An Infinite-Feature Extension for Bayesian ReLU Nets That Fixes Their Asymptotic Overconfidence

Agustinus Kristiadi, Matthias Hein, Philipp Hennig

SPONSORED BY THE







NNs with ReLU activation are asymptotically overconfident

NNs with ReLU activation are asymptotically overconfident

Bayesian treatment mitigates this to some degree

- NNs with ReLU activation are asymptotically overconfident
- Bayesian treatment mitigates this to some degree
- But previous result:
 - only shows this for binary classification and
 - doesn't achieve the ideal maximum uncertainty even in the limit

- NNs with ReLU activation are asymptotically overconfident
- Bayesian treatment mitigates this to some degree
- But previous result:
 - only shows this for binary classification and
 - doesn't achieve the ideal maximum uncertainty even in the limit
- ► We:
 - propose an extension to multi-class ReLU BNNs,
 - which is guaranteed to be maximally uncertain far from the data

- NNs with ReLU activation are asymptotically overconfident
- Bayesian treatment mitigates this to some degree
- But previous result:
 - only shows this for binary classification and
 - doesn't achieve the ideal maximum uncertainty even in the limit
- ► We:
 - propose an extension to multi-class ReLU BNNs,
 - which is guaranteed to be maximally uncertain far from the data
- Moreover, the method is beneficial for the *non-asymptotic* uncertainty, without affecting the prediction

Problem with ReLU nets



• Point-estimation of a ReLU net f_{θ} is almost always overconfident¹

Problem with ReLU nets



- Point-estimation of a ReLU net f_{θ} is almost always overconfident¹
- Because
 - Far from the data, $f_{\theta_{MAP}}$ is linear²
 - So, given an input x and a scalar $\alpha > 0$, there is a class c s.t. $\lim_{\alpha \to \infty} \operatorname{softmax} (f_{\theta_{MAP}}(\alpha x)))_c = 1$

¹Hein et al., CVPR 2019 ²And non-constant

Bayesian ReLU nets

• Approximate instead the posterior $p(\theta \mid D) \approx \mathcal{N}(\mu, \Sigma) =: q(\theta)$

Bayesian ReLU nets

- Approximate instead the posterior $p(\theta \mid D) \approx \mathcal{N}(\mu, \Sigma) =: q(\theta)$
- Kristiadi et al. (ICML 2020) shows that¹

$$\lim_{\alpha\to\infty}p(y=1\mid \alpha x,\mathcal{D})\approx\lim_{\alpha\to\infty}\int \sigma\left(f_{\theta}(\alpha x)\right) q(\theta) d\theta < 1,$$

and the exact value depends on the eigenvalues of \varSigma

Bayesian ReLU nets

- Approximate instead the posterior $p(\theta \mid D) \approx \mathcal{N}(\mu, \Sigma) =: q(\theta)$
- Kristiadi et al. (ICML 2020) shows that¹

$$\lim_{\alpha \to \infty} p(y = 1 \mid \alpha x, \mathcal{D}) \approx \lim_{\alpha \to \infty} \int \sigma \left(f_{\theta}(\alpha x) \right) \, q(\theta) \, d\theta < 1,$$

and the exact value depends on the eigenvalues of \varSigma

But:

- This result is limited to binary classification
- This bound can be loose—ideally we have the uniform confidence $1/C^2$.

 ${}^{1}\sigma$ is the logistic-sigmoid function

²Where C is the number of classes.

Achieving the uniform confidence

Previous result uses¹

$$p(y = 1 \mid \alpha x, \mathcal{D}) \approx \sigma \left(\frac{\alpha \mathbb{E}_q(f_\theta(x))}{\sqrt{1 + \pi/8 \operatorname{Var}_q(f_\theta(\alpha x))}} \right)$$

¹Via linearization and the probit approximation

Achieving the uniform confidence

Previous result uses¹

$$\rho(y = 1 \mid \alpha x, \mathcal{D}) \approx \sigma\left(\frac{\alpha \mathbb{E}_q(f_\theta(x))}{\sqrt{1 + \pi/8 \operatorname{Var}_q(f_\theta(\alpha x))}}\right)$$

- No uniform confidence because:
 - The numerator is linear in α
 - The denominator is also linear in α

Achieving the uniform confidence

Previous result uses¹

$$\rho(y = 1 \mid \alpha x, \mathcal{D}) \approx \sigma\left(\frac{\alpha \mathbb{E}_q(f_\theta(x))}{\sqrt{1 + \pi/8 \operatorname{Var}_q(f_\theta(\alpha x))}}\right)$$

- No uniform confidence because:
 - The numerator is linear in α
 - The denominator is also linear in α
- ► So, to achieve the uniform confidence:
 - The numerator must stay the same
 - The variance must be in $\Theta(\alpha^d)$ for d > 2

Super-quadratic variance does exist

Just not for BNNs

- ▶ In GPs, the *cubic spline kernel*¹ has cubic variance
 - ▶ "Placing" K ReLU features on the input space and take $K \to \infty$
 - ▶ But it is defined *only* on ℝ_{>=0}

Super-quadratic variance does exist

Just not for BNNs

- ▶ In GPs, the *cubic spline kernel*¹ has cubic variance
 - ▶ "Placing" K ReLU features on the input space and take $K \to \infty$
 - ▶ But it is defined only on ℝ_{>=0}
- We extend this kernel (Double-Sided Cubic Spline (DSCS) kernel)²



¹Wahba, 1990

²For multi-dimensional inputs, average the kernel value of each component

Super-quadratic variance does exist

Just not for BNNs

- ▶ In GPs, the *cubic spline kernel*¹ has cubic variance
 - "Placing" K ReLU features on the input space and take $K \to \infty$
 - ▶ But it is defined only on ℝ_{>=0}
- We extend this kernel (Double-Sided Cubic Spline (DSCS) kernel)²



▶ Important properties: $k(x, x) \approx 0$ for $x \approx 0$ and $k(\alpha x, \alpha x) \in \Theta(\alpha^3)$

¹Wahba, 1990

²For multi-dimensional inputs, average the kernel value of each component

With the DSCS kernel

• The ReLU BNN $f_{\theta}(x)$ doesn't achieve the uniform confidence \implies there is a *residual* predictive uncertainty

With the DSCS kernel

- ► The ReLU BNN $f_{\theta}(x)$ doesn't achieve the uniform confidence ⇒ there is a *residual* predictive uncertainty
- ▶ Model this residual with the DSCS kernel *k*, call it *ReLU-GP Residual* (*RGPR*):

 $\widetilde{f}(x) := f_{\theta}(x) + \widehat{f}(x)$ where $\widehat{f} \sim \mathcal{GP}(0, k)$

With the DSCS kernel

- The ReLU BNN $f_{\theta}(x)$ doesn't achieve the uniform confidence \implies there is a *residual* predictive uncertainty
- ▶ Model this residual with the DSCS kernel *k*, call it *ReLU-GP Residual* (*RGPR*):

$$\widetilde{f}(x) := f_{\theta}(x) + \widehat{f}(x)$$
 where $\widehat{f} \sim \mathcal{GP}(0, k)$

• Under posterior $q(\theta) = \mathcal{N}(\mu, \Sigma)$, we show that the *GP* posterior of $\tilde{f}(x)$ is¹

 $p(\widetilde{f}(x) \mid \mathcal{D}) \approx \mathcal{N}\left(\mathbb{E}_q(f_{\theta}(x)), \operatorname{Var}_q(f_{\theta}(x)) + k(x, x)\right)$

¹Under linearization and $k(x, x) \approx 0$ for $x \approx 0$

With the DSCS kernel

- ► The ReLU BNN $f_{\theta}(x)$ doesn't achieve the uniform confidence ⇒ there is a *residual* predictive uncertainty
- ▶ Model this residual with the DSCS kernel *k*, call it *ReLU-GP Residual* (*RGPR*):

 $\widetilde{f}(x) := f_{\theta}(x) + \widehat{f}(x)$ where $\widehat{f} \sim \mathcal{GP}(0, k)$

• Under posterior $q(\theta) = \mathcal{N}(\mu, \Sigma)$, we show that the *GP posterior* of $\tilde{f}(x)$ is¹

 $p(\widetilde{f}(x) \mid \mathcal{D}) \approx \mathcal{N}\left(\mathbb{E}_q(f_{\theta}(x)), \operatorname{Var}_q(f_{\theta}(x)) + k(x, x)\right)$

Thus, RGPR can be applied post-hoc cheaply, given a pre-trained ReLU BNN

¹Under linearization and $k(x, x) \approx 0$ for $x \approx 0$

RGPR fixes asymptotic overconfidence

In multi-class classification

- ► Recall $p(\tilde{f}(x) | \mathcal{D}) \approx \mathcal{N}\left(\mathbb{E}_q(f_\theta(x)), \operatorname{Var}_q(f_\theta(x)) + k(x, x)\right)$
 - Since $\mathbb{E}(\tilde{f}(x)) = \mathbb{E}_q(f_\theta(x))$ we retain the BNN's prediction
 - But $Var(\tilde{f}(x)) = Var_q(f_\theta(x)) + k(x, x) \in \Theta(\alpha^3)!$

RGPR fixes asymptotic overconfidence

In multi-class classification

- ► Recall $p(\tilde{f}(x) | \mathcal{D}) \approx \mathcal{N}\left(\mathbb{E}_q(f_\theta(x)), \operatorname{Var}_q(f_\theta(x)) + k(x, x)\right)$
 - Since $\mathbb{E}(\tilde{f}(x)) = \mathbb{E}_q(f_\theta(x))$ we retain the BNN's prediction
 - But $Var(\tilde{f}(x)) = Var_q(f_\theta(x)) + k(x, x) \in \Theta(\alpha^3)!$
- It induces the predictive distribution:

$$p(y = c \mid x, \tilde{f}, \mathcal{D}) = \int \operatorname{softmax}(\tilde{f}(x))_c p(\tilde{f}(x) \mid \mathcal{D}) d\tilde{f}(x)$$

RGPR fixes asymptotic overconfidence

In multi-class classification

- ► Recall $p(\tilde{f}(x) | \mathcal{D}) \approx \mathcal{N} \left(\mathbb{E}_q(f_\theta(x)), \operatorname{Var}_q(f_\theta(x)) + k(x, x) \right)$
 - Since $\mathbb{E}(\tilde{f}(x)) = \mathbb{E}_q(f_\theta(x))$ we retain the BNN's prediction
 - But $Var(\tilde{f}(x)) = Var_q(f_\theta(x)) + k(x, x) \in \Theta(\alpha^3)!$
- It induces the predictive distribution:

$$p(y = c \mid x, \tilde{f}, \mathcal{D}) = \int \operatorname{softmax}(\tilde{f}(x))_c p(\tilde{f}(x) \mid \mathcal{D}) d\tilde{f}(x)$$

• Under some approximations,¹ we can thus show:

 $\lim_{\alpha \to \infty} p(y = c \mid \alpha x, \tilde{f}, \mathcal{D}) = \frac{1}{C} \quad \text{for each class } c = 1, \dots, C$

¹Linearization and the generalized probit approximation (Gibbs, 1997)

Extending RGPR to non-asymptotic regimes

Apply RGPR to not only the input, but also hidden layer {h_l(x)}^{L-1}_{l=1} of the (point-estimated) NN¹

$$p(\widehat{f}(x)) = \mathcal{N}\left(0, \sum_{l=0}^{L-1} \sigma_l^2 k(h_l(x), h_l(x))\right)$$



(a) Input only

(b) Input & hiddens

Extending RGPR to non-asymptotic regimes

Apply RGPR to not only the input, but also hidden layer {h_l(x)}^{L-1}_{l=1} of the (point-estimated) NN¹

$$p(\widehat{f}(x)) = \mathcal{N}\left(0, \sum_{l=0}^{L-1} \sigma_l^2 k(h_l(x), h_l(x))\right)$$



(a) Input only

(b) Input & hiddens

• One can also optimize the hyperparameters $\{\sigma_l^2\}_{l=0}^{L-1}$

 $^{^1\}mbox{We}$ assume that the GP for each hidden space is independent

OOD detection

Table: OOD data detection in terms of FPR@95–lower is better. All values are in percent and averages over five OOD test sets and over 5 prediction runs. Prediction is done via Monte Carlo integration.

Methods	MNIST	CIFAR10	SVHN	CIFAR100
MAP	28.2	38.9	17.8	72.2
Temp. Scaling	28.4	34.9	17.6	71.9
Deep Ens.	23.0	51.0	11.3	74.7
Vanilla GP + DSCS	27.8	46.7	19.1	69.1
Last-layer Laplace	24.8	29.8	15.7	69.5
Last-layer Laplace + RGPR	3.6	24.2	9.6	63.0



• We extend the "ReLU kernel" of Wahba (1990) to the whole \mathbb{R}

- We extend the "ReLU kernel" of Wahba (1990) to the whole \mathbb{R}
- Using this kernel, we model the "uncertainty residual" of ReLU BNNs

- We extend the "ReLU kernel" of Wahba (1990) to the whole \mathbb{R}
- Using this kernel, we model the "uncertainty residual" of ReLU BNNs
- ▶ The resulting method, RGPR, can be applied *post-hoc* to ReLU BNNs

- We extend the "ReLU kernel" of Wahba (1990) to the whole \mathbb{R}
- Using this kernel, we model the "uncertainty residual" of ReLU BNNs
- The resulting method, RGPR, can be applied post-hoc to ReLU BNNs
- ► Theoretically: RGPR fixes the asymptotic overconfidence problem

- ▶ We extend the "ReLU kernel" of Wahba (1990) to the whole ℝ
- Using this kernel, we model the "uncertainty residual" of ReLU BNNs
- ▶ The resulting method, RGPR, can be applied *post-hoc* to ReLU BNNs
- Theoretically: RGPR fixes the asymptotic overconfidence problem
- Practically: RGPR can be extended to non-asymptotic regimes and gives good uncertainty quantification performance