $\mathcal{D}$

$\mathcal{D}^{(i)} \leftarrow$  TRIAGE( $\mathcal{D}^{(i)}$ ,  $b$ ,  $\theta^{(i)}$ )

$\nabla \leftarrow 0$

**for**  $(\mathbf{x}, y, h) \in \mathcal{D}^{(i)}$  **do**

$\nabla \leftarrow \nabla + \nabla_{\theta} \ell(m_{\theta}(\mathbf{x}), y)|_{\theta=\theta^{(i)}}$

$\theta^{(i+1)} \leftarrow \theta^{(i)} - \alpha \frac{\nabla}{B}$

**return**  $\theta^{(M)}$

The machine model using the gradients of the points for which

$$\pi_{m_{\theta^{(i)}}}(\mathbf{x}) = 0.$$

For each mini-batch:

Use the optimal triage policy to find those samples inside the current batch for which

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} *Repeat for T time steps*

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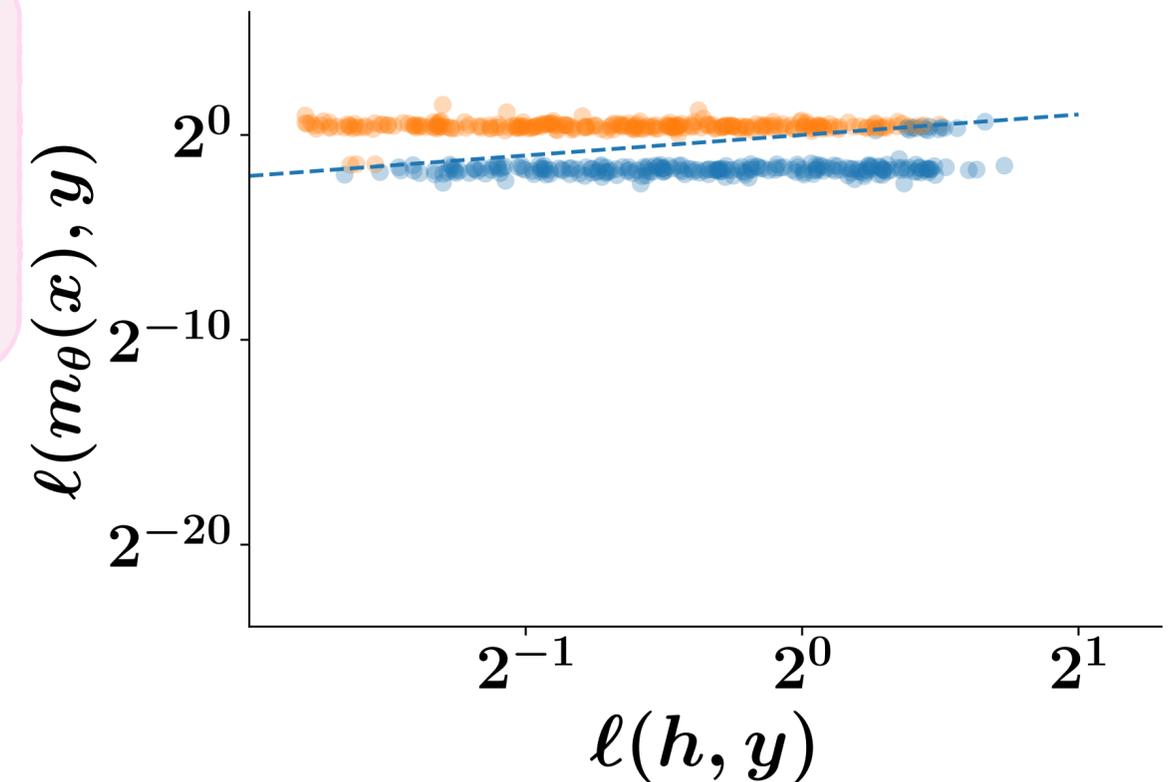
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**T=1**



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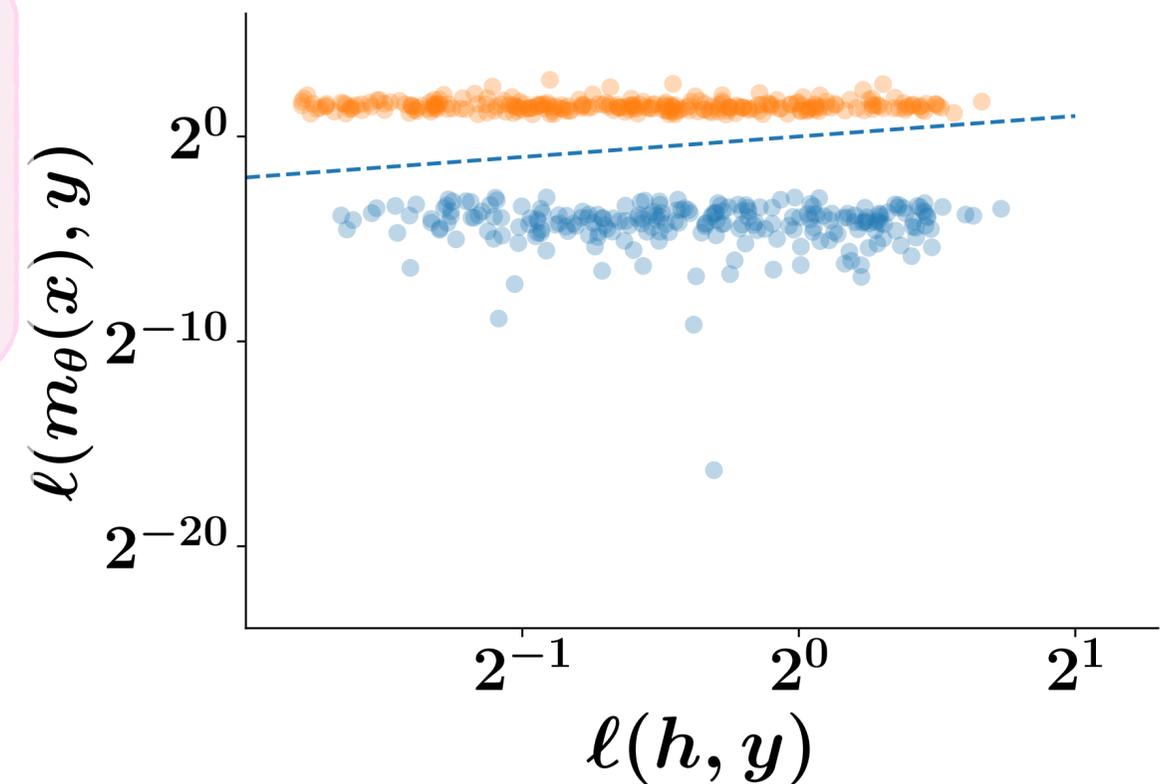
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**T=2**



# SIMPLE, SCALABLE, EASY TO IMPLEMENT ALGORITHM

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**return**  $\theta^{(M)}$

The machine model using the gradients of the points for which

$$\pi_{m_{\theta^{(i)}}}(\mathbf{x}) = 0.$$

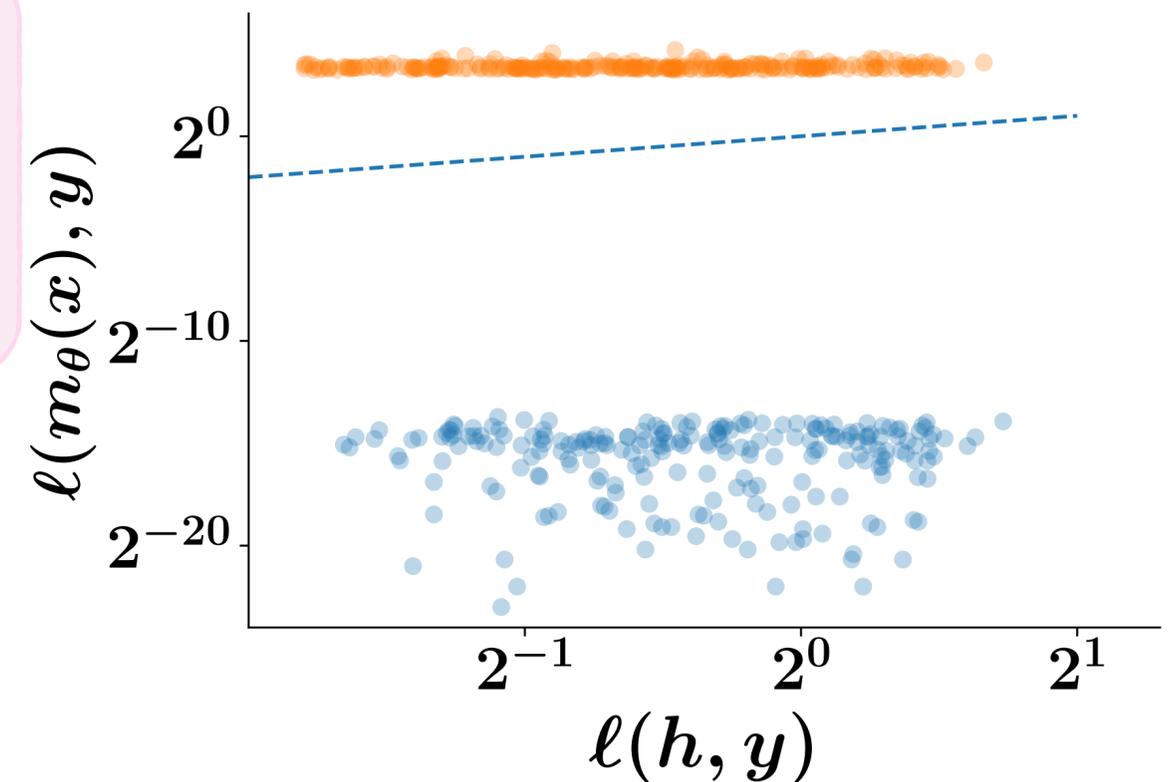
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**T=3**



# SIMPLE, SCALABLE, EASY TO IMPLEMENT ALGORITHM

```
function TRAINMODEL( $\theta'$ ,  $\mathcal{D}$ ,  $M$ ,  $B$ ,  $b$ ,  $\alpha$ )
```

```
 $\theta^{(0)} \leftarrow \theta'$ 
```

```
for  $i = 0, \dots, M - 1$  do
```

```
 $\mathcal{D}^{(i)} \leftarrow$  the  $i$ 'th mini batch of  $\mathcal{D}$ 
```

```
 $\mathcal{D}^{(i)} \leftarrow$  TRIAGE( $\mathcal{D}^{(i)}$ ,  $b$ ,  $\theta^{(i)}$ )
```

```
 $\nabla \leftarrow 0$ 
```

```
for  $(\mathbf{x}, y, h) \in \mathcal{D}^{(i)}$  do
```

```
 $\nabla \leftarrow \nabla + \nabla_{\theta} \ell(m_{\theta}(\mathbf{x}), y)|_{\theta=\theta^{(i)}}$ 
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```
 $\theta^{(i+1)} \leftarrow \theta^{(i)} - \alpha \frac{\nabla}{B}$ 
```

```
return  $\theta^{(M)}$ 
```

The machine model using the gradients of the points for which

$$\pi_{m_{\theta^{(i)}}}(\mathbf{x}) = 0.$$

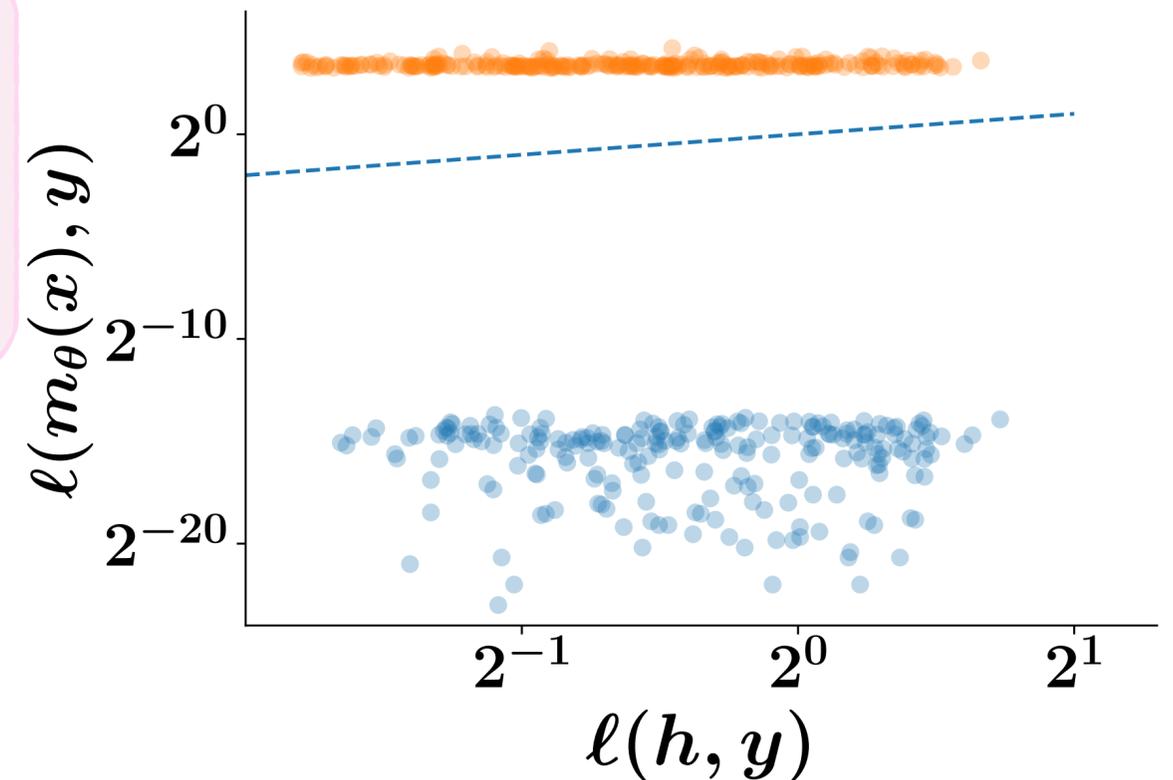
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## T=3

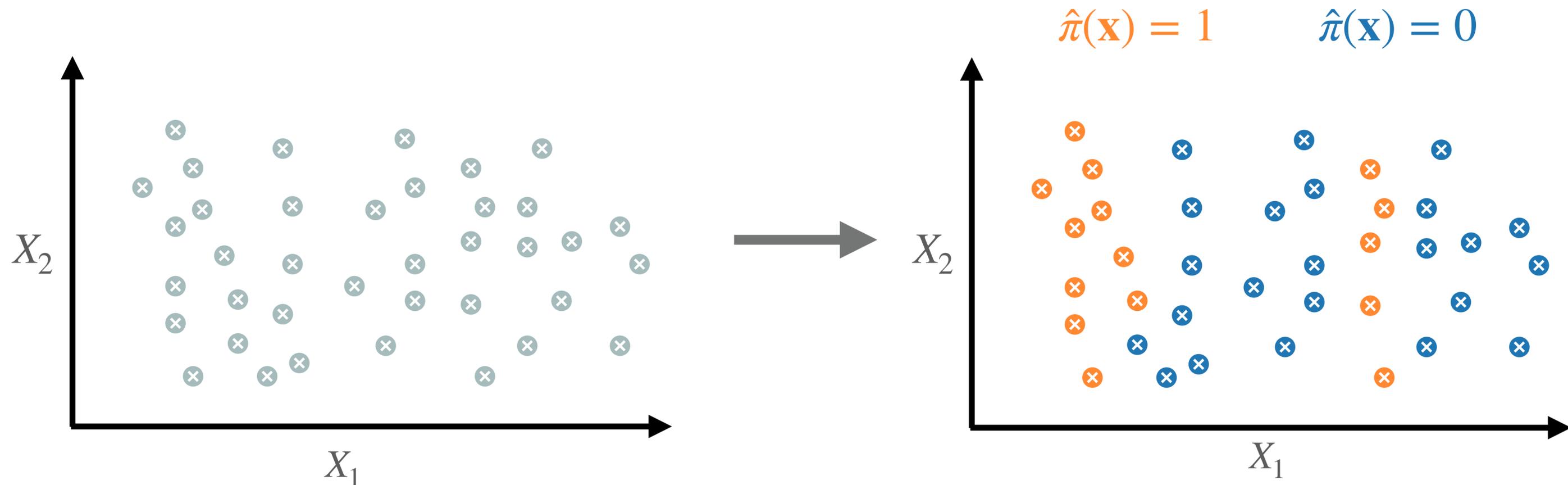


Later into the training process, the predictive model focuses on predicting more accurately the samples that the triage policy hands in to the model.

# HOW TO ASSIGN SAMPLES DURING TEST TIME?

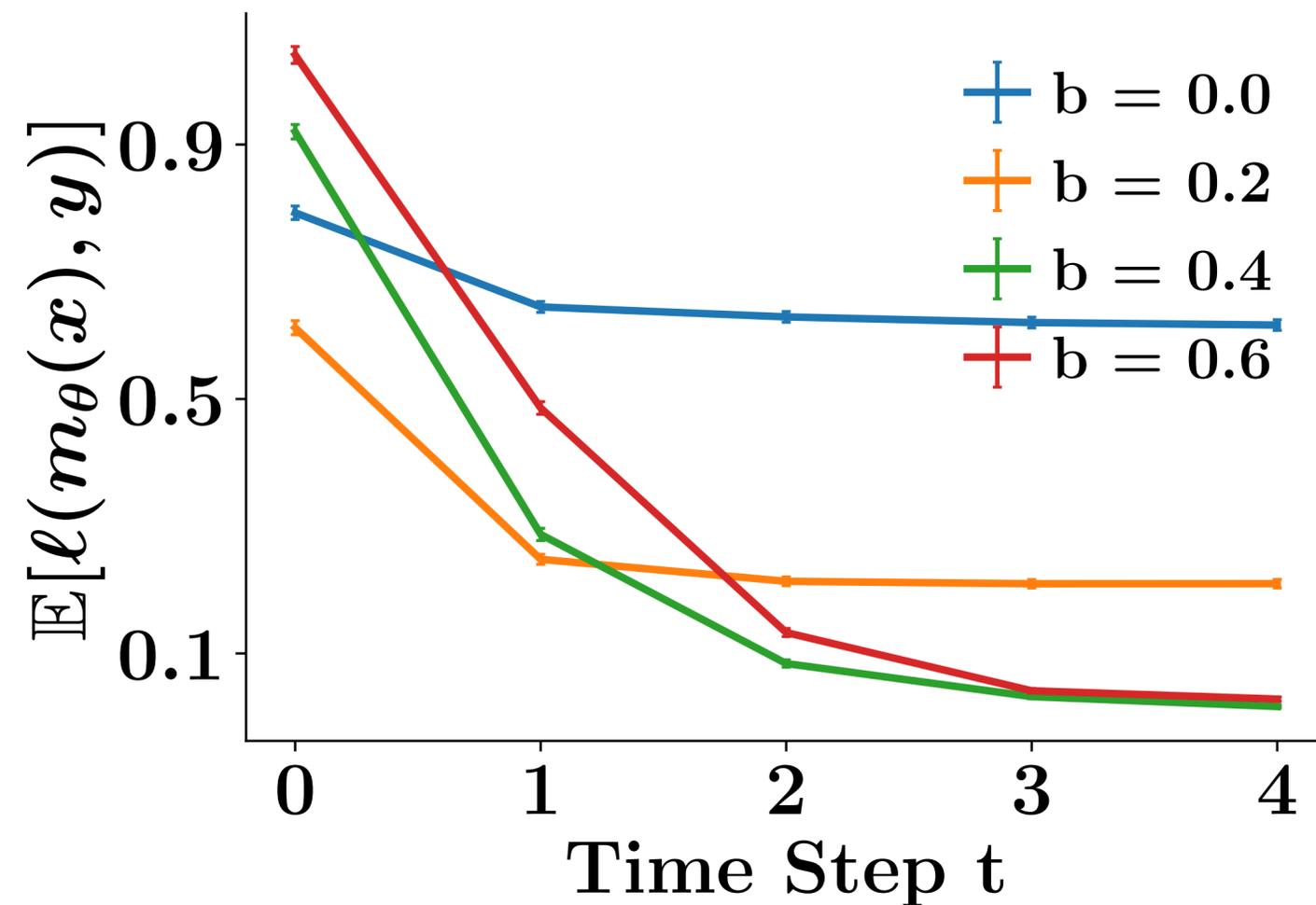
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- ▶ We do not observe the true label and the human prediction at test time.
- ▶ We cannot compute the optimal triage policy at test time since it depends on the true label.
- ▶ **Solution:** train a parametrised triage policy to **approximate the optimal triage policy**.



# HOW DOES TRAINING PERFORMANCE CHANGE UNDER DIFFERENT AUTOMATION LEVELS?

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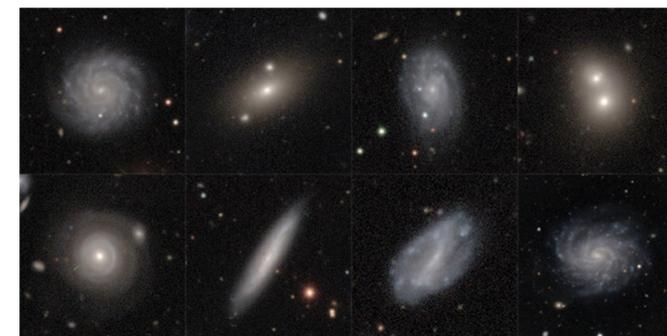
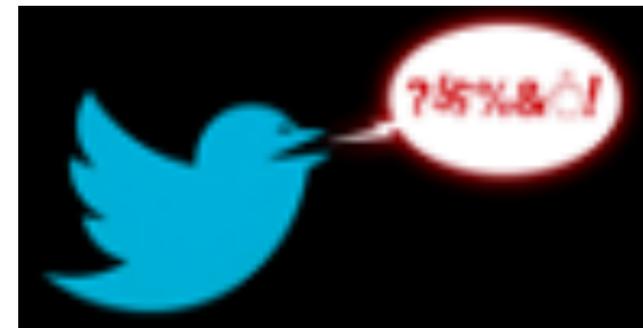
The model is generalising across a large portion of the feature space incurring high error.

The models trained under higher levels of triage need to generalise across a smaller region of the feature space and achieve much lower error.

# EXPERIMENTS

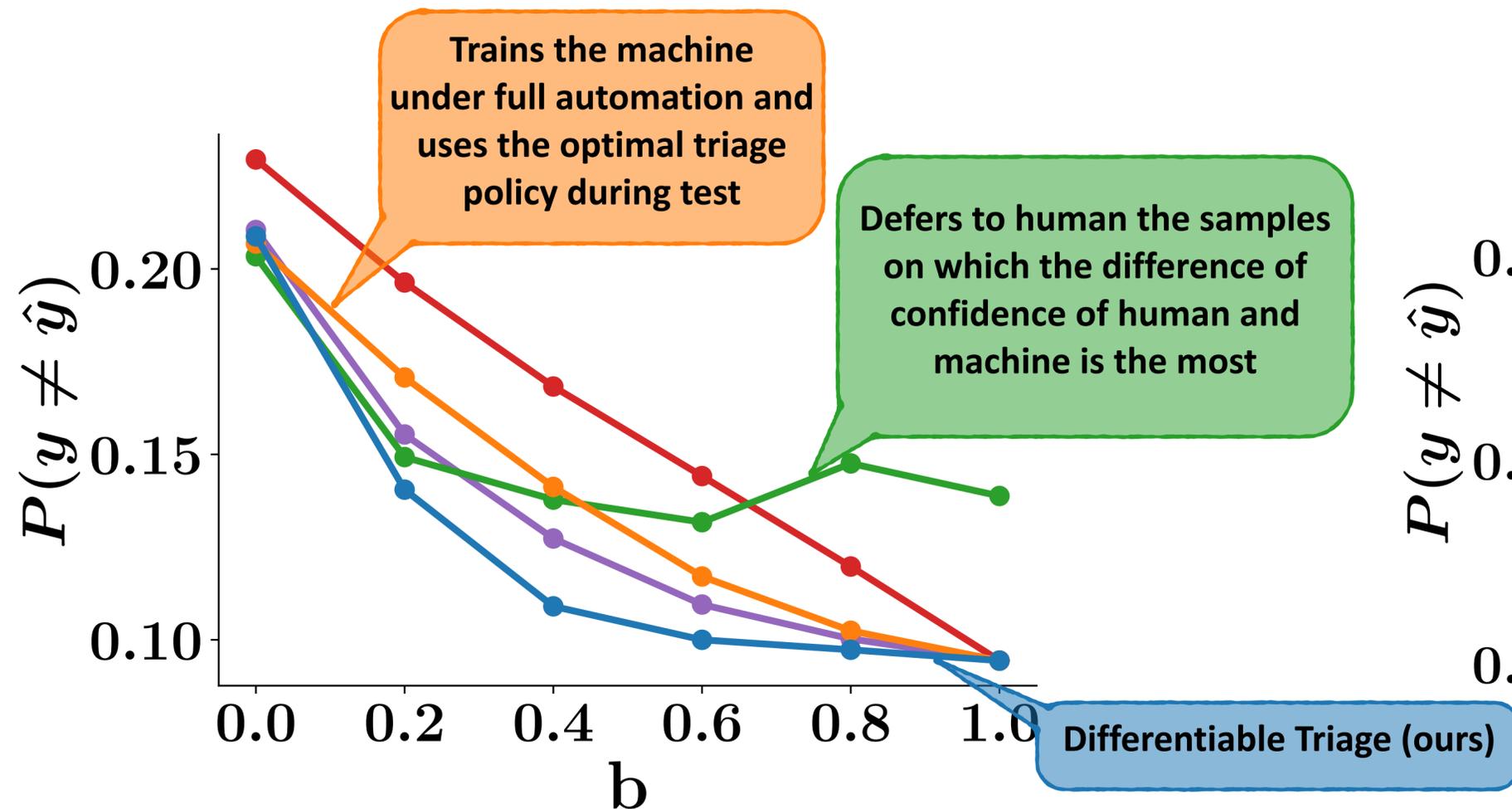
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- Few public dataset with **several human predictions per instance**, necessary to estimate the human loss per instance.
- Hatespeech:
  - 25k tweets
  - Each tweet labeled by 3-5 annotator
  - Labels = {hatespeech, offensive, neither}
- Galaxy-zoo:
  - 10k images
  - Each image labelled by 30+ humans
  - Labels = {early-type, spiral}

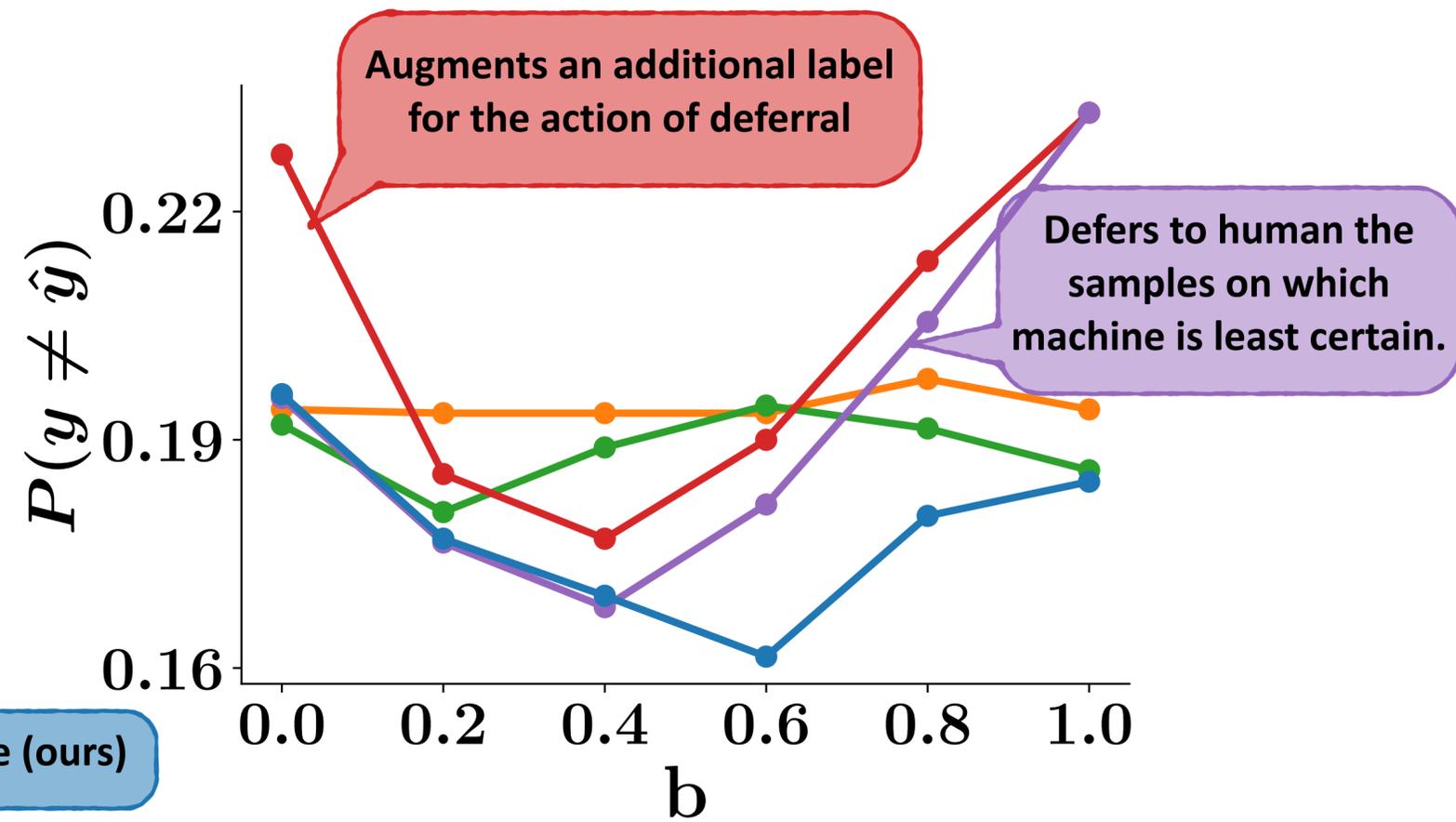


# AVERAGE TEST MISCLASSIFICATION ERROR

- Differentiable Triage (ours)
- Confidence-based Triage
- Score-based Triage
- Full Automation Triage
- Surrogate-based Triage



Hatespeech Dataset



Galaxy-zoo Dataset

# CONCLUSION

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- We have contributed towards a better understanding of **supervised learning under algorithmic triage**.
- We have designed a **gradient-based algorithm** for the task of supervised learning under algorithmic triage that is:
  - Easy to implement
  - Is applicable to any differentiable machine learning model
  - Does not increase the complexity of the vanilla SGD
  - Is guaranteed to converge to a local minima