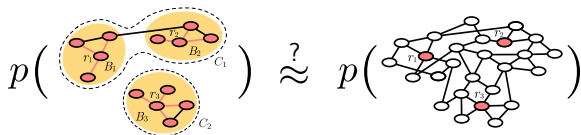
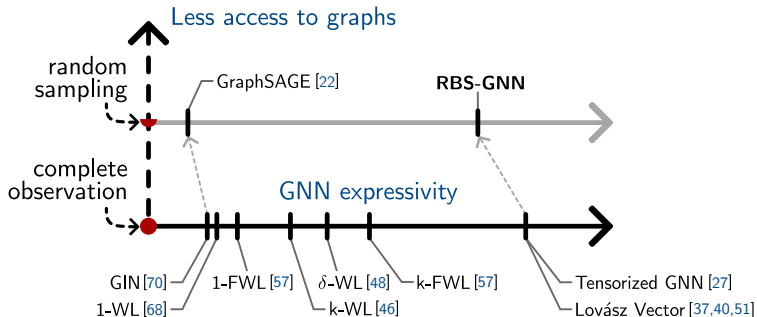


Learning on Random Balls is Sufficient for Estimating (Some) Graph Parameters



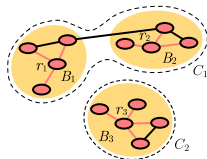
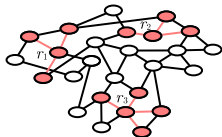
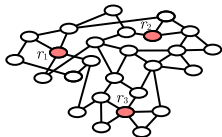
Takanori Maehara & Hoang NT
Facebook AI & Tokyo Tech/RIKEN AIP

35th NeurIPS, December, 2021



! Additional dimensionality to the discussion: What if we do not have complete observations over the graphs?

We study the following computational model, which can be found in large-scale systems (or methods like GraphSAGE).



Step 1: Sample random roots ▶ Step 2: Sample random neighbors ▶ Step 3: Get induced subgraphs and connected components

! **RBS-GNN** is defined to be the class of universal GNNs which takes Step 3 as input.

! Computational model defines a notion of *continuity* in the space of all graphs.

Theorem 1 (RBS-GNN Universality)

If a graph parameter $p : \mathcal{G} \rightarrow \mathbb{R}$ is estimable (in the random neighborhood computational model), then it is estimable by a RBS-GNN.

! This theorem connects GNN literature and graph property testing literature. Furthermore, we define the following distance:

$$d(G, H) = \sum_{r=1}^{\infty} 2^{-r} d_{TV}(z_r(G), z_r(H)). \quad (1)$$

Theorem 2 (Estimable iff Continuous)

Graph parameter p is estimable iff continuous w.r.t. the distance defined by Equation 1.

Example 3 (Estimable Parameters)

Edge density, triangle density, and the local clustering coefficient are estimable.

Example 4 (Non-estimable Parameters)

Connectivity, number of connected components, and min/max-degrees are non-estimable.

! Theorem 2 can be used to prove a parameter is estimable or not using continuity.

Theorem 5

Estimable functions are size-generalizable in the approximation-theoretic sense.

! Theorem 2 can also prove the main theorem of GraphSAGE:

Lemma 6

The mini-batch version of the GraphSAGE can estimate the local clustering coefficient.

! See our manuscript for other results on size-generalization by domain adaptation and non-universal RBS-GNN.

Thank you for listening!

